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1. STRUCTURE

This service manual has been prepared as an aid to improve the quality of repairs by giving the serviceman an accurate understanding of the product and by showing him the correct way to perform repairs and make judgements. Make sure you understand the contents of this manual and use it to full effect at every opportunity.

This service manual mainly contains the necessary technical information for operations performed in a service workshop.

For ease of understanding, the manual is divided into the following sections.

SECTION 1 GENERAL

This section explains the safety hints and gives the specification of the machine and major components.

SECTION 2 STRUCTURE AND FUNCTION

This section explains the structure and function of each component. It serves not only to give an understanding of the structure, but also serves as reference material for troubleshooting.

SECTION 3 HYDRAULIC SYSTEM

This section explains the hydraulic circuit, single and combined operation.

SECTION 4 ELECTRICAL SYSTEM

This section explains the electrical circuit, monitoring system and each component. It serves not only to give an understanding electrical system, but also serves as reference material for trouble shooting.

SECTION 5 MECHATRONICS SYSTEM

This section explains the computer aided power optimization system and each component.

SECTION 6 TROUBLESHOOTING

This section explains the troubleshooting charts correlating problems to causes.

SECTION 7 MAINTENANCE STANDARD

This section gives the judgement standards when inspecting disassembled parts.

SECTION 8 DISASSEMBLY AND ASSEMBLY

This section explains the order to be followed when removing, installing, disassembling or assembling each component, as well as precautions to be taken for these operations.

SECTION 9 COMPONENT MOUNTING TORQUE

This section shows bolt specifications and standard torque values needed when mounting components to the machine.

The specifications contained in this shop manual are subject to change at any time and without any advance notice. Contact your HYUNDAI distributor for the latest information.

2. HOW TO READ THE SERVICE MANUAL

Distribution and updating

Any additions, amendments or other changes will be sent to HYUNDAI distributors.

Get the most up-to-date information before you start any work.

Filing method

1. See the page number on the bottom of the page.

File the pages in correct order.

2. Following examples shows how to read the page number.

Example 1

2-3



 Item number(2. Structure and Function)

Consecutive page number for each item.

- 3. Additional pages : Additional pages are indicated by a hyphen(-) and number after the page number. File as in the example.
 - 10 4

10 - 5

Revised edition mark(123...)

When a manual is revised, an edition mark is recorded on the bottom outside corner of the pages.

Revisions

Revised pages are shown at the list of revised pages on the between the contents page and section 1 page.

Symbols

So that the shop manual can be of ample practical use, important places for safety and quality are marked with the following symbols.

Symbol	Item	Remarks				
	Cofoty	Special safety precautions are necessary when performing the work.				
	Safety	Extra special safety precautions are necessary when performing the work because it is under internal pressure.				
*	Caution	Special technical precautions or other precautions for preserving standards are necessary when performing the work.				

3. CONVERSION TABLE

Method of using the Conversion Table

The Conversion Table in this section is provided to enable simple conversion of figures. For details of the method of using the Conversion Table, see the example given below.

Example

1. Method of using the Conversion Table to convert from millimeters to inches

Convert 55mm into inches.

- (1) Locate the number 50in the vertical column at the left side, take this as (a), then draw a horizontal line from (a).
- (2) Locate the number 5in the row across the top, take this as , then draw a perpendicular line down from .
- (3) Take the point where the two lines cross as \bigcirc . This point \bigcirc gives the value when converting from millimeters to inches. Therefore, 55mm = 2.165 inches.
- 2. Convert 550mm into inches.
 - (1) The number 550 does not appear in the table, so divide by 10(Move the decimal point one place to the left) to convert it to 55mm.
 - (2) Carry out the same procedure as above to convert 55mm to 2.165 inches.
 - (3) The original value(550mm) was divided by 10, so multiply 2.165 inches by 10(Move the decimal point one place to the right) to return to the original value. This gives 550mm = 21.65 inches.

h

							1mm = 0.				0.03937 in
		0	1	2	3	4	5	6	7	8	9
	0		0.039	0.079	0.118	0.157	0.197	0.236	0.276	0.315	0.354
	10	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.669	0.709	0.748
	20	0.787	0.827	0.866	0.906	0.945	0.984	1.024	1.063	1.102	1.142
	30	1.181	1.220	1.260	1.299	1.339	1.378	1.417	1.457	1.496	1.536
	40	1.575	1.614	1.654	1.693	1.732	1.772	1.811	1.850	1.890	1.929
							©				
a	50	1.969	2.008	2.047	2.087	2.126	2.165	2.205	2.244	2.283	2.323
	60	2.362	2.402	2.441	2.480	2.520	2.559	2.598	2.638	2.677	2.717
	70	2.756	2.795	2.835	2.874	2.913	2.953	2.992	3.032	3.071	3.110
	80	3.150	3.189	3.228	3.268	3.307	3.346	3.386	3.425	3.465	3.504
	90	3.543	3.583	3.622	3.661	3.701	3.740	3.780	3.819	3.858	3.898

Millimeters to inches

Millimeters to inches

1 mm = 0.03937 in

	0	1	2	3	4	5	6	7	8	9
0		0.039	0.079	0.118	0.157	0.197	0.236	0.276	0.315	0.354
10	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.669	0.709	0.748
20	0.787	0.827	0.866	0.906	0.945	0.984	1.024	1.063	1.102	1.142
30	1.181	1.220	1.260	1.299	1.339	1.378	1.417	1.457	1.496	1.536
40	1.575	1.614	1.654	1.693	1.732	1.772	1.811	1.850	1.890	1.929
50	1.969	2.008	2.047	2.087	2.126	2.165	2.205	2.244	2.283	2.323
60	2.362	2.402	2.441	2.480	2.520	2.559	2.598	2.638	2.677	2.717
70	2.756	2.795	2.835	2.874	2.913	2.953	2.992	3.032	3.071	3.110
80	3.150	3.189	3.228	3.268	3.307	3.346	3.386	3.425	3.465	3.504
90	3.543	3.583	3.622	3.661	3.701	3.740	3.780	3.819	3.858	3.898

Kilogram to Pound

1kg = 2.2046lb

									5	
	0	1	2	3	4	5	6	7	8	9
0		2.20	4.41	6.61	8.82	11.02	13.23	15.43	17.64	19.84
10	22.05	24.25	26.46	28.66	30.86	33.07	35.27	37.48	39.68	41.89
20	44.09	46.30	48.50	50.71	51.91	55.12	57.32	59.5.	61.73	63.93
30	66.14	68.34	70.55	72.75	74.96	77.16	79.37	81.57	83.78	85.98
40	88.18	90.39	92.59	94.80	97.00	99.21	101.41	103.62	105.82	108.03
50	110.23	112.44	114.64	116.85	119.05	121.25	123.46	125.66	127.87	130.07
60	132.28	134.48	136.69	138.89	141.10	143.30	145.51	147.71	149.91	152.12
70	154.32	156.53	158.73	160.94	163.14	165.35	167.55	169.76	171.96	174.17
80	176.37	178.57	180.78	182.98	185.19	187.39	189.60	191.80	194.01	196.21
90	198.42	200.62	202.83	205.03	207.24	209.44	211.64	213.85	216.05	218.26

Liter to U.S. Gallon

1 *l* = 0.2642 U.S.Gal

	0	1	2	3	4	5	6	7	8	9
0		0.264	0.528	0.793	1.057	1.321	1.585	1.849	2.113	2.378
10	2.642	2.906	3.170	3.434	3.698	3.963	4.227	4.491	4.755	5.019
20	5.283	5.548	5.812	6.6076	6.340	6.604	6.869	7.133	7.397	7.661
30	7.925	8.189	8.454	8.718	8.982	9.246	9.510	9.774	10.039	10.303
40	10.567	10.831	11.095	11.359	11.624	11.888	12.152	12.416	12.680	12.944
50	13.209	13.473	13.737	14.001	14.265	14.529	14.795	15.058	15.322	15.586
60	15.850	16.115	16.379	16.643	16.907	17.171	17.435	17.700	17.964	18.228
70	18.492	18.756	19.020	19.285	19.549	19.813	20.077	20.341	20.605	20.870
80	21.134	21.398	21.662	21.926	22.190	22.455	22.719	22.983	23.247	23.511
90	23.775	24.040	24.304	24.568	24.832	25.096	25.631	25.625	25.889	26.153

Liter to U.K. Gallon

1 *l* = 0.21997 U.K.Gal

	0	1	2	3	4	5	6	7	8	9
0		0.220	0.440	0.660	0.880	1.100	1.320	1.540	1.760	1.980
10	2.200	2.420	2.640	2.860	3.080	3.300	3.520	3.740	3.950	4.179
20	4.399	4.619	4.839	5.059	5.279	5.499	5.719	5.939	6.159	6.379
30	6.599	6.819	7.039	7.259	7.479	7.969	7.919	8.139	8.359	8.579
40	8.799	9.019	9.239	9.459	9.679	9.899	10.119	10.339	10.559	10.778
50	10.998	11.281	11.438	11.658	11.878	12.098	12.318	12.528	12.758	12.978
60	13.198	13.418	13.638	13.858	14.078	14.298	14.518	14.738	14.958	15.178
70	15.398	15.618	15.838	16.058	16.278	16.498	16.718	16.938	17.158	17.378
80	17.598	17.818	18.037	18.257	18.477	18.697	18.917	19.137	19.357	19.577
90	19.797	20.017	20.237	20.457	20.677	20.897	21.117	21.337	21.557	21.777

kgf \cdot m to lbf \cdot ft

 $1 \text{kgf} \cdot \text{m} = 7.233 \text{lbf} \cdot \text{ft}$

	0	1	2	3	4	5	6	7	8	9
		7.2	14.5	21.7	28.9	36.2	43.4	50.6	57.9	65.1
10	72.3	79.6	86.8	94.0	101.3	108.5	115.7	123.0	130.2	137.4
20	144.7	151.9	159.1	166.4	173.6	180.8	188.1	195.3	202.5	209.8
30	217.0	224.2	231.5	238.7	245.9	253.2	260.4	267.6	274.9	282.1
40	289.3	396.6	303.8	311.0	318.3	325.5	332.7	340.0	347.2	354.4
50	361.7	368.9	376.1	383.4	390.6	397.8	405.1	412.3	419.5	426.8
60	434.0	441.2	448.5	455.7	462.9	470.2	477.4	484.6	491.8	499.1
70	506.3	513.5	520.8	528.0	535.2	542.5	549.7	556.9	564.2	571.4
80	578.6	585.9	593.1	600.3	607.6	614.8	622.0	629.3	636.5	643.7
90	651.0	658.2	665.4	672.7	679.9	687.1	694.4	701.6	708.8	716.1
100	723.3	730.5	737.8	745.0	752.2	759.5	766.7	773.9	781.2	788.4
110	795.6	802.9	810.1	817.3	824.6	831.8	839.0	846.3	853.5	860.7
120	868.0	875.2	882.4	889.7	896.9	904.1	911.4	918.6	925.8	933.1
130	940.3	947.5	954.8	962.0	969.2	976.5	983.7	990.9	998.2	10005.4
140	1012.6	1019.9	1027.1	1034.3	1041.5	1048.8	1056.0	1063.2	1070.5	1077.7
150	1084.9	1092.2	1099.4	1106.6	1113.9	1121.1	1128.3	1135.6	1142.8	1150.0
160	1157.3	1164.5	1171.7	1179.0	1186.2	1193.4	1200.7	1207.9	1215.1	1222.4
170	1129.6	1236.8	1244.1	1251.3	1258.5	1265.8	1273.0	1280.1	1287.5	1294.7
180	1301.9	1309.2	1316.4	1323.6	1330.9	1338.1	1345.3	1352.6	1359.8	1367.0
190	1374.3	1381.5	1388.7	1396.0	1403.2	1410.4	1417.7	1424.9	1432.1	1439.4

kgf/cm2 to lbf/in2

 $1 \text{kgf} / \text{cm}^2 = 14.2233 \text{lbf} / \text{in}^2$

<u> </u>							s			
	0	1	2	3	4	5	6	7	8	9
		14.2	28.4	42.7	56.9	71.1	85.3	99.6	113.8	128.0
10	142.2	156.5	170.7	184.9	199.1	213.4	227.6	241.8	256.0	270.2
20	284.5	298.7	312.9	327.1	341.4	355.6	369.8	384.0	398.3	412.5
30	426.7	440.9	455.1	469.4	483.6	497.8	512.0	526.3	540.5	554.7
40	568.9	583.2	597.4	611.6	625.8	640.1	654.3	668.5	682.7	696.9
50	711.2	725.4	739.6	753.8	768.1	782.3	796.5	810.7	825.0	839.2
60	853.4	867.6	881.8	896.1	910.3	924.5	938.7	953.0	967.2	981.4
70	995.6	1010	1024	1038	1053	1067	1081	1095	1109	1124
80	1138	1152	1166	1181	1195	1209	1223	1237	1252	1266
90	1280	1294	1309	1323	1337	1351	1365	1380	1394	1408
100	1422	1437	1451	1465	1479	1493	1508	1522	1536	1550
110	1565	1579	1593	1607	1621	1636	1650	1664	1678	1693
120	1707	1721	1735	1749	1764	1778	1792	1806	1821	1835
130	1849	2863	1877	1892	1906	1920	1934	1949	1963	1977
140	1991	2005	2020	2034	2048	2062	2077	2091	2105	2119
150	2134	2148	2162	2176	2190	2205	2219	2233	2247	2262
160	2276	2290	2304	2318	2333	2347	2361	2375	2389	2404
170	2418	2432	2446	2460	2475	2489	2503	2518	2532	2546
180	2560	2574	2589	5603	2617	2631	2646	2660	2674	2688
200	2845	2859	2873	2887	2901	2916	2930	2944	2958	2973
210	2987	3001	3015	3030	3044	3058	3072	3086	3101	3115
220	3129	3143	3158	3172	3186	3200	3214	3229	3243	3257
230	3271	3286	3300	3314	3328	3343	3357	3371	3385	3399
240	3414	3428	3442	3456	3470	3485	3499	3513	3527	3542

TEMPERATURE

Fahrenheit-Centigrade Conversion.

A simple way to convert a fahrenheit temperature reading into a centigrade temperature reading or vice verse is to enter the accompanying table in the center or boldface column of figures.

These figures refer to the temperature in either Fahrenheit or Centigrade degrees.

If it is desired to convert from Fahrenheit to Centigrade degrees, consider the center column as a table of Fahrenheit temperatures and read the corresponding Centigrade temperature in the column at the left.

If it is desired to convert from Centigrade to Fahrenheit degrees, consider the center column as a table of Centigrade values, and read the corresponding Fahrenheit temperature on the right.

°C		۴F	°C		°F	°C		°F	°C		°F
-40.4	-40	-40.0	-11.7	11	51.8	7.8	46	114.8	27.2	81	117.8
-37.2	-35	-31.0	-11.1	12	53.6	8.3	47	116.6	27.8	82	179.6
-34.4	-30	-22.0	-10.6	13	55.4	8.9	48	118.4	28.3	83	181.4
-31.7	-25	-13.0	-10.0	14	57.2	9.4	49	120.2	28.9	84	183.2
-28.9	-20	-4.0	-9.4	15	59.0	10.0	50	122.0	29.4	85	185.0
-28.3	-19	-2.2	-8.9	16	60.8	10.6	51	123.8	30.0	86	186.8
-27.8	-18	-0.4	-8.3	17	62.6	11.1	52	125.6	30.6	87	188.6
-27.2	-17	1.4	-7.8	18	64.4	11.7	53	127.4	31.1	88	190.4
-26.7	-16	3.2	-6.7	20	68.0	12.8	55	131.0	32.2	90	194.0
-26.1	-15	5.0	-6.7	20	68.0	12.8	55	131.0	32.2	90	194.0
-25.6	-14	6.8	-6.1	21	69.8	13.3	56	132.8	32.8	91	195.8
-25.0	-13	8.6	-5.6	22	71.6	13.9	57	134.6	33.3	92	197.6
-24.4	-12	10.4	-5.0	23	73.4	14.4	58	136.4	33.9	93	199.4
-23.9	-11	12.2	-4.4	24	75.2	15.0	59	138.2	34.4	94	201.2
-23.3	-10	14.0	-3.9	25	77.0	15.6	60	140.0	35.0	95	203.0
-22.8	-9	15.8	-3.3	26	78.8	16.1	61	141.8	35.6	96	204.8
-22.2	-8	17.6	-2.8	27	80.6	16.7	62	143.6	36.1	97	206.6
-21.7	-7	19.4	-2.2	28	82.4	17.2	63	145.4	36.7	98	208.4
-21.1	-6	21.2	-1.7	29	84.2	17.8	64	147.2	37.2	99	210.2
-20.6	-5	23.0	-1.1	35	95.0	21.1	70	158.0	51.7	125	257.0
-20.0	-4	24.8	-0.6	31	87.8	18.9	66	150.8	40.6	105	221.0
-19.4	-3	26.6	0	32	89.6	19.4	67	152.6	43.3	110	230.0
-18.9	-2	28.4	0.6	33	91.4	20.0	68	154.4	46.1	115	239.0
-18.3	-1	30.2	1.1	34	93.2	20.6	69	156.2	48.9	120	248.0
-17.8	0	32.0	1.7	35	95.0	21.1	70	158.0	51.7	125	257.0
-17.2	1	33.8	2.2	36	96.8	21.7	71	159.8	54.4	130	266.0
-16.7	2	35.6	2.8	37	98.6	22.2	72	161.6	57.2	135	275.0
-16.1	3	37.4	3.3	38	100.4	22.8	73	163.4	60.0	140	284.0
-15.6	4	39.2	3.9	39	102.2	23.3	74	165.2	62.7	145	293.0
-15.0	5	41.0	4.4	40	104.0	23.9	75	167.0	65.6	150	302.0
-14.4	6	42.8	5.0	41	105.8	24.4	76	168.8	68.3	155	311.0
-13.9	7	44.6	5.6	42	107.6	25.0	77	170.6	71.1	160	320.0
-13.3	8	46.4	6.1	43	109.4	25.6	78	172.4	73.9	165	329.0
-12.8	9	48.2	6.7	44	111.2	26.1	79	174.2	76.7	170	338.0
-12.2	10	50.0	7.2	45	113.0	26.7	80	176.0	79.4	172	347.0

Group	1 Safety Hints	1-1
Group	2 Specifications	1-9

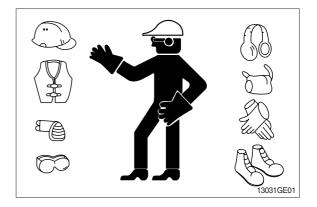
GROUP 1 SAFETY

FOLLOW SAFE PROCEDURE

Unsafe work practices are dangerous. Understand service procedure before doing work; Do not attempt shortcuts.

WEAR PROTECTIVE CLOTHING

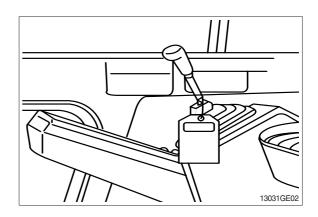
Wear close fitting clothing and safety equipment appropriate to the job.



WARN OTHERS OF SERVICE WORK

Unexpected machine movement can cause serious injury.

Before performing any work on the excavator, attach a **Do Not Operate** tag on the right side control lever.



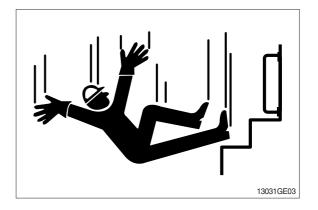
USE HANDHOLDS AND STEPS

Falling is one of the major causes of personal injury.

When you get on and off the machine, always maintain a three point contact with the steps and handrails and face the machine. Do not use any controls as handholds.

Never jump on or off the machine. Never mount or dismount a moving machine.

Be careful of slippery conditions on platforms, steps, and handrails when leaving the machine.

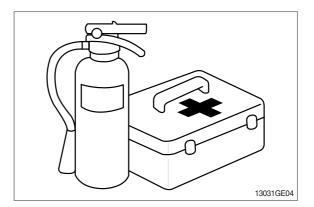


PREPARE FOR EMERGENCIES

Be prepared if a fire starts.

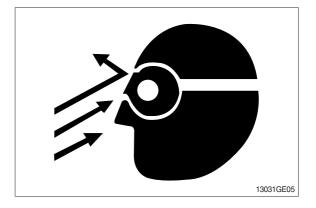
Keep a first aid kit and fire extinguisher handy.

Keep emergency numbers for doctors, ambulance service, hospital, and fire department near your telephone.



PROTECT AGAINST FLYING DEBRIS

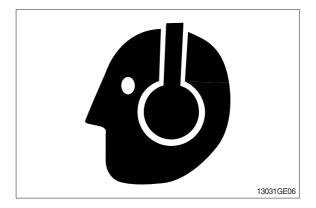
Guard against injury from flying pieces of metal or debris; Wear goggles or safety glasses.



PROTECT AGAINST NOISE

Prolonged exposure to loud noise can cause impairment or loss of hearing.

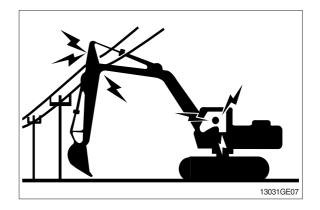
Wear a suitable hearing protective device such as earmuffs or earplugs to protect against objectionable or uncomfortable loud noises.



AVOID POWER LINES

Serious injury or death can result from contact with electric lines.

Never move any part of the machine or load closer to electric line than 3m(10ft) plus twice the line insulator length.



KEEP RIDERS OFF EXCAVATOR

Only allow the operator on the excavator. Keep riders off.

Riders on excavator are subject to injury such as being struck by foreign objects and being thrown off the excavator. Riders also obstruct the operator's view resulting in the excavator being operated in an unsafe manner.

MOVE AND OPERATE MACHINE SAFELY

Bystanders can be run over. Know the location of bystanders before moving, swinging, or operating the machine.

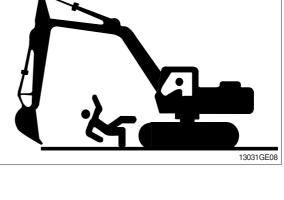
Always keep the travel alarm in working condition. It warns people when the excavator starts to move.

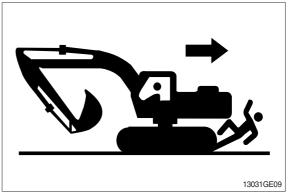
Use a signal person when moving, swinging, or operating the machine in congested areas. Coordinate hand signals before starting the excavator.

OPERATE ONLY FORM OPERATOR'S SEAT

Avoid possible injury machine damage. Do not start engine by shorting across starter terminals.

NEVER start engine while standing on ground. Start engine only from operator's seat.







PARK MACHINE SAFELY

Before working on the machine:

- \cdot Park machine on a level surface.
- · Lower bucket to the ground.
- \cdot Turn auto idle switch off.
- Run engine at 1/2 speed without load for 2 minutes.
- Turn key switch to OFF to stop engine. Remove key from switch.
- · Move pilot control shutoff lever to locked position.
- · Allow engine to cool.

SUPPORT MACHINE PROPERLY

Always lower the attachment or implement to the ground before you work on the machine. If you must work on a lifted machine or attachment, securely support the machine or attachment.

Do not support the machine on cinder blocks, hollow tiles, or props that may crumble under continuous load.

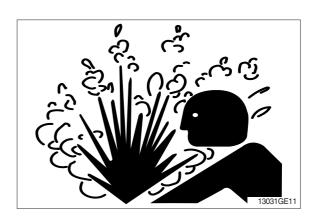
Do not work under a machine that is supported solely by a jack. Follow recommended procedures in this manual.

SERVICE COOLING SYSTEM SAFELY

Explosive release of fluids from pressurized cooling system can cause serious burns.

Shut off engine. Only remove filler cap when cool enough to touch with bare hands.





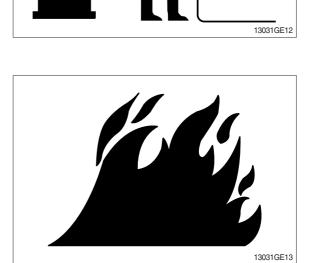
HANDLE FLUIDS SAFELY-AVOID FIRES

Handle fuel with care; It is highly flammable. Do not refuel the machine while smoking or when near open flame or sparks. Always stop engine before refueling machine. Fill fuel tank outdoors.

Store flammable fluids away from fire hazards. Do not incinerate or puncture pressurized containers.

Make sure machine is clean of trash, grease, and debris.

Do not store oily rags; They can ignite and burn spontaneously.



BEWARE OF EXHAUST FUMES

Prevent asphyxiation. Engine exhaust fumes can cause sickness or death.

If you must operate in a building, be positive there is adequate ventilation. Either use an exhaust pipe extension to remove the exhaust fumes or open doors and windows to bring enough outside air into the area.

REMOVE PAINT BEFORE WELDING OR HEATING

Avoid potentially toxic fumes and dust.

Hazardous fumes can be generated when paint is heated by welding, soldering, or using a torch.

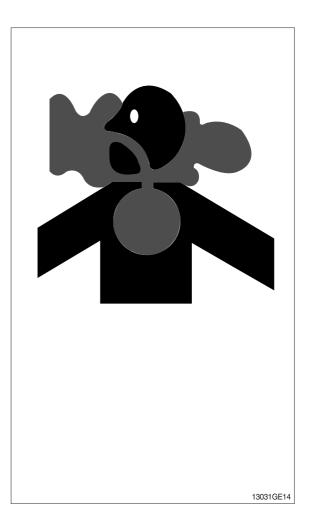
Do all work outside or in a well ventilated area. Dispose of paint and solvent properly.

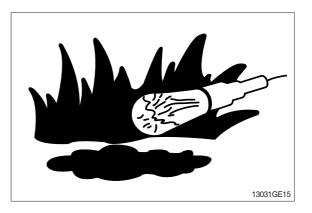
Remove paint before welding or heating:

- If you sand or grind paint, avoid breathing the dust. Wear an approved respirator.
- If you use solvent or paint stripper, remove stripper with soap and water before welding. Remove solvent or paint stripper containers and other flammable material from area. Allow fumes to disperse at least 15 minutes before welding or heating.

ILLUMINATE WORK AREA SAFELY

Illuminate your work area adequately but safely. Use a portable safety light for working inside or under the machine. Make sure the bulb is enclosed by a wire cage. The hot filament of an accidentally broken bulb can ignite spilled fuel or oil.





SERVICE MACHINE SAFELY

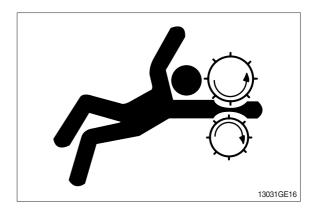
Tie long hair behind your head. Do not wear a necktie, scarf, loose clothing or necklace when you work near machine tools or moving parts. If these items were to get caught, severe injury could result.

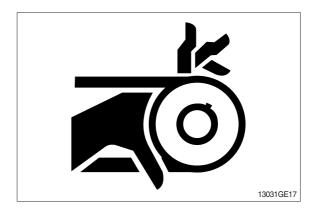
Remove rings and other jewelry to prevent electrical shorts and entanglement in moving parts.

STAY CLEAR OF MOVING PARTS

Entanglements in moving parts can cause serious injury.

To prevent accidents, use care when working around rotating parts.





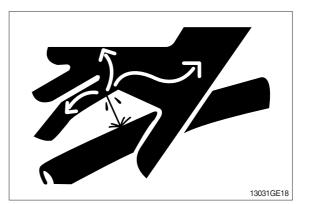
AVOID HIGH PRESSURE FLUIDS

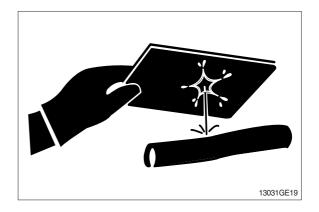
Escaping fluid under pressure can penetrate the skin causing serious injury.

Avoid the hazard by relieving pressure before disconnecting hydraulic or other lines. Tighten all connections before applying pressure.

Search for leaks with a piece of cardboard. Protect hands and body from high pressure fluids.

If an accident occurs, see a doctor immediately. Any fluid injected into the skin must be surgically removed within a few hours or gangrene may result.





AVOID HEATING NEAR PRESSURIZED FLUID LINES

Flammable spray can be generated by heating near pressurized fluid lines, resulting in severe burns to yourself and bystanders. Do not heat by welding, soldering, or using a torch near pressurized fluid lines or other flammable materials.

Pressurized lines can be accidentally cut when heat goes beyond the immediate flame area. Install fire resisting guards to protect hoses or other materials.



PREVENT BATTERY EXPLOSIONS

Keep sparks, lighted matches, and flame away from the top of battery. Battery gas can explode.

Never check battery charge by placing a metal object across the posts. Use a volt-meter or hydrometer.

Do not charge a frozen battery; It may explode. Warm battery to $16^{\circ}C$ ($60^{\circ}F$).



PREVENT ACID BURNS

Sulfuric acid in battery electrolyte is poisonous. It is strong enough to burn skin, eat holes in clothing, and cause blindness if splashed into eyes.

Avoid the hazard by:

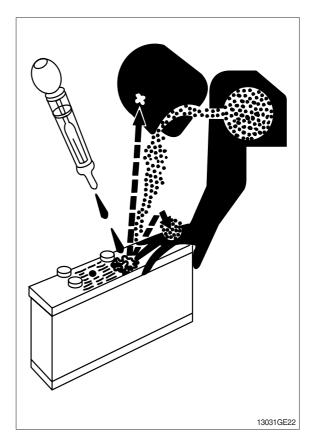
- 1. Filling batteries in a well-ventilated area.
- 2. Wearing eye protection and rubber gloves.
- 3. Avoiding breathing fumes when electrolyte is added.
- 4. Avoiding spilling of dripping electrolyte.
- 5. Use proper jump start procedure.

If you spill acid on yourself:

- 1. Flush your skin with water.
- 2. Apply baking soda or lime to help neutralize the acid.
- 3. Flush your eyes with water for 10-15 minutes. Get medical attention immediately.

If acid is swallowed:

- 1. Drink large amounts of water or milk.
- 2. Then drink milk of magnesia, beaten eggs, or vegetable oil.
- 3. Get medical attention immediately.



USE TOOLS PROPERLY

Use tools appropriate to the work. Makeshift tools, parts, and procedures can create safety hazards.

Use power tools only to loosen threaded tools and fasteners.

For loosening and tightening hardware, use the correct size tools. DO NOT use U.S. measurement tools on metric fasteners. Avoid bodily injury caused by slipping wrenches.

Use only recommended replacement parts.(aee Parts catalogue.)

DISPOSE OF FLUIDS PROPERLY

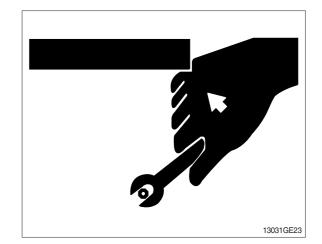
Improperly disposing of fluids can harm the environment and ecology. Before draining any fluids, find out the proper way to dispose of waste from your local environmental agency.

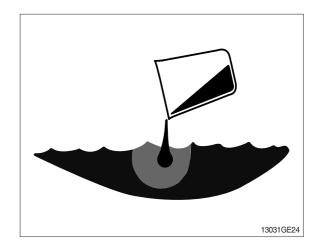
Use proper containers when draining fluids. Do not use food or beverage containers that may mislead someone into drinking from them.

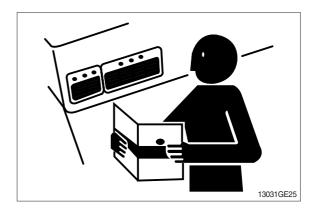
DO NOT pour oil into the ground, down a drain, or into a stream, pond, or lake. Observe relevant environmental protection regulations when disposing of oil, fuel, coolant, brake fluid, filters, batteries, and other harmful waste.

REPLACE SAFETY SIGNS

Replace missing or damaged safety signs. See the machine operator's manual for correct safety sign placement.





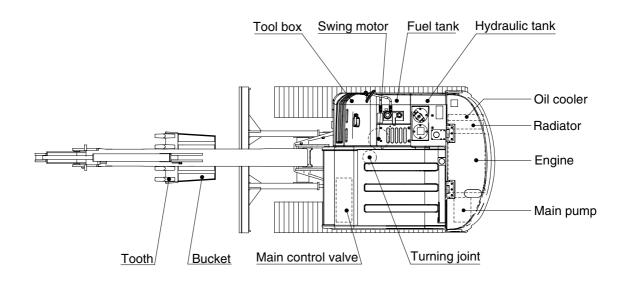


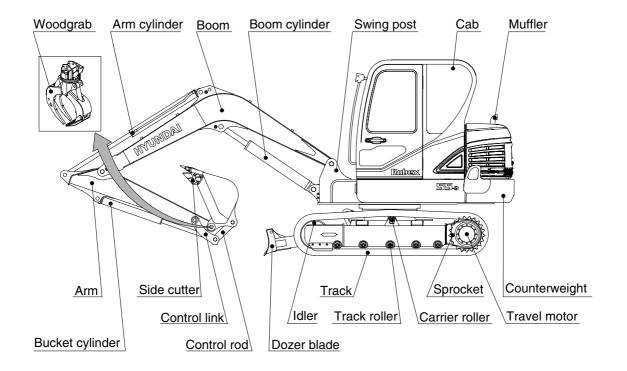
LIVE WITH SAFETY

Before returning machine to customer, make sure machine is functioning properly, especially the safety systems. Install all guards and shields.

GROUP 2 SPECIFICATIONS

1. MAJOR COMPONENT

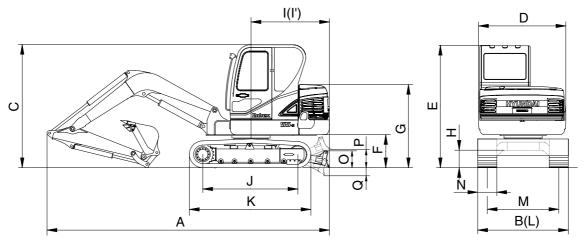




5592SP01A

2. SPECIFICATIONS

1) 3.0 m (9'10") MONO BOOM, 1.6 m (5' 3") ARM, WITH BOOM SWING SYSTEM

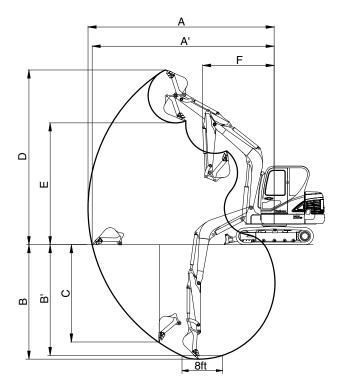


5592SP02

Description		Unit	Specification
Operating weight		kg (lb)	5650 (12460)
Bucket capacity (SAE heaped), standard		m³ (yd³)	0.18 (0.24)
Overall length	A		5900 (19' 4")
Overall width, with 380 mm shoe	В		1920 (6' 4")
Overall height	С		2550 (8' 4")
Superstructure width	D		1850 (6' 1")
Overall height of cab	E		2550 (8' 4")
Ground clearance of counterweight	F		690 (2' 3")
Engine cover height	G		1690 (5' 7")
Minimum ground clearance	Н		380 (1' 3")
Rear-end distance	I	thin)	1650 (5' 5")
Rear-end swing radius	ľ	mm (ft-in)	1650 (5' 5")
Distance between tumblers	J		1990 (6' 6")
Undercarriage length	К		2530 (8' 4")
Undercarriage width	L		1880 (6' 2")
Track gauge	М		1500 (4' 11")
Track shoe width, standard	N		380 (15")
Height of blade	0		350 (1' 2")
Ground clearance of blade up	Р		390 (1' 3")
Depth of blade down	Q		590 (1' 11")
Travel speed (low/high)		km/hr (mph)	2.2/4.0 (1.4/2.5)
Swing speed		rpm	9.3
Gradeability		Degree (%)	35 (70)
Ground pressure (380 mm shoe)		kgf/cm²(psi)	0.34 (4.83)
Max traction force		kg (lb)	5300 (11680)

3. WORKING RANGE

1) 3.0 m (9' 10") MONO BOOM WITH BOOM SWING SYSTEM



5592SP03

Decoription		1.6 m (5' 3") Arm					
Description		1.011 (5-5) Alti					
Max digging reach	Α	6150 mm (20' 2")					
Max digging reach on ground	A'	6010 mm (19' 9")					
Max digging depth	В	3820 mm (12' 6")					
Max digging depth (8ft level)	B'	3420 mm (11' 3")					
Max vertical wall digging depth	С	3200 mm (10' 6")					
Max digging height	D	5780 mm (19' 0")					
Max dumping height	Е	4050 mm (13' 3")					
Min swing radius	F	2350 mm (7' 9")					
Boom swing radius (left/right)		80°/50°					
		37.7 kN					
	SAE	3850 kgf					
Pueket diaging force		8490 lbf					
Bucket digging force		42.4 kN					
	ISO	4330 kgf					
		9550 lbf					
		28.4 kN					
	SAE	2900 kgf					
Arm crowd force		6390 lbf					
		31.9 kN					
	ISO	3260 kgf					
		7190 lbf					

4. WEIGHT

Item	kg	lb
Upperstructure assembly	2710	5970
Main frame weld assembly	600	1320
Engine assembly	280	620
Main pump assembly	30	70
Main control valve assembly	40	90
Swing motor assembly	80	180
Hydraulic oil tank assembly	90	200
Fuel tank assembly	60	130
Boom swing post	110	240
Counterweight	235	520
Cab assembly	350	770
Lower chassis assembly	2150	4740
Track frame weld assembly	700	1540
Swing bearing	90	200
Travel motor assembly	80	180
Turning joint	30	70
Track recoil spring	20	45
Idler & tension body	60	130
Carrier roller	10	20
Track roller	10	20
Sprocket	20	40
Track-chain assembly (380 mm standard triple grouser shoe)	320	710
Dozer blade assembly	210	460
Front attachment assembly (3.0 m boom, 1.6 m arm, 0.18 m ³ SAE heaped bucket)	790	1740
3.0 m boom assembly	240	530
1.6 m arm assembly	130	290
0.18 m ³ SAE heaped bucket	170	370
Boom cylinder assembly	70	155
Arm cylinder assembly	60	130
Bucket cylinder assembly	35	80
Bucket control link assembly	40	90
Dozer cylinder assembly	40	90
Boom swing cylinder assembly	40	90

5. LIFTING CAPACITIES

1) 3.0 m (9' 10") boom, 1.6 m (5' 3") arm equipped with 0.18 m³ (SAE heaped) bucket and 380 mm (15") triple grouser shoe.

				At	max. rea	ch						
Load point		2.0 m (7 ft)		3.0 m	(10 ft)	4.0 m	(13 ft)	5.0 m (16 ft)		Capacity		Reach
heigh	it	ľ		ľ	⋐	ľ	╔╋╍	ľ	⋐⋣⋑	ľ		m (ft)
5.0 m (16 ft)	kg Ib									*950 *2090	*950 *2090	4.12 (13.5)
4.0 m (13 ft)	kg Ib					*1020 *2250	*1020 *2250			*980 *2160	780 1720	5.08 (16.7)
3.0 m (10 ft)	kg Ib					*1090 *2400	*1090 *2400			*1010 *2230	650 1430	5.60 (18.4)
2.0 m (7 ft)	kg Ib	*3050 *6720	*3050 *6720	*1690 *3730	*1690 *3730	*1320 *2910	1100 2430	*1170 *2580	760 1680	*1050 *2310	590 1300	5.84 (19.2)
1.0 m (3 ft)	kg Ib			*2360 *5200	1610 3550	*1600 *3530	1040 2290	*1280 *2820	740 1630	*1100 *2430	580 1280	5.85 (19.2)
Ground Line	kg Ib	*2350 *5180	*2350 *5180	*2700 *5950	1540 3400	*1790 *3950	1000 2200	*1350 *2980	720 1590	*1140 *2510	610 1340	5.63 (18.5)
-1.0 m (-3 ft)	kg Ib	*3600 *7940	3020 6660	*2670 *5890	1530 3370	*1800 *3970	990 2180			*1180 *2600	700 1540	5.13 (16.8)
-2.0 m (-7 ft)	kg Ib	*3770 *8310	3060 6750	*2300 *5070	1540 3400					*1140 *2510	960 2120	4.23 (13.9)
-3.0 m (-10 ft)	kg Ib	*2040 *4500	*2040 *4500									

• 🖣 : Rating over-front

Note 1. Lifting capacity are based on SAE J1097 and ISO 10567.

2. Lifting capacity of the ROBEX series does not exceed 75% of tipping load with the machine on firm, level ground or 87% of full hydraulic capacity.

3. The load point is a hook located on the back of the bucket.

4. *indicates load limited by hydraulic capacity.

^{• 🖃 :} Rating over-side or 360 degree

2) 3.0 m (9'10") boom, 1.6 m (5' 3") arm equipped with 0.18 m³ (SAE heaped) bucket and 380 mm (15") triple grouser shoe.

				At	max. rea	ch						
Load point		2.0 m (7 ft)		3.0 m (10 ft)		4.0 m (13 ft)		5.0 m (16 ft)		Capacity		Reach
heigh	nt	ľ	⋐	ľ	⋐	ŀ	₢╋╸	ľ	╔╋╍	ľ		m (ft)
5.0 m (16 ft)	kg Ib									*950 *2090	*950 *2090	4.12 (13.5)
4.0 m (13 ft)	kg Ib					*1020 *2250	*1020 *2250			*980 *2160	740 1630	5.08 (16.7)
3.0 m (10 ft)	kg Ib					*1090 *2400	1080 2380			890 1960	610 1340	5.60 (18.4)
2.0 m (7 ft)	kg Ib	*3050 *6720	*3050 *6720	*1690 *3730	1630 3590	*1320 *2910	1030 2270	1040 2290	710 1570	810 1790	550 1210	5.84 (19.2)
1.0 m (3 ft)	kg Ib			2250 4960	1510 3330	1430 3150	980 2160	1010 2230	690 1520	800 1760	540 1190	5.85 (19.2)
Ground Line	kg Ib	*2350 *5180	*2350 *5180	2170 4780	1440 3170	1390 3060	940 2070	990 2180	670 1480	840 1850	570 1260	5.63 (18.5)
-1.0 m (-3 ft)	kg Ib	*3600 *7940	2780 6130	2150 4740	1420 3130	1370 3020	930 2050			970 2140	660 1460	5.13 (16.8)
-2.0 m (-7 ft)	kg Ib	*3770 *8310	2830 6240	2170 4780	1440 3170					*1140 *2510	900 1980	4.23 (13.9)
-3.0 m (-10 ft)	kg Ib	*2040 *4500	*2040 *4500									

Bating over-front Rating over-side or 360 degree

6. BUCKET SELECTION GUIDE

1) GENERAL BUCKET

0.07m³ SAE	0.18 m³ SAE
heaped bucket	heaped bucket

Capacity		\\/idth		Weight	Recommendation	
Capacity		Width			3.0 m (9' 10") boom	
SAE heaped	CECE heaped	Without side cutter	With side cutter	t e g	1.6 m (5' 3") arm	
0.07 m ³ (0.09 yd ³)	0.06 m ³ (0.08 yd ³)	315 mm (12.4")	360 mm (14.2")	115 kg (255 lb)	Applicable for materials with density of 1600 kgf/m ³	
0.18 m ³ (0.24 yd ³)	0.15 m ³ (0.20 yd ³)	670 mm (26.4")	740 mm (29.1")	170 kg (375 lb)	(2700 lb/yd³) or less	

7. UNDERCARRIAGE

1) TRACKS

X-leg type center frame is integrally welded with reinforced box-section track frames. The design includes dry tracks, lubricated rollers, idlers, sprockets, hydraulic track adjusters with shock absorbing springs and assembled track-type tractor shoes with triple grousers.

2) TYPES OF SHOES

	Shapes		Triple grouser		
Model					
	Shoe width	mm (in)	380 (15)	400 (16)	
R55-9	Operating weight	kg (lb)	5450 (12020)	5450 (12020)	
N00-9	Ground pressure	kgf/cm² (psi)	0.33 (4.69)	0.33 (4.69)	
	Overall width mm (ft-in)		1880 (6' 2")	1900 (6' 3")	

3) NUMBER OF ROLLERS AND SHOES ON EACH SIDE

Item	Quantity
Carrier rollers	1 EA
Track rollers	5 EA
Track shoes	40 EA

8. SPECIFICATIONS FOR MAJOR COMPONENTS

1) ENGINE

Item	Specification		
Model	Yanmar 4TNV98-EPHYBU		
Туре	4-cycle diesel engine, low emission		
Cooling method	Water cooling		
Number of cylinders and arrangement	4 cylinders, in-line		
Firing order	1-3-4-2		
Combustion chamber type	Direct injection type		
Cylinder bore×stroke	98×110 mm (3.85"×4.33")		
Piston displacement	3319 cc (203 cu in)		
Compression ratio	18.5 : 1		
Rated gross horse power (SAE J1995)	57.8 Hp at 2400 rpm (42.5 kW at 2400 rpm)		
Maximum torque at 1550 rpm	20.5 kgf · m (148 lbf · ft)		
Engine oil quantity	11.6 / (3.1 U.S. gal)		
Dry weight	270 kg (595 lb)		
High idling speed	2400+50 rpm		
Low idling speed	1050±100 rpm		
Rated fuel consumption	175.6 g/Hp · hr at 2400 rpm		
Starting motor	12 V-3.0 kW		
Alternator	12 V-80 A		
Battery	1×12 V×100 Ah		

2) MAIN PUMP

Item	Specification		
Туре	Variable displacement tandem axis piston pumps		
Capacity	2×27.5 cc/rev		
Maximum pressure	220 kgf/cm ² (3130 psi)		
Rated oil flow	2 × 57.8 / /min (15.3 U.S. gpm / 12.7 U.K. gpm)		
Rated speed	2100 rpm		

3) GEAR PUMP

Item	Specification	
Туре	Fixed displacement gear pump single stage	
Capacity	18.3 + 4.5 cc/rev	
Maximum pressure	220/30 kgf/cm ² (3130/430 psi)	
Rated oil flow	38.4/9.5 l /min (10.1/2.5 U.S. gpm / 8.4/2.1 U.K. gpm)	

4) MAIN CONTROL VALVE

Item	Specification		
Туре	Sectional, 9 spools+1 option		
Operating method	Hydraulic pilot system+Mechanical control system		
Main relief valve pressure	220 kgf/cm ² (3130 psi)		
Overload relief valve pressure	240 kgf/cm ² (3410 psi)		

[]: Power boost

5) SWING MOTOR

Item	Specification		
Туре	Fixed displacement axial piston motor		
Capacity	32.3 cc/rev		
Relief pressure	220 kgf/cm² (3130 psi)		
Braking system	Automatic, spring applied hydraulic released		
Braking torque	14 kgf · m (101 lbf · ft)		
Brake release pressure	20~40 kgf/cm ² (284~570 psi)		
Reduction gear type	2 - stage planetary		

6) TRAVEL MOTOR

Item	Specification		
Туре	Variable displacement axial piston motor		
Relief pressure	220 kgf/cm ² (3130 psi)		
Reduction gear type	2-stage planetary		
Braking system	Automatic, spring applied hydraulic released		
Brake release pressure	9 kgf/cm ² (128 psi)		
Braking torque	8.4 kgf · m (61 lbf · ft)		

7) CYLINDER

	Item	Specification		
Deem eulinder	Bore dia \times Rod dia \times Stroke			
Boom cylinder	Cushion	Extend only		
Arm outinder	Bore dia \times Rod dia \times Stroke			
Arm cylinder	Cushion	Extend and retract		
Rueket evlinder	Bore dia \times Rod dia \times Stroke	$\emptyset 80 \times \emptyset 50 \times 660 \text{ mm}$		
Bucket cylinder	Cushion	Extend only		
Dozer blade	Bore dia \times Rod dia \times Stroke			
	Cushion	Extend only		

* Discoloration of cylinder rod can occur when the friction reduction additive of lubrication oil spreads on the rod surface.

* Discoloration does not cause any harmful effect on the cylinder performance.

8) SHOE

Item	Width	Ground pressure	Link quantity	Overall width
R55-9	380 mm (15")	0.33 kgf/cm ² (4.69 psi)	40	1880 mm (6' 2")

9) BUCKET

Item		Cap	Tooth	Width		
		SAE heaped	CECE heaped	quantity	Without side cutter	With side cutter
DEE O	STD	0.18 m ³ (0.24 yd ³)	0.15 m ³ (0.20 yd ³)	5	670 mm (26.4")	740 mm (29.1")
R55-9	OPT	0.07 m ³ (0.09 yd ³)	0.06 m ³ (0.08 yd ³)	3	315 mm (12.4")	360 mm (14.2")

9. RECOMMENDED OILS

Use only oils listed below. Do not mix different brand oil. Please use HYUNDAI genuine oil and grease.

	Kind of fluid	Capacity ℓ (U.S. gal)	Ambient temperature °C (°F)						
Service point			-20		0			30	40
			(-4)	(14)	(32)	(50)	(68)	(86)	(104)
Engine oil pan	Engine oil	11.6 (3.1)					SAE	20	
							SAE	30	
				S	SAE 10W	/			
			SAE 10W-30						
						SAE 1	5W-40		
	Grease	0.35 (0.09)							
Swing drive			N	ILGI NO.	1				
						N	ILGI NO.2		
	Gear oil	1.5 (0.4)							
						SAE 8	0\\/_QO		
Final drive	Gear oil	1.2×2 (0.3×2)				JAL 0	000-30		
	Hydraulic oil	Tank: 70 (18.5) System: 120 (31.7)							
			ISO VG 32						
I budue dia tamb									_
Hydraulic tank						ISO VG	46		
						10	SO VG 68		
						- K			
	Diesel fuel	120 (31.7)							
Fuel tank			ASTI	M D975 I	NO.1				
						ASTI	M D975 N	0.2	
Fitting (Grease nipple)	Grease	As required	N	ILGI NO.	4]			
				ILGI NO.	I				
						NLGI	NO.2		
Radiator (Reservoir tank)	Mixture of antifreeze and water 50 : 50	9.5 (2.5)							
				E	thylene (glycol ba	se permar	nent type)

SAE : Society of Automotive Engineers

API : American Petroleum Institute

ISO : International Organization for Standardization

NLGI : National Lubricating Grease Institute

ASTM : American Society of Testing and Material

SECTION 2 STRUCTURE AND FUNCTION

Group	1 Pump Device	2-1
Group	2 Main Control Valve	2-9
Group	3 Swing Device	2-31
Group	4 Travel Device	2-41
Group	5 RCV Lever ······	2-50

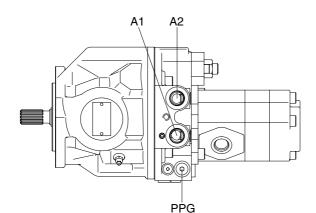
GROUP 1 HYDRAULIC PUMP

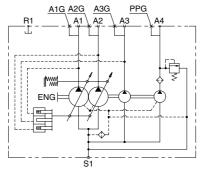
1. GENERAL

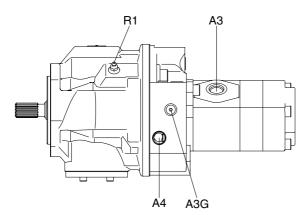
This is a variable displacement double-piston pump for discharge with equal displacements from one cylinder block. This pump is so compact as to appear a single pump though this is actually a double pump.

Because this pump has one swash plate, the tilting angle is the same for two pumps. Tilting of the pump changes in response to the total pressure of P1 + P2. Namely, the output is controlled to the constant value so that the relationship between the discharge pressure and flow rate Q becomes constant, $(P1 + P2) \times Q$ =Constant.

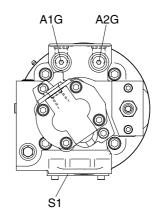
The third pump and pilot pump can be connected to the same shaft via a coupling.









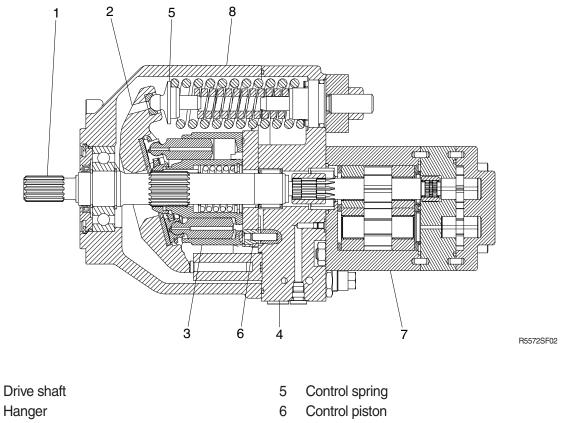


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Description of the ports

Port Name		Bore		
S1	Suction port	SAE 1 1/2 (standard)		
A1, A2	Discharge port	PF 1/2		
A3	Discharge port	PF 1/2		
A4	Discharge port	PF 1/4		
A1G, A2G	Gauge port	PF 1/4 With quick coupler		
A3G	Gauge port	PF 1/8 With quick coupler		
A4G	Gauge port	PF 1/4 With quick coupler		
R1	Air bleeder port	M10 \times 1.0 (with bleeder valve)		

2. PRINCIPAL COMPONENTS AND FUNCTIONS



- 3 Rotary group
- 4 Cover

1

2

- 7 Gear pump
- 8 Housing

SPECIFICATIONS

- Capacity : 2 × 27.5+18.3+4.5 cc/rev
- Rated oil flow : 2 × 57.8+38.4+9.5 *l* /min
- Rated pressure : 3 × 220+30 kgf/cm²

This is a variable displacement double-piston pump for discharge with two equal displacements from one cylinder block. Because this is one rotary group, there is only one suction port.

The oil is divided into two equal flows by the control plate in the cover and directed to two discharge ports provided in the cover.

The discharge pressure directed to the control piston tilts the hanger by overcoming the spring force.

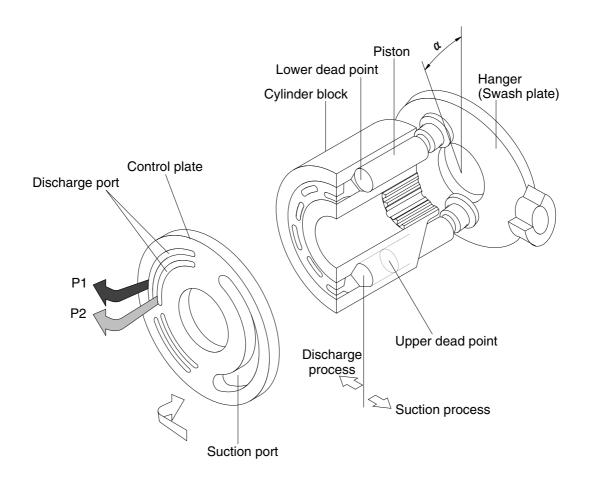
Since the piston stroke changes according to the tilting angle of the hanger, the flow can be changed.

The simultaneous tilting angle constant-output control method is employed.

The third pump and pilot pump can be connected to the same shaft via a coupling.

1) PRINCIPLE OF OPERATION

(1) Function of pump



R5572SF03

The cylinder block is connected via spline and can rotate together with the drive shaft.

The piston assembled into the cylinder block performs reciprocal operation while following the swash plate on the hanger.

The piston moves in a direction to increase the displacement during a stroke from the lower to the upper dead points. The oil flows from the suction port via a port plate into the cylinder block (suction process).

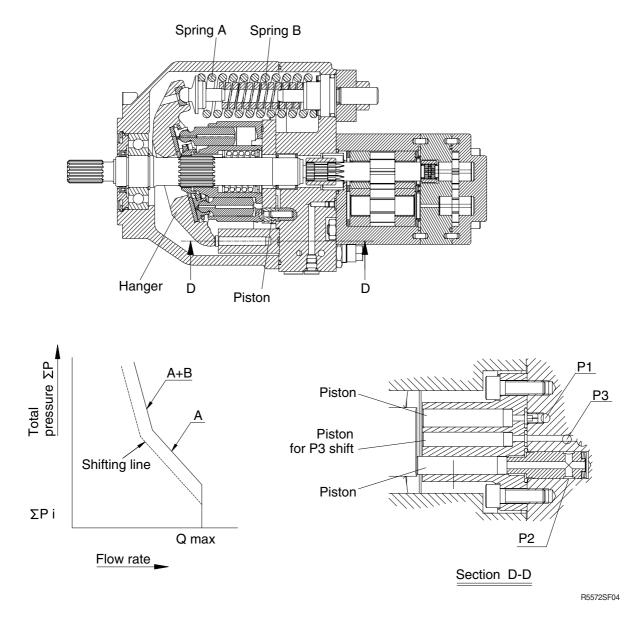
During a stroke from the upper to the lower dead points, the piston moves in a direction to decrease the displacement. The oil is discharged to the discharge port (discharge process).

The displacement can be changed by changing the tilting of the hanger (swash plate).

The oil sucked through the port in the cylinder block is discharged from the discharge port in the port plate.

The oil sucked through the port on the outside of the cylinder block is discharged from the discharge port on the outside of the port plate.

2) CONTROL FUNCTIONS



The discharge pressures P1 and P2 are directed to the pistons of equal area act on the hanger.

The spring is provided to act against the discharge pressure. When the oil pressure acting on the piston is less than the installation load of the spring A (outer spring), the hanger is fixed to the maximum tilting position. When the oil, pressure acting on the piston exceeds the installation load of the spring A the hanger is tilted and kept tilted at a position where the oil pressure is balanced with the spring force. (region A in the middle of the figure above)

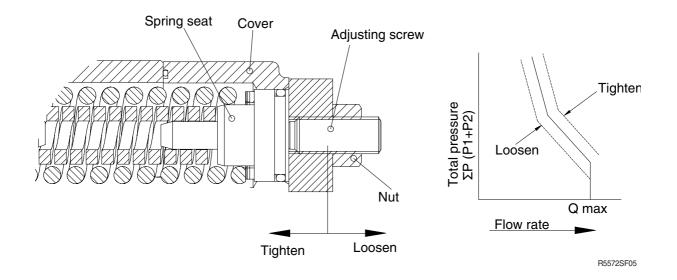
When the oil pressure acting on the piston rises further to reduce the tilting angle, the spring B which has been inactive up to now becomes active.

To overcome the spring force of two springs, the oil pressure must be higher and the shifting line becomes more steep. (regions A + B in the middle of the figure above)

When the P3 oil pressure acts on the shift piston, the control shifting line is shifted.

3) CONTROL / ADJUSTMENT PROCEDURE

- (1) Loosen the hexagonal nut.
- (2) Tighten or loosen the adjusting screw to set the power shifting line.



3. ADJUSTMENT

This hydraulic pump has been set and inspected according to your specified input power and control. Readjustment of all the adjusting portions may lead to the loss of functions specified for each control and the pump proper may be excluded from the scope of guarantee. Never attempt operating the adjusting screw, etc.

4. INSTALLATION

- (1) Install the pump so that the input shaft becomes horizontal.
- (2) Install the pump in a position lower than the lowest oil level in the tank to allow continuous flow of the oil into the pump.
- (3) Since the pump is installed directly to the diesel engine, always use a flexible hose. Install the suction pipe firmly to prevent suction of an air.
- (4) Use the high-pressure type flexible hoses for the discharge ports P1 and P2.
- (5) After installation, fill the pump housing with the hydraulic oil.
- (6) Do not direct the external drain piping from within the oil.

5. DRIVE

- (1) Use a flexible coupling for connection to the motor.
- (2) Insert the coupling firmly onto the input shaft. Do not hammer the coupling during insertion.
- (3) The input shaft must rotate clockwise when viewed from the shaft end.

6. HYDRAULIC OIL

The hydraulic oil to be used must be a general petroleum, hydraulic oil or wear-resistant hydraulic oil (ISO 3448, VG 32 ~ 56 or equivalent).

The applicable viscosity range is as follows :

Maximum allowable viscosity : 1000 mm²/s

Minimum allowable viscosity : 10 mm²/s

Recommended viscosity range : 15 ~ 150 mm²/s

7. STARTING PROCEDURE

* Before start up, check the following points and observe the cautions :

- (1) Check if the tank has been washed clean.
- (2) Check if the piping is clean and installed in such a manner as to prevent stress on the pump.
- (3) Check if the piping is connected correctly according to the piping (circuit) diagram.
- (4) Check if the joint and flange are correctly tightened.
- (5) Check if the joint between the motor and pump is correctly installed.
- (6) Check if the motor rotation direction agrees with the pump rotation direction.
- (7) Check if the specific hydraulic oil is supplied though the filter and filled in the tank to the specified position of the oil level gage.
- (8) Check if the filter has the specified filtration accuracy (10 μ m or less).
- (9) Check if the filter has been installed correctly relative to the float direction.
- (10) Check if the pump housing is filled with oil.
- (11) Check if the control valve is set to the bypass position.
- (12) Start the motor. If necessary, carry out warm-up operation at low speed.
- (13) Check, without any load on the system, if the actuator operates correctly.

- (14) When the motor has reached the operation speed, check the operation while applying the load to the actuator.
- (15) Check the monitoring or measuring instrument if installed.
- (16) Check the noise level.
- (17) Check the oil level in the tank. Supply the oil. If required.
- (18) Check the setting of the pressure control valve while applying the load to the actuator.
- (19) Check the parts for any leakage.
- (20) Stop the motor.
- (21) Retighten all the bolts and plugs even when they have proved to by free from Leakage. (Be sure to remove the pressure from the circuit before retightening.)
- (22) Check the oil level in the tank.
- (23) Check if the pump and actuator function correctly.
- (24) Irregular operation of the actuator indicates that an air is left still in the circuit. When the air is bleeded completely from the circuit, all the parts operates smoothly without any irregular movement and there is no bubble in the oil of the tank.
- (25) Check the oil temperature.
- (26) Stop the motor.
- (27) Check the filter if the element is fouled.
- (28) If the element is heavily fouled, carry out flashing in the circuit.
- * To prevent damage to the pump, be sure to observe the following cautions during the operation which may allow entry of the actuator, hydraulic oil change, etc :
- (1) After oil supply, fill the pump housing with the hydraulic oil.
- (2) Start the pump with the speed of 1000 rpm or less and take care not to allow the oil level to lower below the specified level of the oil level gauge.
- (3) When bleeding an air from the hydraulic circuit, keep the motor speed at 1000 rpm or less. Operate each actuator for three or more cycles and carry out idling for 5 minutes or more.

8. MAINTENANCE

The maintenance of this hydraulic pump is limited mainly to the tank, in particular, the hydraulic oil change.

Since the maintenance interval varies depending on respective operation and use conditions, the cautions described below for the users should be for reference only.

(1) Checking the filter

- ① Every day for the initial period after start up.
- 0 Once a week when the operation becomes stable.
- ③ Once a month when the operation hours exceed about 100 hours.
- * When any part of the hydraulic system is changed (e.g., assembling of an additional part, change and repair of the piping), check the filter newly as in the case of startup.

(2) Changing the filter

- ① After startup
- ② After 500 hours of operation
- ③ Every 500 hours of operation after that, and each time the hydraulic oil is changed or the failure occurs. If any abnormal fouling of the filter is observed during daily check up to the first filter change after startup, find out the cause.

In this case, do not extend the check and filter change intervals to 500 hours.

* The paper filter can not be cleaned. Change the filter as a whole.

(3) Changing the hydraulic oil

- After 2000 hours of operation.
- 2 Every 2000 hours of operation or once a year after that.

The change interval may have to be shortened depending on the degree of fouling and the thermal load condition of the hydraulic oil.

If the hydraulic oil is not appropriate and need be changed, pay attention to the following points :

Be sure to control the oil temperature below the highest temperature and above the lowest temperature during operation in winter and summer.

- Pay attention to the following points during change of the hydraulic oil :
- Change the hydraulic oil as a whole quantity.
- Do not allow dust to mix into the circuit.
- Clean the tank inside.
- Supply the oil through the filter.

(4) Checking for the oil leakage

- 1 Daily during the initial period after startup.
- O Once a week when the operation becomes stable.

(5) Checking the temperature

- ① Monitor the temperature continuously.
- 2 When the viscosity is above the allowable value because of low hydraulic oil temperature, warm-up operation is necessary.

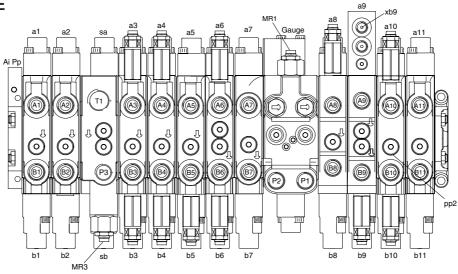
Start the motor with the speed set to about one half of the rated speed, then operate the actuator under the load for a short period.

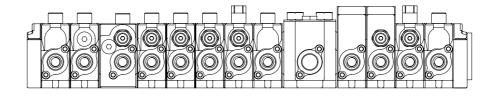
When the oil temperature is below the allowable ambient temperature, it is necessary to preheat the oil tank before start of the motor.

Take care not to allow the hydraulic oil temperature to exceed +90°C

GROUP 2 MAIN CONTROL VALVE

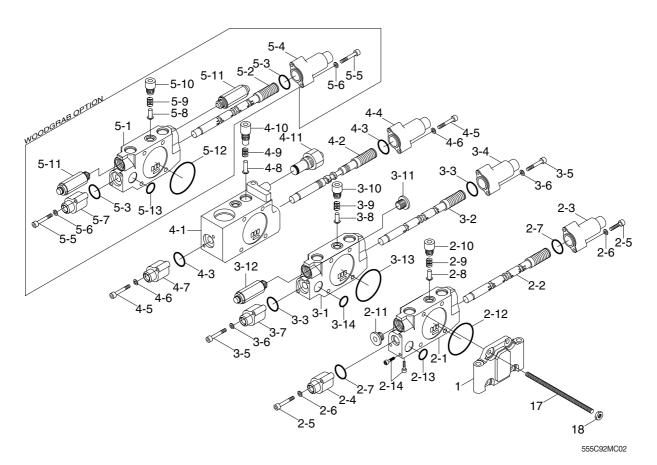
1. OUTLINE





Mark	Port name	Port size	Tightening torque	Mark	Port name	Port size	Tightening torque
P1	P1 pump port			B10	Bucket in port		
P2	P2 pump port			B11	Arm 2 port	PF 1/2	6.0~7.0 kgf ⋅ m
P3	P3 pump port			T2	Tank return port	1/2	Kgi * III
A1	Swing port (LH)			T1	Tank return port	PF1	10~12 kgf · m
B1	Swing port (RH)			a1	Swing pilot port (LH)		
A2	Dozer down port			b1	Swing pilot port (RH)		
B2	Dozer up port		PF 1/2 6.0~7.0	a2	Dozer down pilot port	-	
A3	Woodgrab rotate port (LH)			b2	Dozer up pilot port		
B3	Woodgrab rotate port (RH)			a3	Woodgrab rotate pilot port (LH)		
A4	Woodgrab close port			b3	Woodgrab rotate pilot port (RH)		
B4	Woodgrab open port	PF		a4	Woodgrab open pilot port		
A5	Boom 2 port	1/2		b4	Woodgrab close pilot port		
B5	Breaker port		kgf ∙ m	a5	Boom 2 pilot port	PF	
A6	Arm out port			b5	Breaker pilot port	1/4	2.5~3.0 kgf ∙ m
B6	Arm in port			a6	Arm out pilot port		
A7	Travel port [LH/FW]			b6	Arm in pilot port		
B7	Travel port [LH/RR]			a9	Boom up pilot port		
A8	Travel port [RH/FW]			b9	Boom down pilot port		
B8	Travel port [RH/RR]			a10	Bucket out pilot port		
A9	Boom up port			b10	Bucket in pilot port		
B9	Boom down port			a11	Arm 2 pilot port		
A10	Bucket out port			b11	Arm 2 pilot port		
MR1 MR2	Main relief valve	-		PP2	Bucket load check pilot port	PF1/8	

2. STRUCTURE (1/4)

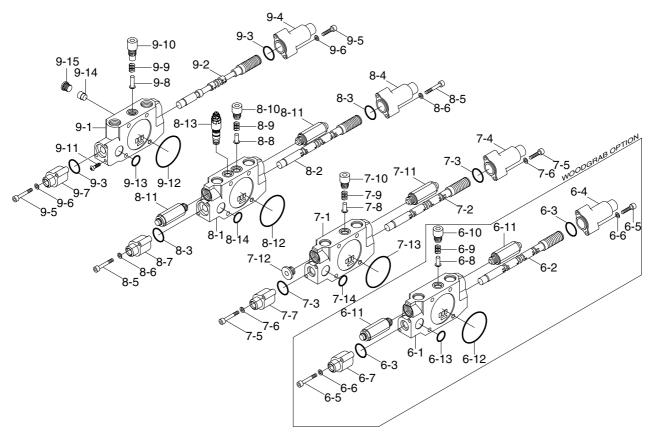


- 1 Cover
- 2 Swing block
- 2-1 Block
- 2-2 Swing spool assy
- 2-3 Pilot cap (A)
- 2-4 Pilot cap (B1)
- 2-5 Wrench bolt
- 2-6 Plain washer
- 2-7 O-ring
- 2-8 Check poppet
- 2-9 Check spring
- 2-10 Plug
- 2-11 Plug
- 2-12 O-ring
- 2-13 O-ring
- 2-14 Plug
- 3 Dozer block
- 3-1 Block
- 3-2 Dozer spool assy
- 3-3 O-ring

- 3-4 Pilot cap (A)
- 3-5 Wrench bolt
- 3-6 Plain washer
- 3-7 Cap
- 3-8 Check poppet
- 3-9 Check spring
- 3-10 Plug
- 3-11 Plug
- 3-12 Check valve
- 3-13 O-ring
- 3-14 O-ring
 - 4 Inlet block
- 4-1 Block
- 4-2 Inlet spool assy
- 4-3 O-ring
- 4-4 Pilot cap (A)
- 4-5 Wrench bolt
- 4-6 Plain washer
- 4-7 Pilot cap (B1)
- 4-8 Check poppet

- 4-9 Check spring
- 4-10 Plug
- 4-11 Main relief valve
- 5 Swing block
- 5-1 Block
- 5-2 Swing spool assy
- 5-3 O-ring
- 5-4 Pilot cap (A)
- 5-5 Wrench bolt
- 5-6 Plain washer
- 5-7 Pilot cap (B1)
- 5-8 Check poppet
- 5-9 Check spring
- 5-10 Plug
- 5-11 Overload relief valve
- 5-12 O-ring
- 5-13 O-ring
- 17 Tie bolt
- 18 Nut

STRUCTURE (2/4)



- 6 Woodgrab block
- 6-1 Block
- 6-2 Woodgrab spool assy
- 6-3 O-ring
- 6-4 Pilot cap (A)
- 6-5 Wrench bolt
- 6-6 Plain washer
- 6-7 Pilot cap (B1)
- 6-8 Check poppet
- 6-9 Check spring
- 6-10 Plug
- 6-11 Overload relief valve
- 6-12 O-ring
- 6-13 O-ring
- 7 Boom 2 block
- 7-1 Block
- 7-2 Boom 2 spool assy
- 7-3 O-ring
- 7-4 Pilot cap (A1)
- 7-5 Wrench bolt

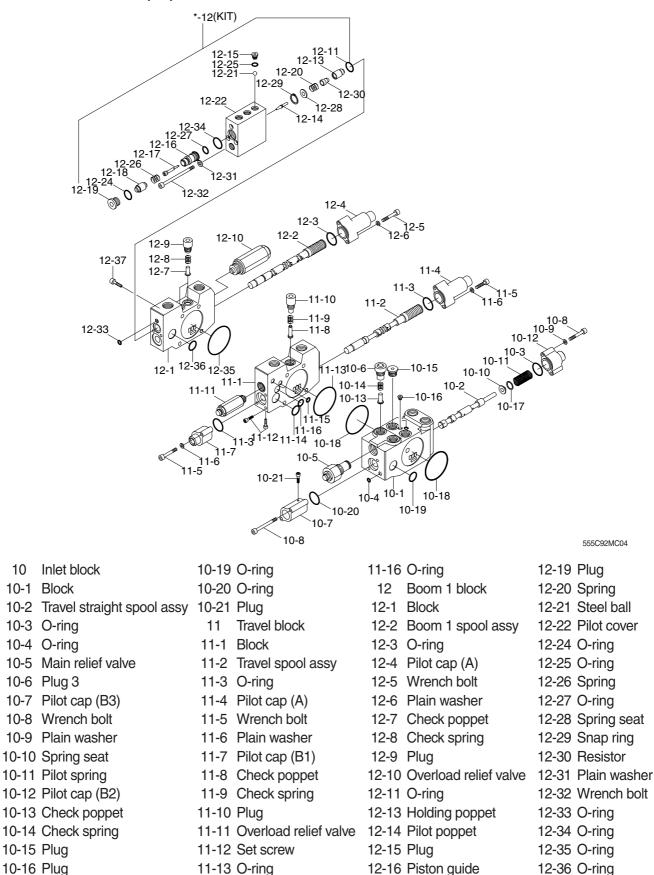
- 7-6 Plain washer
- 7-7 Pilot cap (B1)
- 7-8 Check poppet
- 7-9 Check spring
- 7-10 Plug
- 7-11 Overload relief valve
- 7-12 Plug
- 7-13 O-ring
- 7-14 O-ring
- 8 Arm 1 block
- 8-1 Block
- 8-2 Arm 1 spool assy
- 8-3 O-ring
- 8-4 Pilot cap (A)
- 8-5 Wrench bolt
- 8-6 Plain washer
- 8-7 Pilot cap (B1)
- 8-8 Check poppet
- 8-9 Check spring
- 8-10 Plug

- 8-11 Overload relief valve
- 8-12 O-ring
- 8-13 Check valve
- 8-14 O-ring
 - 9 Travel block
- 9-1 Block
- 9-2 Travel spool assy
- 9-3 O-ring
- 9-4 Pilot cap (A)
- 9-5 Wrench bolt
- 9-6 Plain washer
- 9-7 Pilot cap (B1)
- 9-8 Check poppet
- 9-9 Check spring
- 9-10 Plug
- 9-11 Plug
- 9-12 O-ring
- 9-13 O-ring
- 9-14 Poppet
- 9-15 Spring seat

STRUCTURE (3/4)

10-17 Spring shim

10-18 O-ring

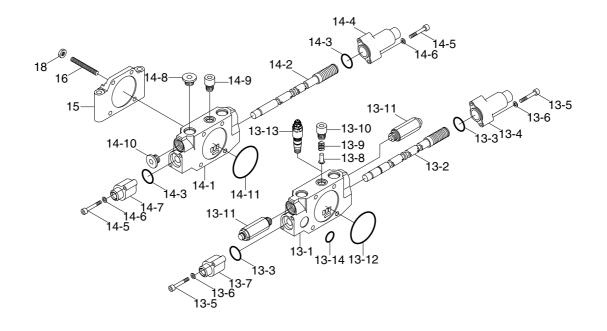


12-37 Socket bolt

11-14 O-ring

11-15 O-ring

¹²⁻¹⁷ Piston 12-18 Pilot piston

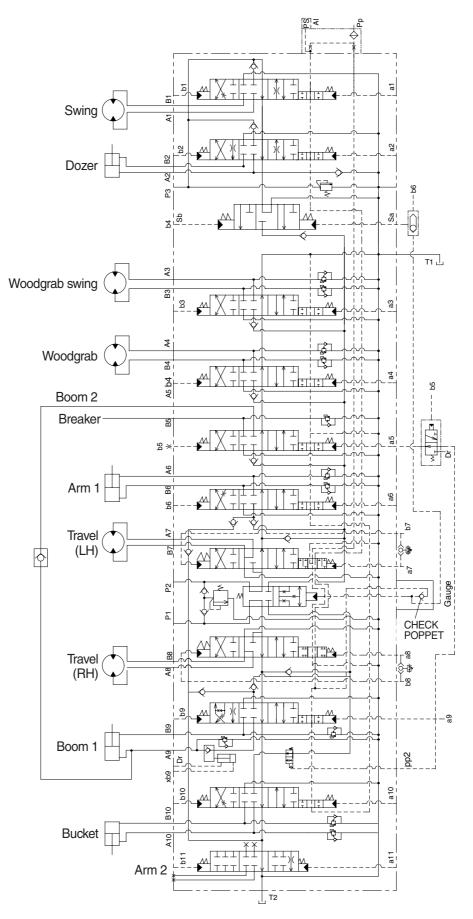


13 Bucket block
13-1 Block
13-2 Bucket spool assy
13-3 O-ring
13-4 Pilot cap (A)
13-5 Wrench bolt
13-6 Plain washer
13-7 Pilot cap (B1)
13-8 Check poppet
13-9 Check spring

13-10 Plug
13-11 Relief valve
13-12 O-ring
13-13 Check valve
13-14 O-ring
14-1 Arm 2 block
14-2 Arm 2 assy
14-3 O-ring
14-4 Pilot cap (A)

- 14-5 Wrench bolt14-6 Plain washer14-7 Pilot cap (B1)
- 14-8 Plug
- 14-9 Plug
- 14-10 Plug
- 14-11 O-ring
 - 15 Cover
- 16 Tie bolt
- 18 Nut

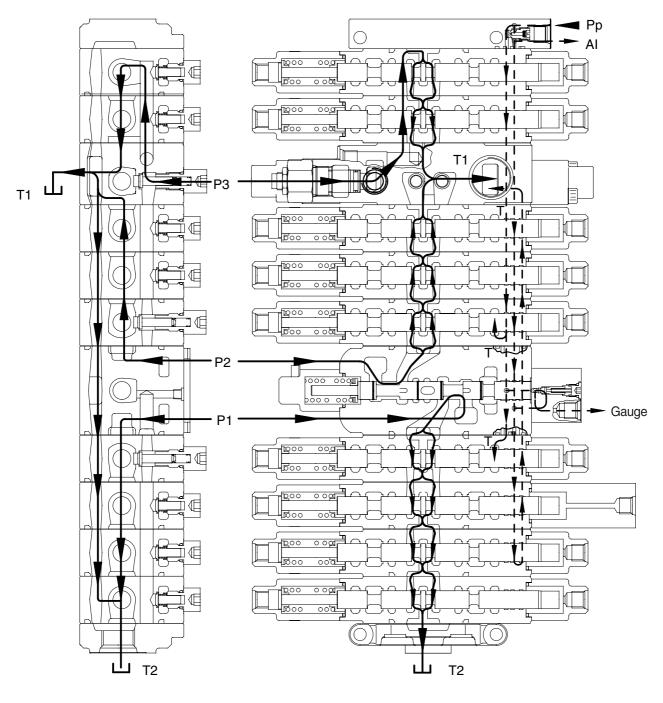
3. HYDRAULIC CIRCUIT



5592MC02

4. FUNCTION

1) CONTROL IN NEUTRAL FUNCTION



555C92MC07

In neutral, spring sets the spool at the neutral position, the hydraulic oil from pumps flows to the tank through the center bypass.

(1) P1

The oil discharged from the hydraulic pump flows into control valve P1 port, and then flows the right side travel valve through the travel straight valve. In neutral, the oil flows through the center bypass passage in the direction of right travel \rightarrow boom 1 \rightarrow bucket \rightarrow arm 2 spool, and then flows from the center bypass passage to the tank port T1 and T2.

(2) P2

The oil discharged from the hydraulic pump flows into control valve P2 port, and then flows the left side travel valve through the travel straight valve. In neutral, the oil flows through the center bypass passage in the direction of left travel \rightarrow arm 1 \rightarrow boom 2/breaker spool, and then flows from the center bypass passage to the tank port T1 and T2.

(3) P3

The oil discharged from the hydraulic pump flows into control valve P3.

In neutral, the oil flows through the center bypass passage in the direction of swing \rightarrow dozer spool, and then flows from the center bypass passage to the tank port T1 and T2.

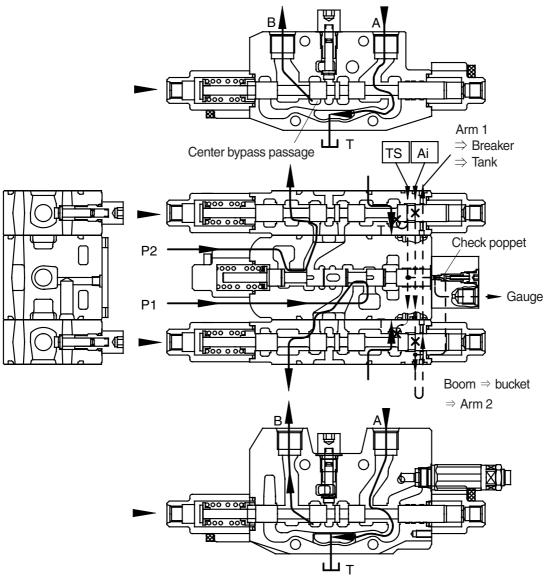
(4) Pp

When Pp port is applied with pilot pressure, the oil flows into the swing block through TS signal passage and Ai signal passage independently via an orifice.

With the spool in neutral, the oil flows into the tank passage through the all section of the control valve(except arm 2 section). As a result, the TS valve is not shifted and the auto idle signal pressure is not raised.

2) EACH SPOOL OPERATION

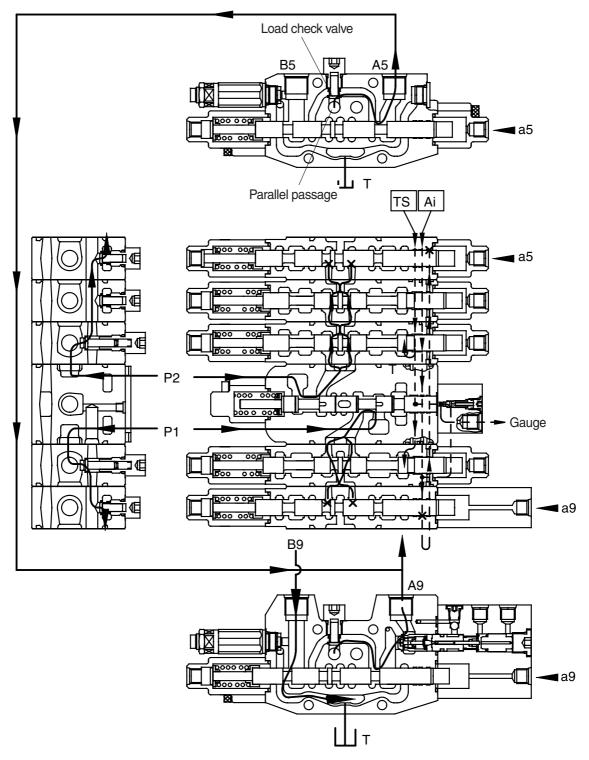
(1) Travel operation (forward / backward)



- During travel (forward/backward) operation, the pilot pressure from RCV is supplied into the travel pilot port and shift the travel spool in the right direction.
- The hydraulic oil fluid from pump is entered center bypass passage of inlet block (P1, P2) and then flows into the port of travel motor.
- The oil from the port A of travel motor flows into the main control valve and return to the hydraulic oil tank through the tank passage.
- The TS signal passage is shut off by shifting of the travel spool, but it is connected with Ai signal passage and drain to the hydraulic oil tank. As a result, the travel straight spool is not shifted.
- The Ai signal passage is connected with travel block through swing and dozer block and it is shut off by shifting of the travel spool and then signal pressure of auto idle is raised.

(2) Boom operation

① Boom up operation (P1 and P2 summation)



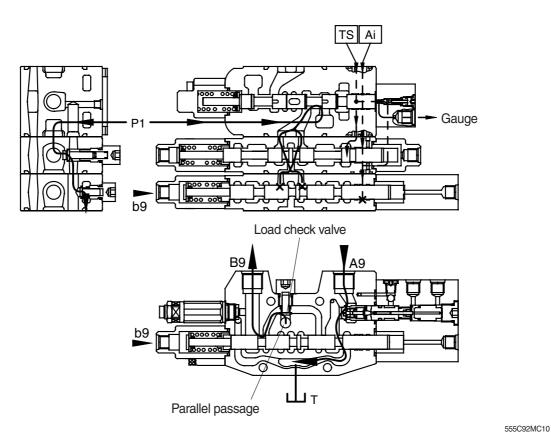
 During boom up operation, the pilot pressure from RCV is supplied into the port a9 and shift the boom 1 spool in the left direction. The hydraulic oil fluid from pump P1 is entered P1 parallel passage and then passes through the load check valve then flows into the port A9.
 Following this, it flows into the head side of the boom cylinder.

At the same time the pilot pressure through the port a5 shifts the boom 2 spool. The hydraulic oil fluid from pump P2 is entered P2 parallel passage and then passes through the load check valve then flows into the port A5. The flows combine in hydraulic hoses and are directed to the cylinder head side of boom cylinder.

The flow from rod side of the boom cylinder return to the boom 1 spool through the port B9. There after it is directed to the hydraulic oil tank through the tank passage.

- The TS signal passage oil from the Pp port is drain to the hydraulic oil tank through the left/right travel valve and the signal pressure is not raised.
- The Ai signal passage oil from the Pp port is shut off by shifting of the boom 1 spool and then signal pressure of auto idle is raised.

2 Boom down operation



• During the boom lowing operation, the pilot pressure from RCV is supplied to the port b9 and

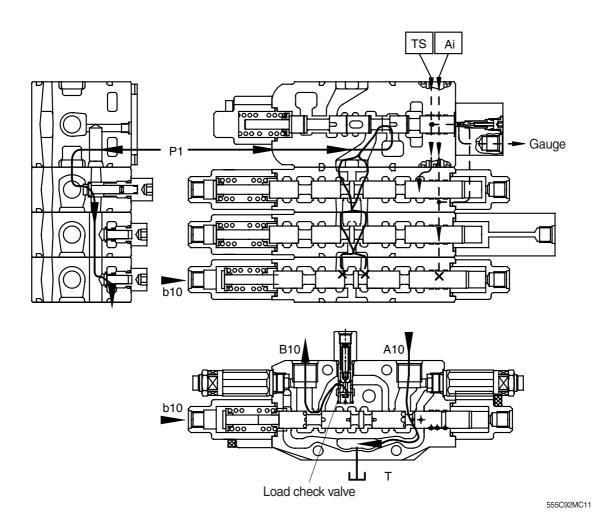
shift the boom 1 spool in the right direction. The hydraulic fluid from the pump P1 enters the parallel passage and is directed to the port B9 through the load check valve. Following this, it flows into the rod side of the boom cylinder.

The return flow from the head side of the boom cylinder returns to the boom 1 spool through the port A9. Thereafter it is directed to the hydraulic oil tank through tank passage.

• The hydraulic oil flow from the Pp port is same as the boom up operation.

(3) Bucket operation

1 Bucket roll in operation



• During the bucket roll in operation, the pilot pressure from RCV is supplied to port b10 and shift the bucket spool in the right direction.

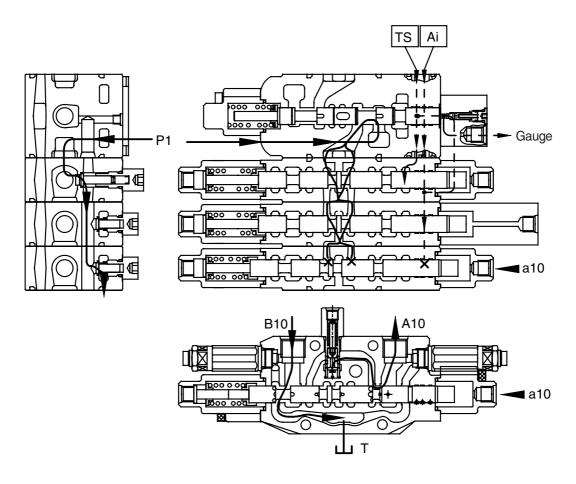
The hydraulic fluid from pump P1 entered P1 parallel passage and is directed to the port B10 through the load check valve.

Following this, it flows into the head side of the bucket cylinder.

The return flow from the rod side of the bucket cylinder returns to the bucket spool through the port A10. Thereafter it is directed to the hydraulic oil tank through the tank passage.

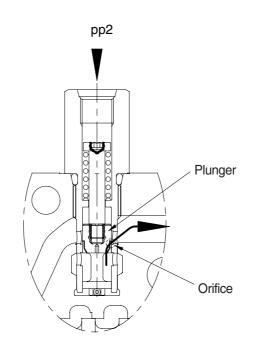
- The TS signal passage oil from the Pp port is drain to the hydraulic oil tank through the left/right travel valve and the signal pressure is not raised.
- The Ai signal passage oil from the Pp port is shut off by shifting of the bucket spool and then signal pressure of auto idle is raised.

$\ensuremath{\textcircled{}^{2}}$ Bucket roll out operation



- In case of the bucket roll out operation, the operation is similar.
- $\cdot\,$ The hydraulic oil flow from the Pp port is same as the bucket in operation.

③ Bucket load check valve operation



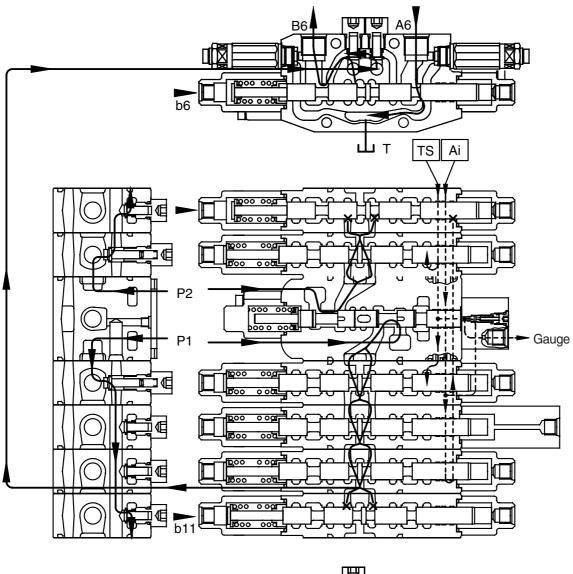
555C92MC13

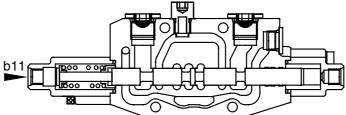
- This function is used to speed up of the boom or arm by reducing the bucket speed when bucket operation with boom or arm operation simultaneously.
- When the signal pressure flows into port pp2, the plunger is shifted and orifice is made.
- The hydraulic oil from the port P1 flow into bucket cylinder via the orifice and then the speed of bucket cylinder is slow down.

Accordingly, the much fluid from the port P1 is supplied other cylinder than the bucket cylinder.

(4) Arm operation

① Arm roll in operation (P1 and P2 summation)





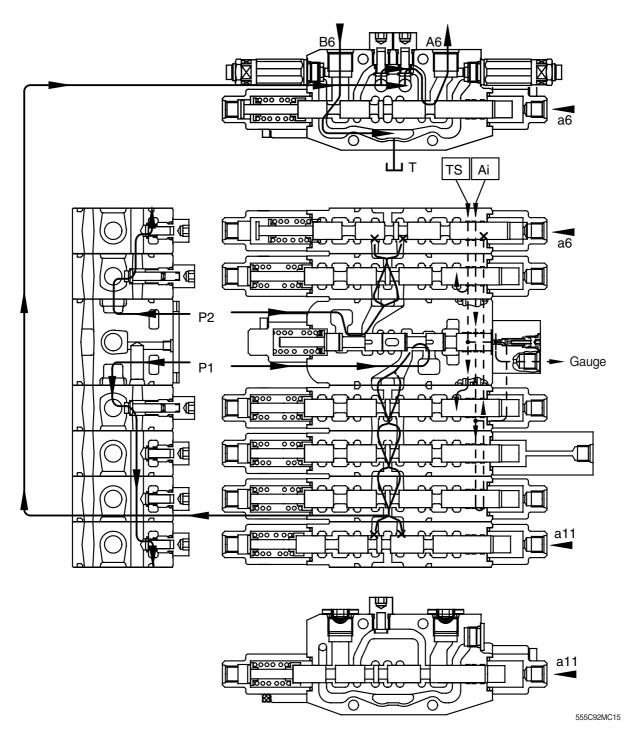
• During arm roll in operation the pilot pressure from the RCV is supplied to the port b6 and b11 and shifts arm 1 spool and arm 2 spool in the direction.

The hydraulic oil from the pump P2 flows into the arm cylinder head side through P2 parallel passage, the load check valve and the port B6.

At same time, the hydraulic fluid from the pump P1 flows into the arm summation passage in arm 1 spool through the arm 2 spool. Then it entered the arm cylinder head side with hydraulic fluid from arm 1 spool.

- The TS signal passage oil from the Pp port is drain to the hydraulic oil tank through the left/right travel valve and the signal pressure is not raised.
- The Ai signal passage oil from the Pp port is shut off by shifting of the arm spool and then signal pressure of auto idle is raised.

2 Arm roll out operation



• During arm roll out operation the pilot pressure from RCV is supplied to the port a6 and the a11 and shifts arm 1 spool and arm 2 spool in the left direction.

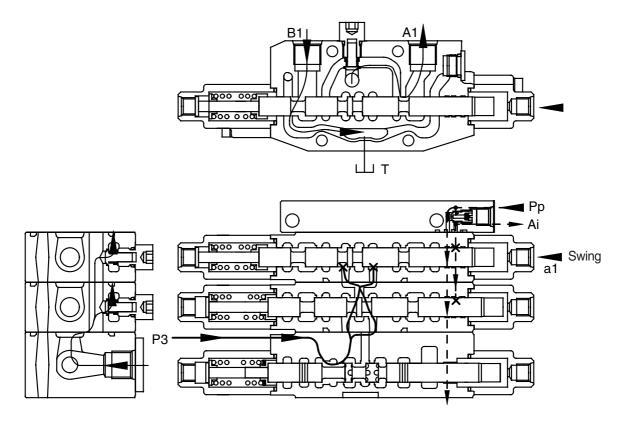
The hydraulic fluid from pump P2 flows into arm 1 spool through the parallel passage. Then it enters into the arm cylinder rod side through the load check valve and the port A6.

At same time, the hydraulic oil from the pump P1 flows into the arm summation passage in arm 1 spool through the arm 2 spool.

The return flow from the arm cylinder head side returns to the hydraulic tank through the port B6 the arm1 spool and tank passage.

• The hydraulic oil flow from the Pp port is same as the arm roll in operation.

(5) Swing operation



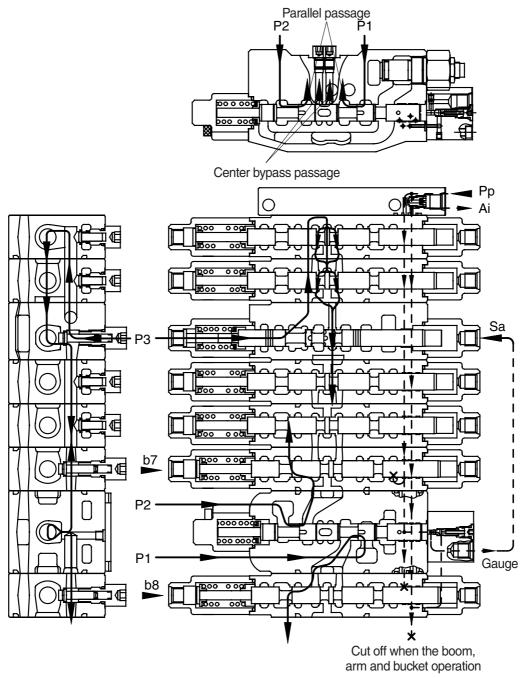
555C92MC16

 The pilot pressure from the RCV is supplied to the a1 and shift the swing spool in left direction. The hydraulic fluid from pump P3 flows into swing spool through the parallel passage. Then it is directed to swing motor through the port A1. As a result, swing motor turns and flow from the swing motor returns to the hydraulic oil tank through the port B1, swing spool and the tank passage.

In case of swing left operation, the operation is similar.

- The TS signal passage oil from the Pp port is drain to the hydraulic oil tank through the left/right travel valve and the signal pressure is not raised.
- The Ai signal passage oil from the Pp port is shut off by shifting of the swing spool and then signal pressure of auto idle is raised.

(6) Travel straight function



- This function keeps straight travel in case of simultaneous operation of other actuators (boom, arm, bucket, swing, woodgrab) during a straight travel.
- $(\underline{)}$ During travel only :

The hydraulic fluid of the pump P1 is supplied to the travel motor and the pump P2 is supplied to the other motor.

Thus, the machine keep travel straight.

(2) The other actuator operation during straight travel operation.

When the other actuator spool(s) is selected under straight travel operation, the straight travel spool is moved.

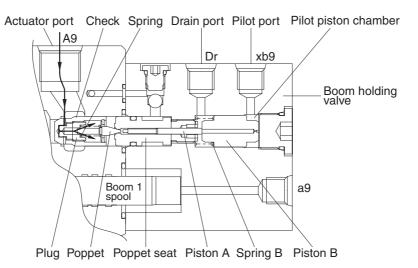
Some of hydraulic fluid from pump P1 and P2 is supplied to the travel motors through parallel passage and the other hydraulic fluid is supplied to the actuator(s) through center bypass passage via orifice passage.

Thus, the machine keeps straight travel.

 The fluid flows into P3 pilot port Sa through the gauge port and the spool is shifted. As a result, the fluid of P3 pump is combined with the boom, arm and bucket and then the actuators speed up.

(7) Holding valve operation

① Holding operation



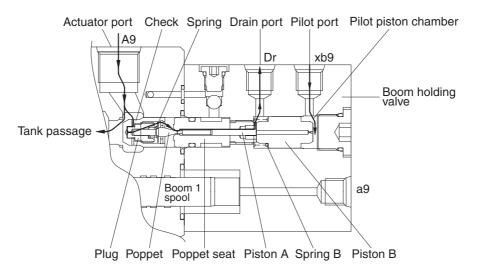
55W72MC16

At neutral condition, the pilot piston chamber is connected to drain port through the pilot port. And the piston "B" is supported with spring "B".

Also, the pressured fluid from actuator entered to inside of the holding valve through the periphery hole of check, crevice of the check and the plug and the periphery hole of plug.

Then, this pressured oil pushed the poppet to the poppet seat and the check to the seat of body. So the hydraulic fluid from actuator is not escaped and the actuator is not moved.

2 Release holding operation



55W72MC17

The pilot pressure is supplied to the pilot port for release holding valve and shifts the piston "B" in the left direction against the spring "B", and shifts the poppet in the left direction through piston "B" and piston "A" against spring "B" and shifts the spool in the left side.

At same time, the return fluid from actuator returns to the drain port through the periphery hole of check, crevice of the check and the plug, the periphery hole of the plug, in side of holding valve,

crevice of the poppet and the poppet seat, the periphery hole of the poppet seat, crevice of socket and spool and internal passage of spool.

When the poppet is opened, pressure of inside of holding valve is decreased and the return fluid from actuator returns to the tank passage through the notch of spool.

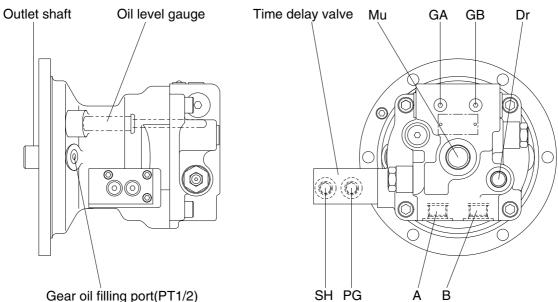
GROUP 3 SWING DEVICE

1. STRUCTURE

Swing device consists swing motor, swing reduction gear.

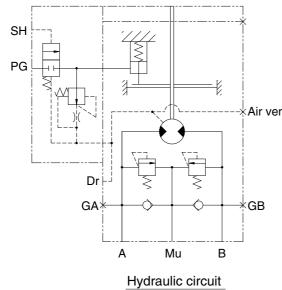
1) SWING MOTOR

Swing motor include mechanical parking valve, relief valve, make up valve and time delay valve.

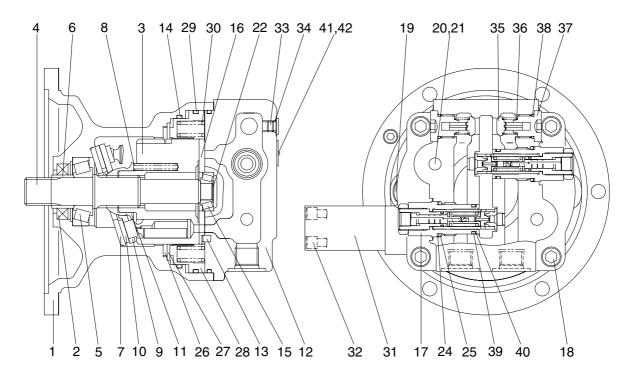


Gear oil filling port(PT1/2)

5592SM01



	Port	Port name	Port size	
nt	А	Main port	SAE PF 1/2	
	В	Main port	SAE PF 1/2	
	Dr	Drain port	PF 3/8	
	Mu	Make up port	PF 3/4	
	PG	Brake release stand by port	PF 1/4	
	SH	Brake release pilot port	PF 1/4	
	GA,GB	Gauge port	PF 1/4	



555K2SM03

1 Body

Oil seal

Shaft

Bushing

Spring

Set plate

Ball guide

12 Rear cover

10 Piston shoe assy

Shoe plate

Cylinder block

Taper bearing

2

3

4

5

6

7

8

9

11

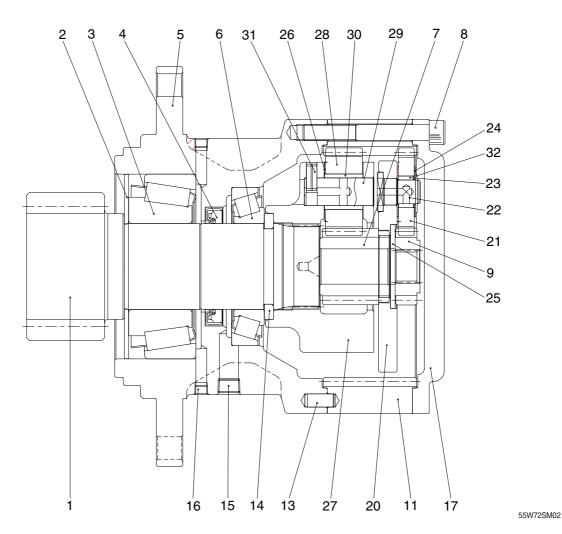
13

- 15 Taper bearing
- 16 Valve plate
- Relief valve assy 17
- 18 Socket bolt
 - 19 Plug
 - 20 Plug
 - O-ring 21
 - 22 Shim
 - 23 Plug
 - 24 Back up ring
 - 25 O-ring
 - 26 Friction plate
 - 27 Plate
 - 28 Parking piston

- 29 O-ring
- 30 Spring
- Time delay valve 31
- 32 Socket bolt
- 33 Plug
- 34 O-ring
- 35 Valve
- 36 Spring
- 37 Plug
- 38 O-ring
- 39 O-ring
- 40 Back up ring
- 41 Name plate
- 42 Rivet

Pin 14 O-ring

2) REDUCTION GEAR



- 1 Shaft
- 2 Bearing cover
- 3 Taper roller bearing
- 4 Case
- 5 Oil seal
- 6 Taper roller bearing
- 7 Sun gear 2
- 8 Socket bolt
- 9 Sun gear 1
- 10 Carrier assy 1
- 11 Ring gear

- 12 Carrier assy 2
- 13 Dowel pin
- 14 Collar
- 15 Plug
- 16 Plug
- 17 Cover
- 18 Pipe
- 19 Level gauge
- 20 Carrier assy 1
- 21 Planet gear 1
- 22 Pin 1

- 23 Bushing 1
- 24 Thrust washer 1
- 25 Thrust washer 3
- 26 Thrust washer 2
- 27 Carrier assy 2
- 28 Planet gear 2
- 29 Pin 2
- 30 Bushing 2
- 31 Spring pin
- 32 Snap ring
- 33 Thrust washer 4

2. FUNCTION

1) ROTARY PART

When high pressurized oil enters a cylinder through port(a), which is the inlet of balance plate(16), hydraulic pressure acting on the piston causes axial force F. The pressure force F works via the piston(10) upon the return plate(9) which acts upon the swash plate(7) via an hydrostatic bearing. Force F1 perpendicular to swash plate(7) and force F2 perpendicular to cylinder center.

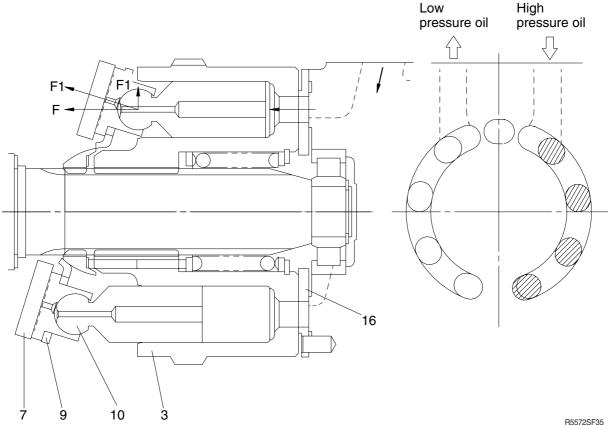
Being transferred to the cylinder block(3) through piston, force F2 causes rotational moment at surroundings of cylinder.

Since cylinder block has 9 equidistantly arrayed pistons, rotational torque is transmitted to cylinder shaft in order by several pistons connected to the inlet port of high pressurized oil. When the direction of oil flow is reversed, rotational direction of cylinder is also reversed. Output torque is given by the equation.

$$T = \frac{p \times q}{2\pi}, q = Z \cdot A \cdot PCD \cdot tan\theta , F1 = \frac{F}{COS\theta}, F_2 = F tan\theta , S = PCD \times tan\theta$$

Where p : Effective difference of pressure (kgf/cm²)

- q : Displacement (cc/rev)
- T : Output torque (kgf \cdot cm)
- Z : Piston number (9EA)
- A : Piston area (cm²)
- θ : Tilting angle of swash plate (degree)
- S: Piston stroke (cm)



2) MAKE UP VALVE

(1) Outline

The safety valve portion consists of a check valve and safety valve.

(2) Function

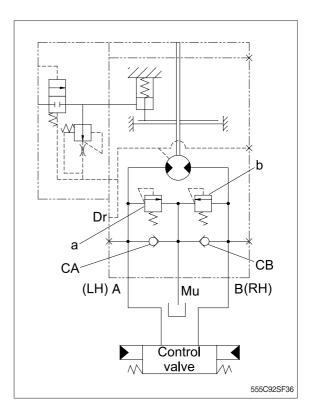
When the swing is stopped, the output circuit of the motor continues to rotate because of inertia. For this reason, the pressure at the output side of the motor becomes abnormality high, and this will damage the motor. To prevent this, the oil causing the abnormal hydraulic pressure is allowed to escape from the outlet port (high-pressure side) of the motor to port Mu, thereby preventing damage to the motor.

Compared with a counterbalance valve, there is no closed-in pressure generated at the outlet port side when slowing down the swing speed. This means that there is no vibration when slowing down, so the ease of swing control is improved.

(3) Operation

① When starting swing

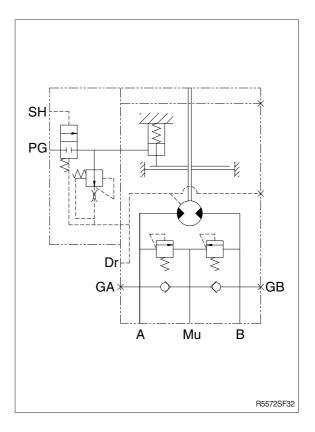
When the swing control lever is operated to left swing, the pressurized oil from the pump passes through the control valves and is supplied to port B. Because of this, the pressure at port B rises, staring torque is generated in the motor, and the motor starts to rotate. The oil from the outlet port of the motor passes from port A through the control valve and returns to the tank.



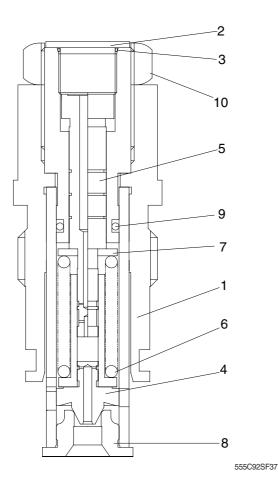
- ② When stopping swing
- When the swing control lever is returned to neutral, no pressurized oil is supplied from the pump to port B.

The return circuit to the tank is closed by the control valve. So the oil from the outlet port of the motor increases in pressure at port A. Resistance to the rotation of the motor is created, and the brake starts to act.

- The pressure at port A rises to the set pressure of make up valve a, and in this way, a high brake torque acts on the motor, and the motor stops.
- When make up valve a is being actuated, the relief oil from make up valve a and the oil from port Mu pass through check valve CB and are supplied to port B. This prevents cavitation from forming at port B.



3) RELIEF VALVE



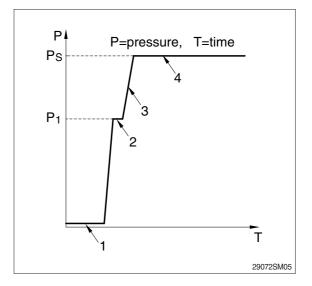
- 1 Body
- 2 Plug
- 3 O-ring
- 4 Plunger
- 5 Piston
- 6 Spring
- 7 Spring seat
- 8 Seat
- 9 O-ring
- 10 Nut

(1) Construction of relief valve

The valve casing contains two cartridge type relief valves that stop the regular and reverse rotations of the hydraulic motor. The relief valves relieve high pressure at start or at stop of swing motion and can control the relief pressure in two steps, high and low, in order to insure smooth operation.

(2) Function of relief valve

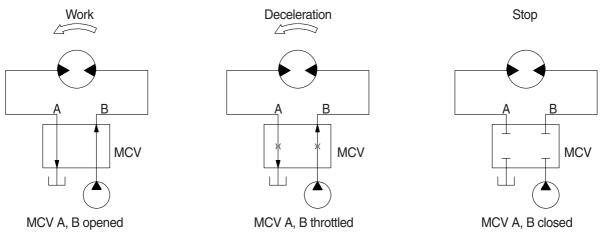
Figure illustrates how the pressure acting on the relief valve is related to its rising process. Here is given the function, referring to the figure following page.



4) BRAKE SYSTEM

(1) Control valve swing brake system

This is the brake system to stop the swing motion of the excavator during operation. In this system, the hydraulic circuit is throttled by the swing control valve, and the resistance created by this throttling works as a brake force to slow down the swing motion.



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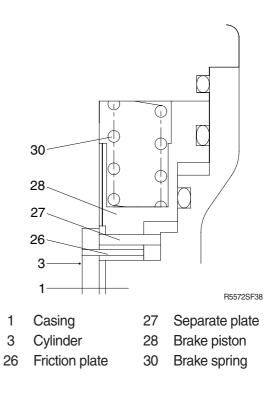
(2) Mechanical swing parking brake system

The mechanical swing parking brake system is installed to prevent the upper structure from swinging downhill because of its own weight when the excavator is parked on a slope since it completely eliminates the hydraulic drift of swing motion while the excavator is on a slop, work can be done more easily and safely.

① Brake assembly

Circumferential rotation of separate plate (27) is constrained by the groove located at casing (1). When housing is pressed down by brake spring (30) through friction plate (26), separate plate (27) and brake piston (28), friction force occurs there.

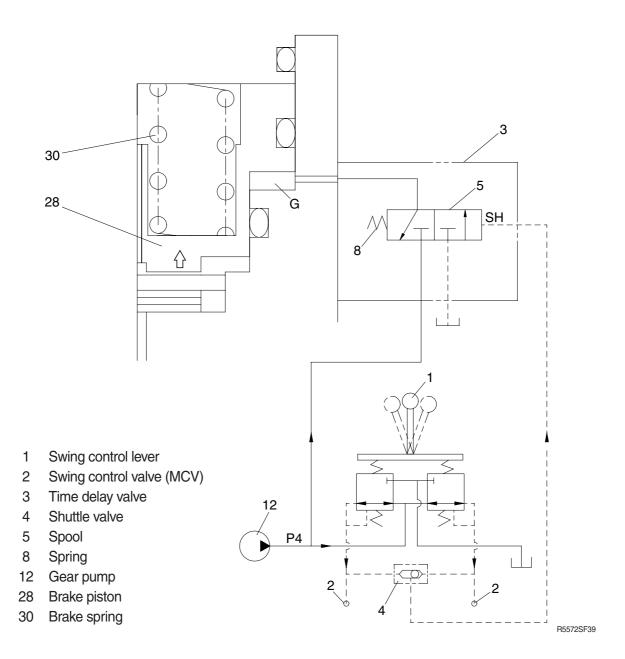
Cylinder (3) is constrained by this friction force and brake acts, while brake releases when hydraulic force exceeds spring force.



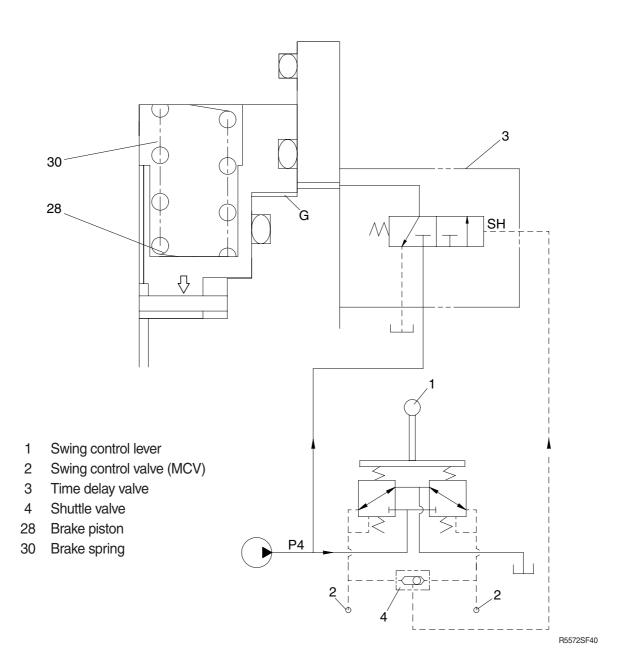
② Operating principle

a. When the swing control lever (1) is set to the swing position, the pilot oil go to the swing control valve (2) and to SH of the time delay valve (3) via the shuttle valve (4), this pressure move spool (5) to the leftward against the force of the spring (8), so pilot pump charged oil (P4) goes to the chamber G.

This pressure is applied to move the piston (28) to the upward against the force of the spring (30). Thus, it releases the brake force.



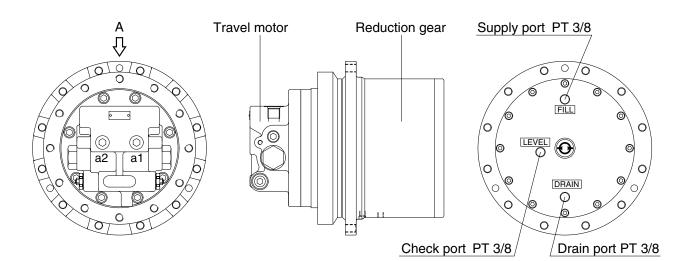
b. When the swing control lever (1) is set the neutral position, the time delay valve (3) shifts the neutral position and the pilot oil blocked chamber G.
 Then, the piston (28) is moved lower by spring (30) force and the return oil from the chamber G is drain.

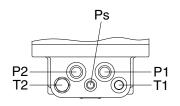


GROUP 4 TRAVEL DEVICE (TYPE 1)

1. CONSTRUCTION

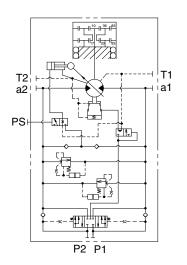
Travel device consists travel motor and gear box. Travel motor includes brake valve, parking brake and high/low speed changeover mechanism.





VIEW A

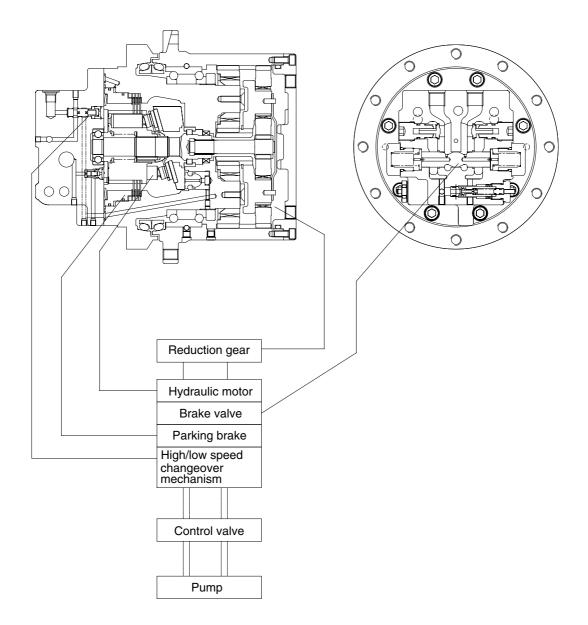
5592TM01



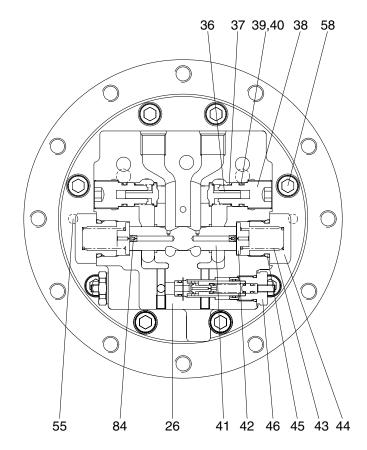
Hydraulic circuit

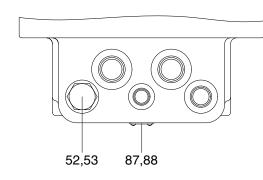
Port	Port name	Port size
P1	Main port	PF 1/2
P2	Main port	PF 1/2
a1,a2	Gauge port	PT 1/4
T1,T2	Drain port	PF 3/8
Ps	2 speed control port	PF 1/4

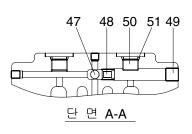
1) BASIC STRUCTURE

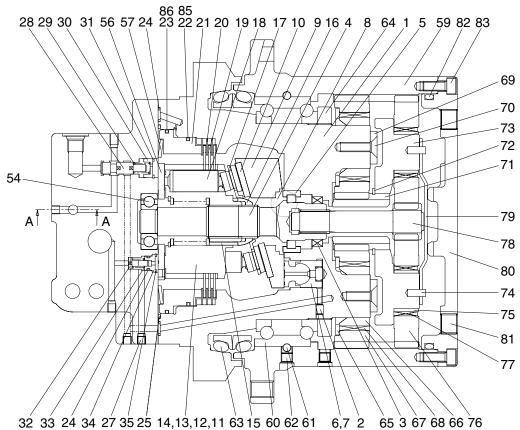


5592TM02









2 Expand 3 Oil seal 4 Shaft 5 Bearing 6 Swash piston kit 7 Spring 8 Swash steel ball

Shaft casing

1

- 9 Swash plate
- 10 Shoe plate
- 11 Cylinder block
- 12 Spring seat
- 13 Spring
- 14 Snap ring 15 Pin

30 Stopper

16	Ball guide
17	Set plate
18	Piston kit
19	Friction plate
20	Parking plate
21	Parking piston
22	O-ring
23	O-ring
24	O-ring
25	O-ring
26	Rear cover
27	Plug
28	Spool
29	Spring

32 Check 33 Spring 34 Seat 35 Snap ring 36 Check 37 Spring 38 Plug 39 O-ring 40 Back up ring 41 Main spool kit 42 Spring seat 43 Spring 44 Plug 45 O-ring

31 Snap ring

46 Relief valve assy 47 Steel ball 48 Check seat 49 Plug 50 Plug 51 O-ring 52 Plug 53 O-ring 54 Ball bearing 55 Pin 56 Valve plate 57 Spring plate 58 Wrench bolt 59 Ring gear 60 Angular bearing

61	Steel ball
62	Plug
63	Floating seal
64	Nut
65	Washer
66	Collar
67	Planetary gear
68	Needle bearing
69	Plate
70	Bolt
71	Sun gear
72	Snap ring
73	Carrier
74	Spring pin

75 Collar

555K2TM03

- 76 Planetary gear
- 77 Needle bearing
- 78 Drive gear
- 79 Thrust plate
- 80 Ring gear cover
- 81 Plug
- 82 O-ring
- 83 Wrench bolt
- 84 Orifice
- 85 Back up ring
- 86 Back up ring
- 87 Name plate
- 88 Rivet

2. PRINCIPLE OF DRIVING

1) GENERATING THE TURNING FORCE

The high hydraulic supplied from a hydraulic pump flows into a cylinder (11) through valve casing of motor (26), and valve plate (56).

The high hydraulic is built as flowing on one side of Y-Y line connected by the upper and lower sides of piston (18).

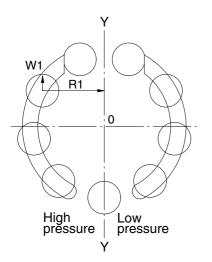
The high hydraulic can generate the force, $F1 = P \times A$ (P : Supplied pressure, A : water pressure area), like following pictures, working on a piston.

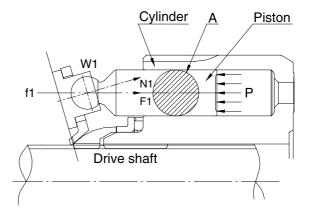
This force, F1, is divided as N1 thrust partial pressure and W1 radial partial pressure, in case of the swash plate (9) of a tilt angle, α .

W1 generates torque, T = W1+R1, for Y-Y line connected by the upper and lower sides of piston as following pictures.

The sum of torque (Σ W1×R1), generated from each piston (4~5pieces) on the side of a high hydraulic, generates the turning force.

This torque transfers the turning force to a cylinder (11) through a piston; because a cylinder is combined with a turning axis and spline, a turning axis rotates and a turning force is sent.





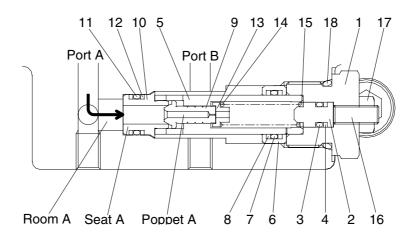
5592TM03

2) WORKING OF RELIEF VALVE

Relief valve carries on two functions of followings.

- (1) It standardizes a pressure in case of driving a hydraulic motor ; bypasses and extra oil in a motor inlet related to acceleration of an inertia to an outlet.
- (2) In case of an inertia stopped, it forces an equipment stopped, according to generating the pressure of a brake on the projected side.

Room A is always connected with port A of a motor. If the pressure of port is increased, press poppet B. And if it is higher than the setting pressure of a spring, the oil of an hydraulic flows from room A to port B, because poppet A is detached from the contact surface of seat A.



5592TM04

3) WORKING OF BRAKE

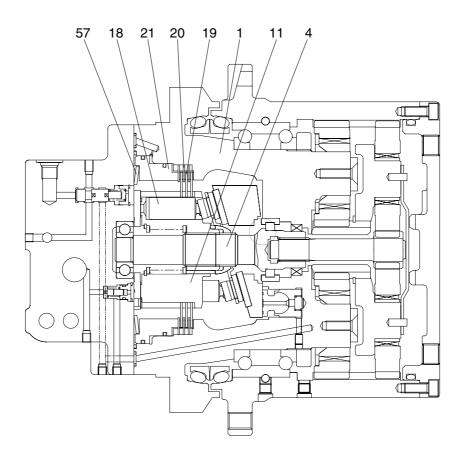
Brake operates the pressure supplied through SPOOL (simultaneous peripheral operation online) installed in valve casing (26) to the part of parking piston (21) and releases a brake.

When the pressure does not work, the brake always runs.

The force of a brake is generated by the frictional force among a plate (20), brake piston (21) and a cylinder block (11) that is connected through spline which are fixed by shaft casing (1) with friction plate (19).

When a pressure does not work on the part of piston, brake spring presses brake piston; oil in a brake room flows into the drain of a motor through an orifice; in that time, brake piston compresses a frictional plate (19) and a detached plate in the middle of shaft casing and brake piston according to the force plate springs (57); finally, it makes a frictional force.

This frictional force helps the brake fixing a turning axis (3) connected by a cylinder and spline operated.

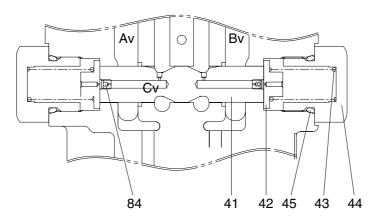


555K2TM06

4) COUNTERBALANCE VALVE

Av port is connected into a hydraulic pump and Bv port is into a tank. Hydraulic pump supplying oil is come into $Av \rightarrow Cv$ room. In accordance with spring force (43) that is working on the spool's side it moves to the spool (41) on the right side which is medium position and that time motor is turning.

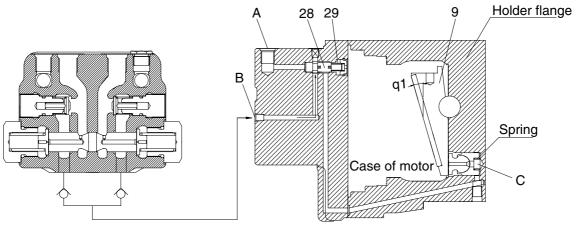
When the spool (41) is come back to the medium position that time hydraulic motor is stopped. In accordance with spool's returning speed and shape control the working oil that is returning from hydraulic motor smoothly stopping the motor.



555K2TM07

4) HIGH/LOW SPEED CHANGEOVER MECHANISM

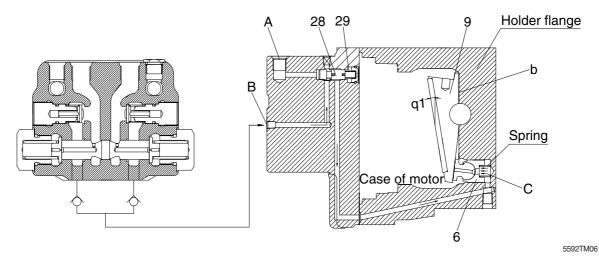
(1) At low speed-at pilot pressure of less than 10 kgf/cm² (0.98 Mpa)



5592TM05

When no pilot pressure is supplied from port (A) at a pressure of 10 kgf/cm² (0.98 Mpa) or less, spool (28) is pressed toward the left by the force of spring (29), the pressurized oil supply port B is shut off, and oil in chamber (C) is released into the motor case via spool (28).

Consequently, swash plate (9) is tilted at a maximum angle (θ 1°) and the piston displacement of hydraulic motor becomes maximum, thus leading to low-speed rotation.



(2) At high speed-at pilot pressure of 10 kgf/cm² (0.98 Mpa) or more

When a pilot pressure is supplied from port (A) at a pressure of 10 kgf/cm² (0.98 Mpa) or more, the pressure overcomes the force of spring (29) and spool (28) is pressed toward the right. The pressurized oil at supply port (B) is then introduced into chamber (C) via spool (28). Piston (6) pushes up swash plate (9) until it touches side (b) of the holder flange.

At this time, swash plate (9) is tilted at a minimum angle (θ 2°) and the piston displacement of hydraulic motor becomes maximum, thus leading to high-speed rotation.

2. REDUCTION GEAR

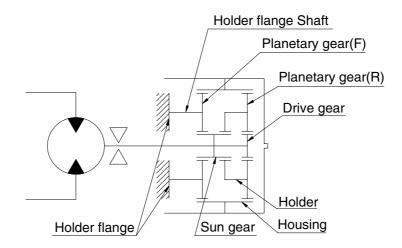
1) FUNCTION

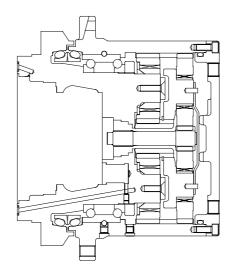
The reduction gear unit consists of a combination of simple planetaly gear mechanism. This mechanism reduce the high speed rotation from the hydraulic motor and convert it into low speed, high torque to rotate the hub (or case), which in turn rotates the sprocket.

2) OPERATING PRINCIPLE

Shaft \rightarrow Drive gear \rightarrow Planetary Gear R \rightarrow Housing

 \rightarrow Holder \rightarrow Sun gear \rightarrow Planetary Gear F \rightarrow Rotation of Housing





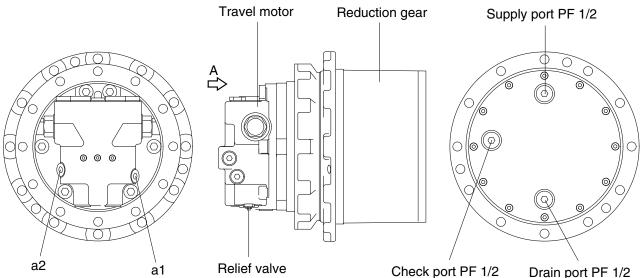
5592TM07

 $\begin{aligned} \text{Reduction ratio} &= (\text{Housing Teeth/Drive Gear Teeth} + 1) \\ &\times (\text{Housing Teeth/Sun Gear Teeth} + 1) - 1. \end{aligned}$

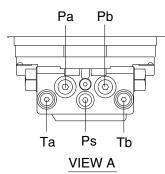
TRAVEL DEVICE (TYPE 2, MACHINE SERIAL NO.: #3959-)

1. CONSTRUCTION

Travel device consists travel motor and gear box. Travel motor includes brake valve, parking brake and high/low speed changeover mechanism.

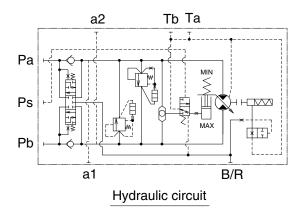


Drain port PF 1/2

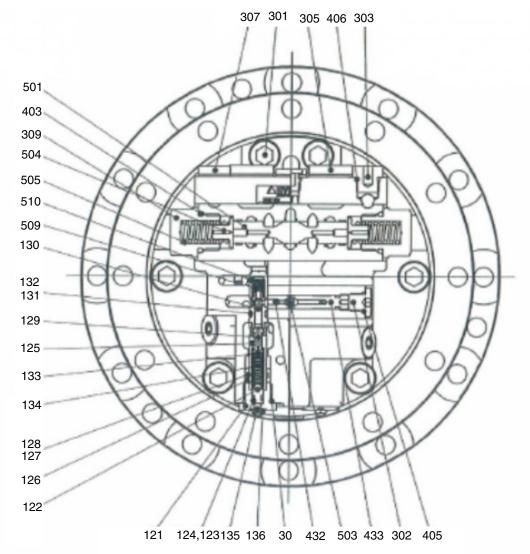


HX60A2TM50E

-		
Port	Port name	Port size
Pa	Main port	PF 1/2
Pb	Main port	PF 1/2
a1,a2	Gauge port	PT 1/4
Ta,Tb	Drain port	PF 3/8
Ps	2 speed control port	PF 1/4



2) STRUCTURE

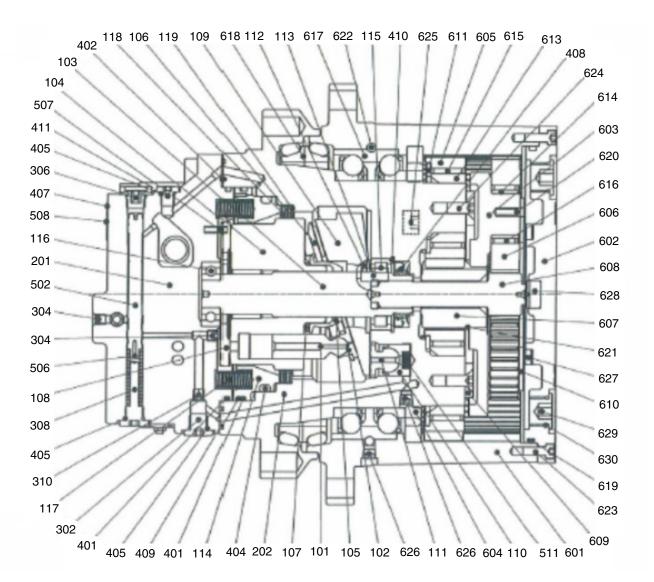


30 Relief valve assy 101 Piston 102 Shoe 103 Drive shaft 104 Cylinder block 105 Spherical bushing 106 Set plate 107 Cylinder spring 108 Valve plate 109 Swash plate 110 Swash piston 111 Swash shoe 112 Pivot 113 Pivot pin 114 Brake piston 115 Roller bearing 116 Ball bearing

117 Brake spring

 118 Friction plate 119 Separator plate 121 Plug 122 Guide 123 O-ring 124 Back up ring 125 Sleeve
121 Plug122 Guide123 O-ring124 Back up ring125 Sleeve
122 Guide123 O-ring124 Back up ring125 Sleeve
123 O-ring124 Back up ring125 Sleeve
124 Back up ring 125 Sleeve
125 Sleeve
126 Piston
127 O-ring
128 Back up ring
129 Poppet
130 Poppet seat
131 O-ring
132 Back up ring
133 Spring seat
134 Spring
135 Adjust screw
136 Hex nut

137	O-ring
201	Valve casing
202	Casing
301	Socket bolt
302	Plug
303	Drain plug
304	NPTF plug
305	Dust plug
306	Dust plug
307	Dust plug
308	2 speed plug
309	Set plug
309 310	Set plug Restrictor
310	Restrictor
310 311	Restrictor Plug
310 311 401	Restrictor Plug O-ring



405	O-ring	510	Сар
406	O-ring	511	Swash piston spring
407	Name plate	601	Housing
408	Oil seal	602	Cover
409	Back up ring	603	Holder
410	Snap ring	604	Ring nut
411	O-ring	605	Planetary gear F
432	Seat	606	Planetary gear R
433	Seat casing	607	Sun gear
501	Main spool	608	Ring nut
502	2 speed spool	609	Thrust plate F
503	Steel ball	610	Thrust plate R
504	Plunger	611	Thrust washer
505	Main spool spring	613	Collar
506	2 speed spool spring	614	Inner race
507	Spring pin	615	Needle bearing
508	Pin	616	Needle bearing
509	Spring cap	617	Angular bearing

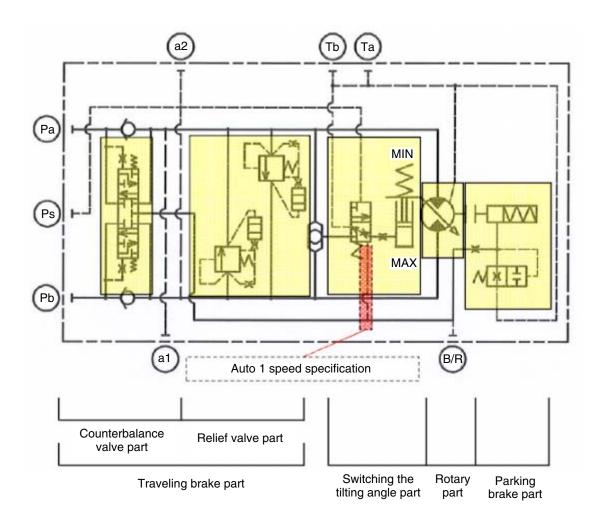
HX60A2TM51

- 618 Floating seal kit
- 619 O-ring
- 620 Spring pin
- 621 Snap ring
- 622 Steel ball
- 623 Socket bolt
- 624 Bolt
- 625 Plug
- 626 Plug
- 627 Side plate A
- 628 Side plate B
- 629 Plug
- 630 O-ring

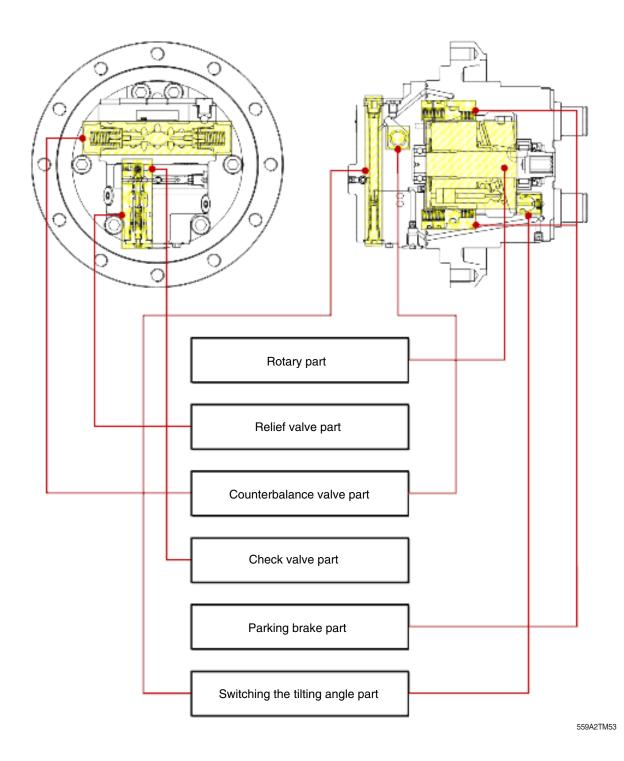
2) MAJOR COMPONENT

This product is only composed of hydraulic motor. Reduction parts are not composed. This hydraulic motor is variable swash plate axial piston motor. It is composed of 4 parts.

- Rotary part which makes rotatory power
- Traveling brake valve part
- Parking brake part
- Switching the tilting angle part (auto 1/2 speed control part)



3) BASIC STRUCTURE



2. WORKING PRINCIPLE

1) HYDRAULIC MOTOR SECTION

When high pressure oil passes from pump through the inlet port of the valve plate(108) and flows into the cylinder (104) as shown in figure, the oil pressure acts upon the piston (101) to generate the axial force "F". The force "F" acts on the swash (109) plane in the axial direction.

 $F = P \times A$ (P : Pressure, A : Area)

The swash plate (109) is fixed with an inclination angle of α to the axis of the drive shaft (103). Therefore, this force is divided into two vector forces through the shoe (102) : namely, the force F1 vertical to the swash plate (109) and the force F2 perpendicular to the drive shaft (103).

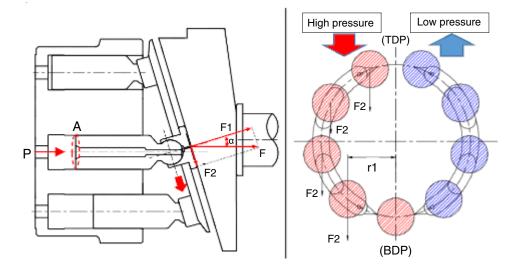
Because of the force "F2", piston (101) slides along with shoe (102) in the direction of the arrow in Figure. This force "F2" is transmitted to the cylinder block (104) via the piston (101) and generates a couple of forces which turn the output drive shaft (103).

In the cylinder block (104) nine pistons are equispaced and the pistons connected to the high pressure oil inlet ports give their rotating torque to the output shaft sequentially.

When the oil inflow/outflow direction are reversed, the rotating direction of the output shaft is reversed.

The theoretical output torque "T [N/m]" is given by the flowing.

 $T = \frac{P \times q}{2\pi}$ P : Effective pressure difference (Mpa), q : Displacement per revolution (cm³)



2) TRAVELING BRAKE VALVE

Traveling brake valve is composed of relief valve, counterbalance valve and check port A is connected with hydraulic pump and port B is connected with tank.

(1) In case of traveling

When the compressed oil, which is supplied along the inlet port, exceeds certain pressure, it pushes cap (509). And, it is supplied to one side of the casing (202).

It is trying to rotate the hydraulic motor.

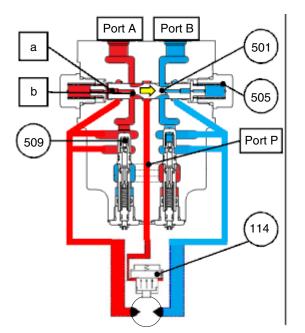
At the same time, the compressed oil enters the chamber {a} along small hole {b} of main spool (501) and acts on the face of main spool (501). After increasing pressure of oil, when this pressure exceeds the spring elasticity force of main spool spring (505), main spool (501), which is held in neutral by the spring elasticity force, moves to the right.

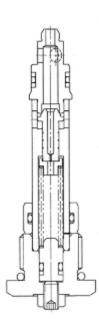
The inlet side and outlet side that was blocked by main spool (501) during stop connect with each other. So, return oil returns to the oil tank, so the hydraulic motor rotates.

Furthermore as main spool (501) moves, the path of parking brake (port P) is connected.

When compressed pressure, which enter to (port P), becomes brake release pressure, it operates brake piston (114) and parking brake is released.

If the direction of oil inlet is reversed, main spool (501) and check valve motion is reversed. Output rotation direction is also reversed.





(2) In case of stop

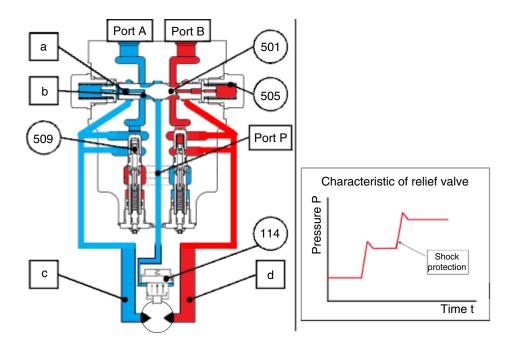
If the pressure supplied along the port to the inlet breaks while traveling, the pressure applied to the section of the main spool (501) is removed. Therefore, the main spool (501), which was pushed to the right, returns to neutral due to the spring elasticity force of the main spool spring (505).

The rotary part continues to rotate under inertia even if pressure is lost from the inlet side. As the main spool (501) returns to neutral, the connected inlet and outlet sides of the flow path are blocked. Since there is no escape location for the returned oil, the pressure of the exit side (D) is raised.

The returned oil with increased pressure enters the relief valve (30). if it exceeds the set pressure of the relief valve (30), operates the relief valve (30). The flow path from the outlet side {D} to the inlet side {C} is connected. And it controls the pressure on the outlet side.

At the same time it prevents cavitation on the inlet side.

It also relieves the shock during stop while controlling pressure on the outlet side with relief valve (30) in two stages, and apply soft braking to the hydraulic motor by applying an orifice and notch on the main spool (501).



(2) In case of stop

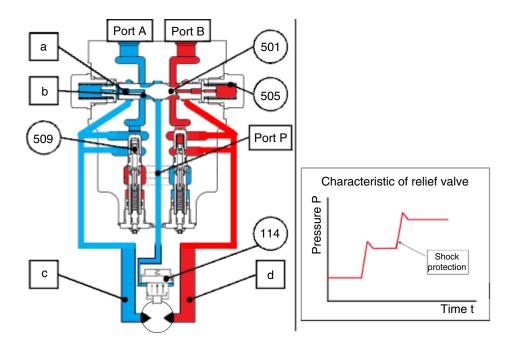
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The returned oil with increased pressure enters the relief valve (30). if it exceeds the set pressure of the relief valve (30), operates the relief valve (30). The flow path from the outlet side {D} to the inlet side {C} is connected. And it controls the pressure on the outlet side.

At the same time it prevents cavitation on the inlet side.

It also relieves the shock during stop while controlling pressure on the outlet side with relief valve (30) in two stages, and apply soft braking to the hydraulic motor by applying an orifice and notch on the main spool (501).

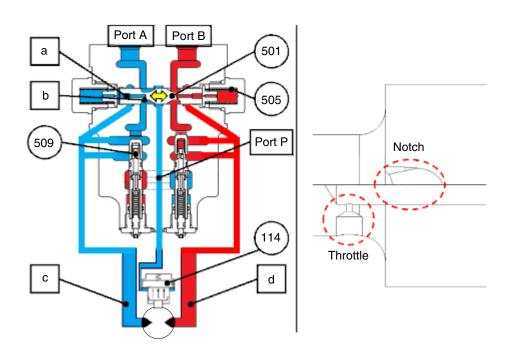


(3) In case of overrun

Overrun is when the excavator's speed is increased by the it's gravity (inertia), such as when an excavator is going downhill, causing the hydraulic motor to rotate above the supply flow of the hydraulic pump.

In the case of overrun, the compressed oil on the inlet side is entered into the rotary and the pressure on the inlet side is reduced. Therefore, due to the spring elasticity force of the main spool spring (505), main spool (501) returns to neutral, as it stops.

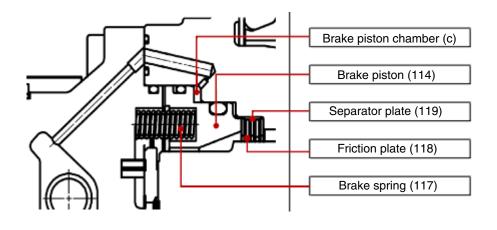
At the same time, back pressure is generated due to the throttle (notch of main spool) between the outlet side (D) and the outlet port (port B) passage. The back pressure controls the return speed of the main spool (501) and hydraulic motor, which is about to be rotated by inertia forces, is decelerated. The operation of main spool (501) is controlled by the notch of main spool (501) and throttle. So motor smoothly moves according to the supply flow rate.



3) PARKING BRAKE

The parking brake is wet-type multiple disk brakes. It is a negative brake system which is released when the brake release pressure enters the brake piston chamber.

The internal structure of parking brake is shown in figure. Friction plate (118) and separator plate (119) are alternately stacked, and acting on springs to produce brake torque with friction forces. It prevents not only the braking of excavators but also overrun or slip during traveling and stopping on the slip.



559A2TM58

(1) In case traveling

The cylinder block (104) is connected to the drive shaft (103) with spline. In addition, the separator plate (119) is restrained from circumferentially-rotating by an arc groove cut on the casing (202).

The friction plate (118) which is connected to the arc groove cut on cylinder block (104), can be rotated along the cylinder block (104).

When pressurized oil is supplied from the inlet side during traveling operation, the blocked flow path is opened. so pressurized oil is supplied to the brake piston chamber (c) that is comprised inside brake piston (114) and casing (202).

If the hydraulic force F4 of the brake piston chamber (c) is greater than the spring elasticity force F3 of the brake spring (117), then brake piston (114) move to valve casing. (above brake release pressure)

F3 = k x n , k : Spring constant, x : Spring stroke, n : Number of spring brake

 $F4 = P \times (A1 - A2), P$: Main pressure of input, (A1 - A2): Area difference of brake piston

The force that friction plate (118) and separator plate (119) pressurize the casing (202) disappears and the brake releases.

So, the hydraulic motor can rotate.

(2) In case of stop

If the pressurized oil supplied by the inlet is cut off during stop, the pressurized oil supplied to the brake piston chamber (c) will also be blocked. (below brake release pressure)

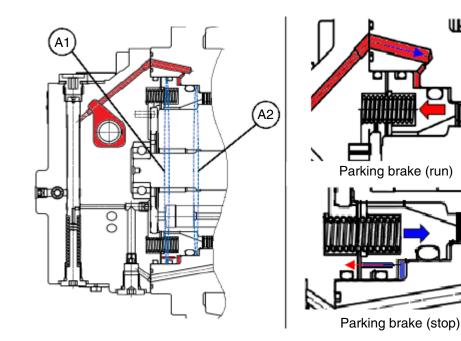
If the spring elasticity force F3 of the brake spring (117) is greater than the hydraulic force F4 of the brake piston chamber (c), then brake piston (114) move to casing by spring elasticity force. The hydraulic oil of the brake piston (114) is drained through the throttle. Therefore brake piston (114) smoothly operates.

F3 < F4

 $F3 = k \times n$, k : Spring constant, x : Spring stroke, n : Number of spring brake

 $F4 = P \times (A1 - A2)$, P : Main pressure of input, (A1 - A2) : Area difference of brake piston

When the brake piston (114) pushes casing (202) by the brake spring (117), the frictional force appears between friction plate (118), casing (202), separator plate (119) and brake piston (114). parking brake appears by friction force and spring elasticity of the brake spring (117), the drive shaft (103) is constrained.



559A2TM59

¶⊢

4) 1/2 SPEED SWITCHING OPERATION (AUTOMATIC 1/2 SPEED CONTROL PART)

(1) Low speed traveling

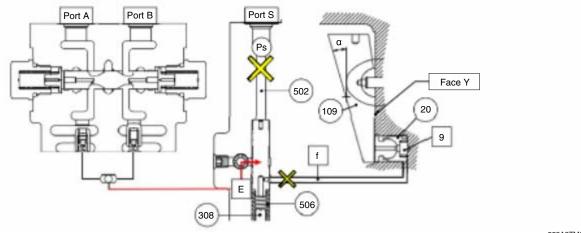
If pilot pressure is not supplied on pilot port (port S), 2 speed spool (502) is pushed in the direction of the port S by spring elasticity of 2 speed spool spring (506).

As a result, the compressed oil from the high pressure selection check valve (E) is not connected to the swash piston chamber (g).

The compressed oil of swash piston chamber{g} is drained through the flow path of 2 speed spool chamber (f).

So, the compressed oil from the high pressure selection check valve (E) is not connected to the swash piston chamber {g}. As a result, the swash plate (109) will be the maximum angle α and the stroke of the piston (101) will be long. So, a large amount of oil will be required for rotating the motor once.

Therefore the displacement of the hydraulic motor is maximized and rotated at low speed.



(2) High speed traveling

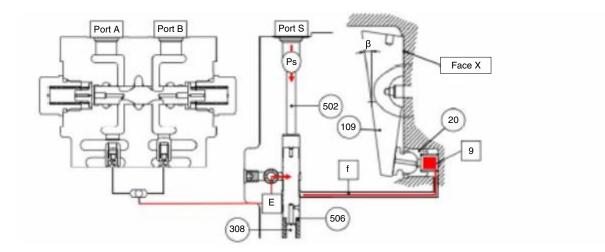
If the pilot pressure (20~50 kgf/cm²) is supplied to the port (port S), the pilot pressure overcomes the oil pressure in the main port and the spring elasticity force of the 2 speed spool spring (506). and it pushes the 2 speed spool (502) to the 2 speed plug (308) direction.

This is why the pressure from the high pressure selection check valve (E) is connected to the flow path (f).

The pressurized oil flows into the $\{g\}$ chamber along the flow path $\{f\}$ and pushes swash piston (20) to contact the face 'X' of swash plate (109) with the wall of the casing (202).

As a result, the swash plate (109) is the minimum angle β . Because stroke of piston (101) is shortened, a small amount of oil is used for one revolution.

Therefore, the displacement of the hydraulic motor is minimized and is rotated at high speed.



(3) Automatic 1/2 speed control part

If the load is increased during the 2-speed driving, the hydraulic pressure on the main port is increased. The pressure ($\triangle P$) of main port and spring elasticity force of 2 speed spool spring (506) will overcome the pressure of pilot, 2 speed spool (502) is pushed in port S direction.

 $F5 < [{F6 \times (A4 - A3)} + (Fspring)]$

2

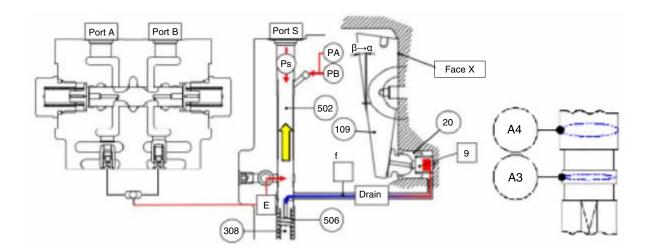
 $F5 = PS \times A3$, PS : Pilot pressure, A3 : 2 speed spool area

 $F6 = (PA \text{ or } PB) \times (A4 - A3), (PA \text{ or } PB) :$ Main pressure difference between inlet side and outlet side Fspring = K x X ; K : Spring constant of 2 speed spool spring, X : Spring stroke

Therefore, flow path from the high pressure selection check valve (E) to (f) is blocked.

And the pressure of (g) is slowly drained to 2 speed spool chamber (f) through throttle and a notch of 2 speed spool.

The angle of swash plate (109) transfers from β to α , and the motor automatically switches from speed to 1 speed to rotate at low speed.



5) REDUCTION GEAR



559A2TM63

- (1) Refer to the section drawing for the basic construction.
- (2) The reduction gear consists of two stage planetary gears.
- (3) The reduction ratio is determined by the number of teeth of the gear, and the reduction ratio is 42.439.

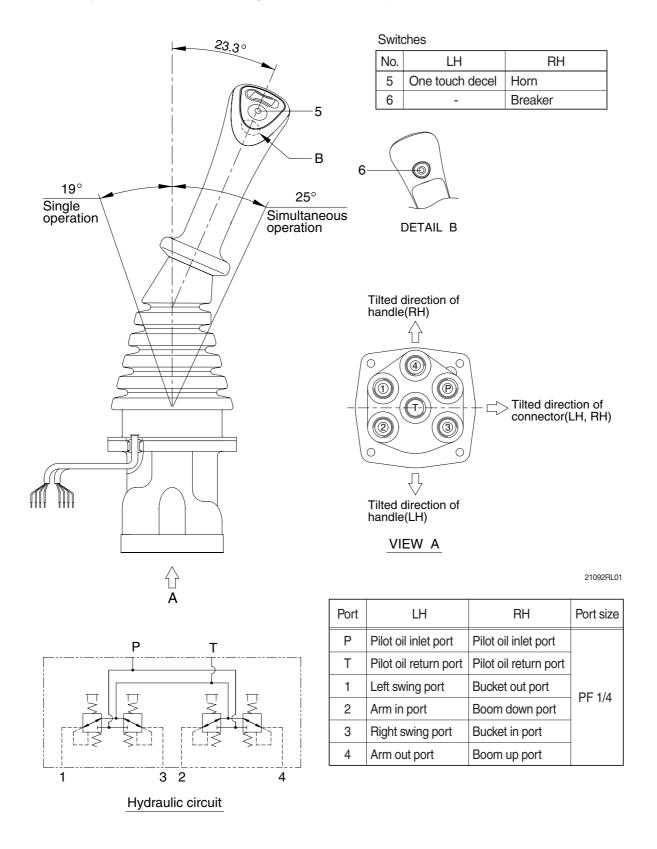
In other words, the number of revolutions of the hydraulic motor is transmitted to the output shaft at 1 / reduction ratio.

(4) The direction of rotation of the input and output shafts is opposite.

GROUP 5 RCV LEVER

1. STRUCTURE

The casing has the oil inlet port P (primary pressure) and the oil outlet port T (tank). In addition the secondary pressure is taken out through ports 1, 2, 3 and 4 provided at the bottom face.

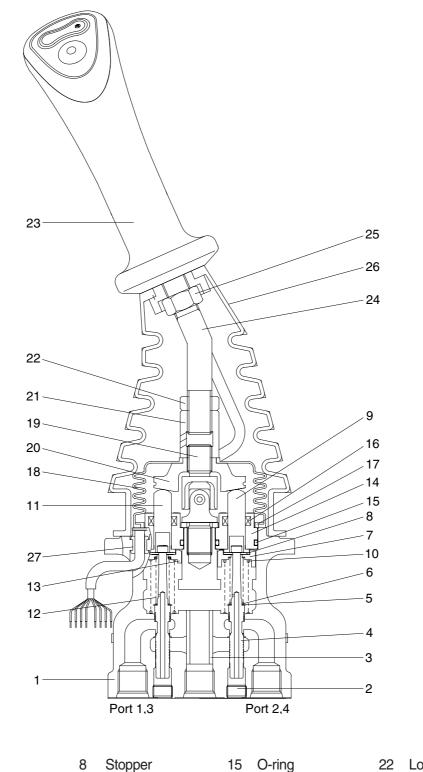


CROSS SECTION

The construction of the pilot valve is shown in the attached cross section drawing. The casing has vertical holes in which reducing valves are assembled.

The pressure reducing section is composed of the spool (4), spring (6) for setting secondary pressure, return spring (10), stopper (8), spring seat (7, 13) and shim (5). The spring for setting the secondary pressure has been generally so preset that the secondary pressure is 5 to 20.5 kgf/cm² (depending on the type). The spool is pushed against the push rod (9, 11) by the return spring. When the push rod is pushed down by tilting the handle, the spring seat comes down simultaneously

and changes setting of the secondary pressure spring.



21092RL02

- 1 Case
- 2 Plug
- 3 Bushing
- 4 Spool
- 5 Shim
- 6 Spring
- 7 Spring seat
- 9 Push rod 10 Spring
- 11 Push rod
- 12 Spring
- 13 Spring seat
- 14 Plug
- 15 O-ring
 16 Rod seal
 17 Plate
 18 Boot
 19 Joint assembly
 20 Swash plate
- 21 Adjusting nut

- . .
- 22 Lock nut
- 23 Handle assembly
- 24 Handle bar
- 25 Nut
- 26 Boot
- 27 Bushing

2. FUNCTIONS

1) FUNDAMENTAL FUNCTIONS

The pilot value is a value that controls the spool stroke, direction, etc of a main control value. This function is carried out by providing the spring at one end of the main control value spool and applying the output pressure (secondary pressure) of the pilot value to the other end.

For this function to be carried out satisfactorily, the pilot valve is composed of the following elements.

- (1) Inlet port (P) where oil is supplied from hydraulic pump.
- (2) Output ports (1, 2, 3 & 4) to apply pressure supplied from inlet port to ends of control valve spools.
- (3) Tank port (T) necessary to control the above output pressure.
- (4) Spool to connect output port to inlet port or tank port.
- (5) Mechanical means to control output pressure, including springs that work on the above spools.

2) FUNCTIONS OF MAJOR SECTIONS

The functions of the spool (4) are to receive the supply oil pressure from the hydraulic pump at its port P, and to change over oil paths to determine whether the pressure oil of port P is led to output ports 1, 2, 3 & 4 or the output port pressure oil to tank port T.

The spring (6) works on this spool to determine the output pressure.

The change the deflection of this spring, the push rod (9,11) is inserted and can slide in the plug (14).

For the purpose of changing the displacement of the push rod through the swash plate (20) and adjusting nut (21) are provided the handle (23) that can be tilted in any direction around the fulcrum of the universal joint (19) center.

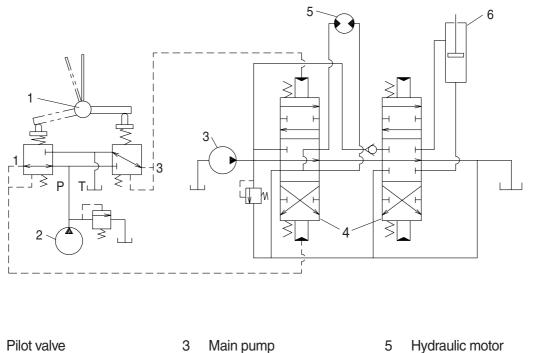
The spring (10) works on the case (1) and spring seat (7, 13) and tries to return the push rod (9,11) to the zero-displacement position irrespective of the output pressure, securing its resetting to the center position.

This also has the effect of a reaction spring to give appropriate control feeling to the operator.

3) OPERATION

The operation of the pilot valve will be described on the basis of the hydraulic circuit diagram shown below and the attached operation explanation drawing.

The diagram shown below is the typical application example of the pilot valve.



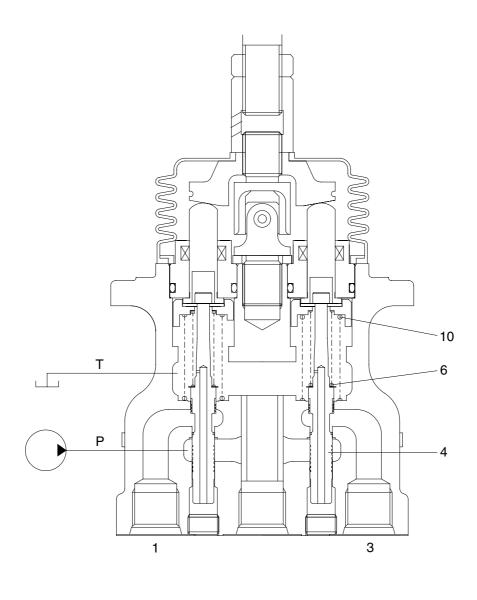
2 Pilot pump

1

- 4 Main control valve
- Hydraulic motor

2-70

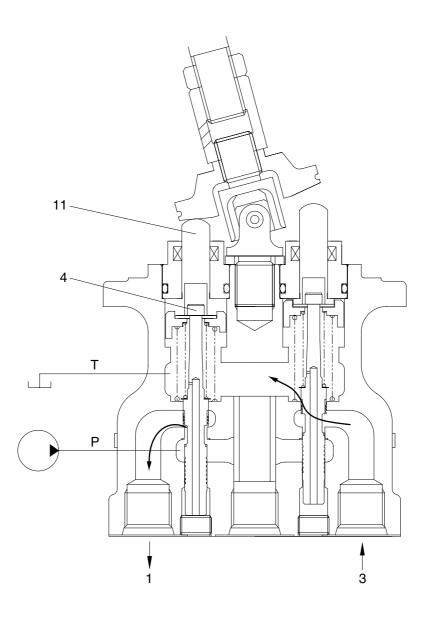
6 Hydraulic cylinder (1) Case where handle is in neutral position



21092RL03

The force of the spring (6) that determines the output pressure of the pilot valve is not applied to the spool (4). Therefore, the spool is pushed up by the spring (10) to the position of port (1, 3) in the operation explanation drawing. Then, since the output port is connected to tank port T only, the output port pressure becomes equal to tank pressure.

(2) Case where handle is tilted



21092RL04

When the push rod (11) is stroked, the spool (4) moves downwards.

Then port P is connected with port (1) and the oil supplied from the pilot pump flows through port (1) to generate the pressure.

When the pressure at port (1) increases to the value corresponding to the spring force set by tilting the handle, the hydraulic pressure force balances with the spring force. If the pressure at port (1) increases higher than the set pressure, port P is disconnected from port (1) and port T is connected with port (1). If it decreases lower than the set pressure, port P is connected with port (1) and port T is disconnected from port 1.

In this manner the secondary pressure is kept at the constant value.

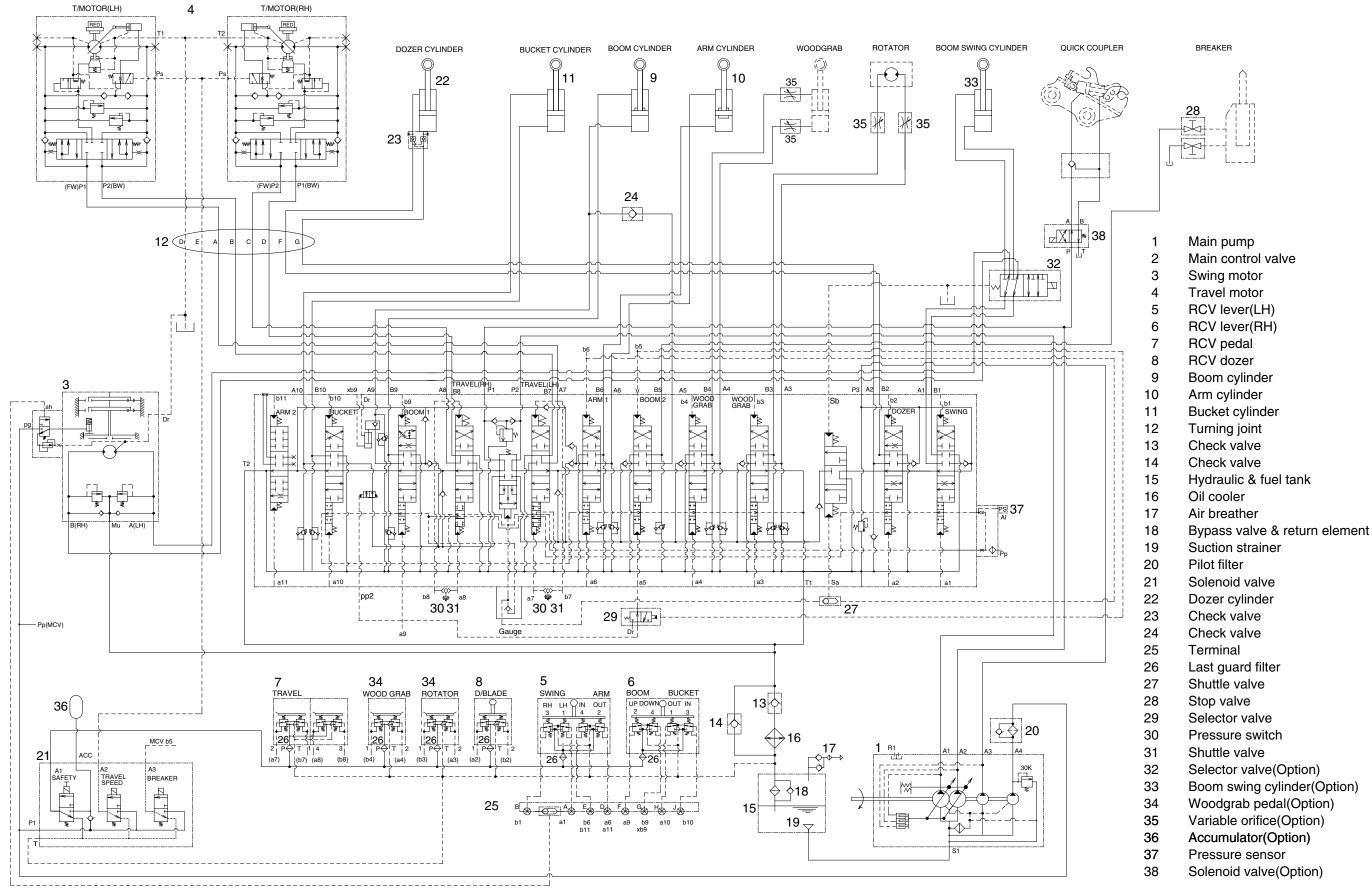
Besides, in some type, when the handle is tilted more than a certain angle, the upper end of the spool contacts with the inside bottom of the push rod and the output pressure is left to be connected with port P.

SECTION 3 HYDRAULIC SYSTEM

Group	1 Hydraulic Circuit	3-1
Group	2 Main Circuit	3-2
Group	3 Pilot Circuit	3-5
Group	4 Single Operation	3-10
Group	5 Combined Operation	3-25

GROUP 1 HYDRAULIC CIRCUIT

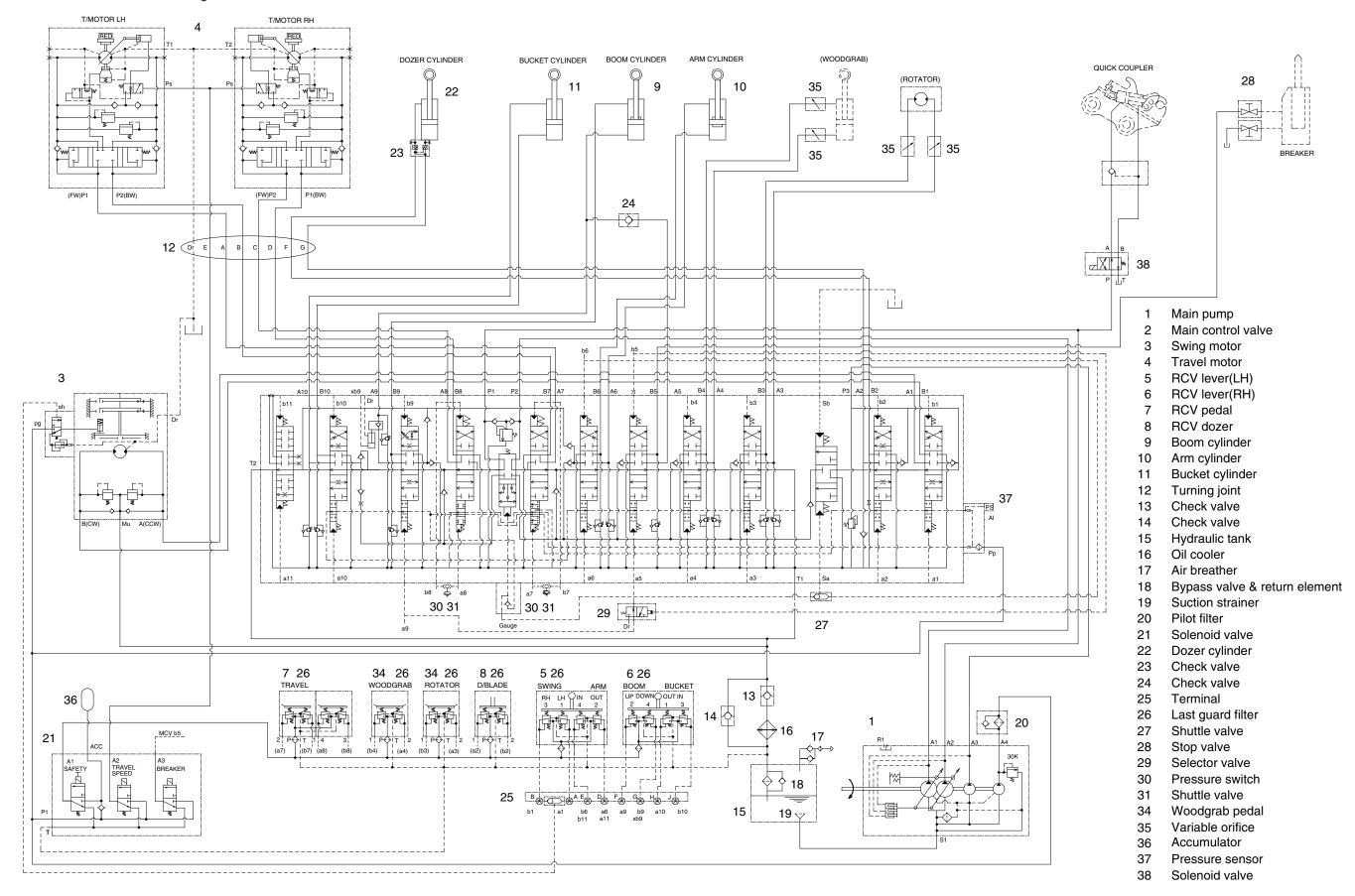
· Machine serial No. : -#1934



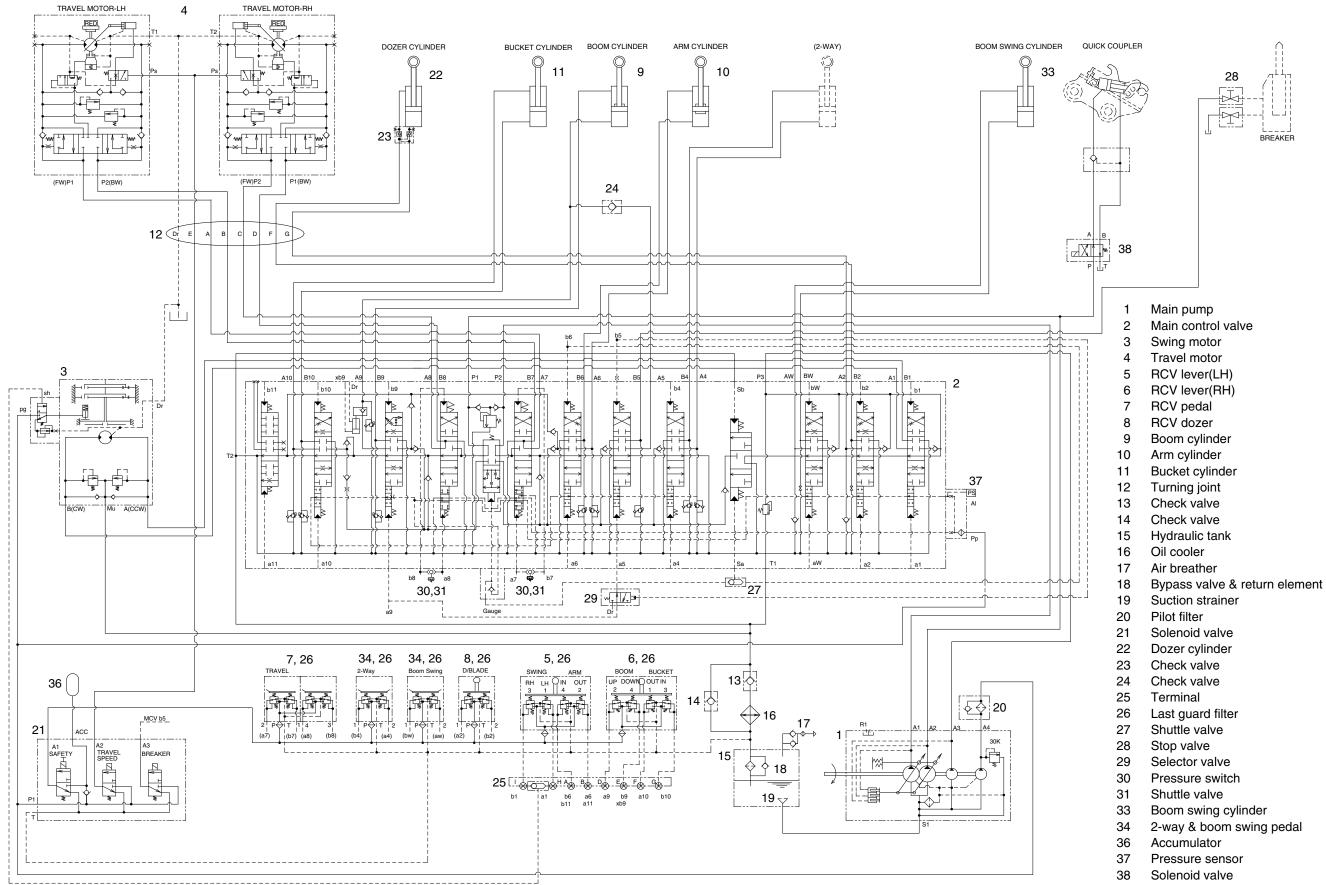
SECTION 3 HYDRAULIC SYSTEM

5593HC01

· Machine serial No. : #1935-, wood grab



· Machine serial No. : #1935-, boom swing, 2-way



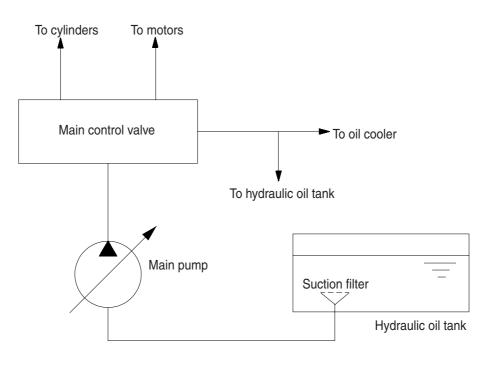
5593HC01-2

GROUP 2 MAIN CIRCUIT

The main hydraulic circuit consists of suction circuit, delivery circuit, return circuit and drain circuit. The hydraulic system consists of one main pump, one control valve, one swing motor, four cylinders and two travel motors.

The swash plate type variable displacement axial piston pump is used as the main pump and is driven by the engine at ratio 1.0 of engine speed.

1. SUCTION AND DELIVERY CIRCUIT



3-02 (140-7 TIER)

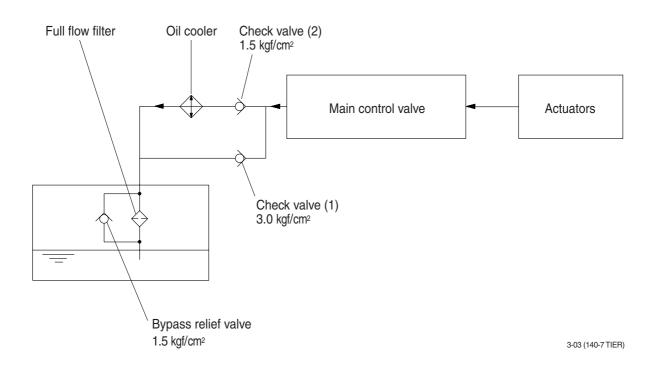
The pumps receive oil from the hydraulic tank through a suction filter. The discharged oil from the pump flows into the control valve and goes out the tank ports.

The oil discharged from the main pump flows to the actuators through the control valve.

The control valve controls the hydraulic functions.

The return oil from the actuators flows to the hydraulic tank through the control valve and the oil cooler.

2. RETURN CIRCUIT



All oil returned from each actuator returns to the hydraulic tank through the control valve.

The bypass check valves are provided in the return circuit.

The setting pressure of bypass check valves are 1.5 kgf/cm² (21 psi) and 3.0 kgf/cm² (43 psi). Usually, oil returns to the hydraulic tank from the left side of control valve through oil cooler.

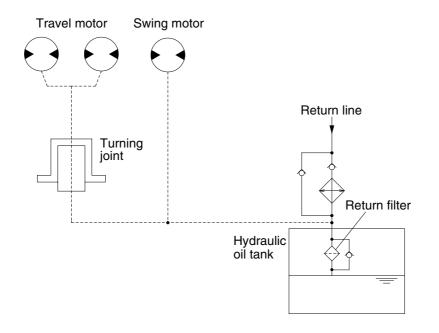
When oil temperature is low, viscosity becomes higher and flow resistance increases when passing through the oil cooler. When the oil pressure exceeds 3.0 kgf/cm² (43 psi), the oil returns directly to the hydraulic tank, resulting in the oil temperature being raised quickly at an appropriate level.

When the oil cooler is clogged, the oil returns directly to the hydraulic tank through bypass check valve (1). The full-flow filter and bypass relief valve are provided in the hydraulic tank.

The oil returned from right and left side of control valve is combined and filtered by the full-flow filter. A bypass relief valve is provided in the full-flow filter.

When the filter element is clogged, the bypass relief valve opens at 1.5 kgf/cm² (21 psi) differential pressure.

3. DRAIN CIRCUIT



R5573Cl02

Besides internal leaks from the motors and main pump, the oil for lubrication circulates.

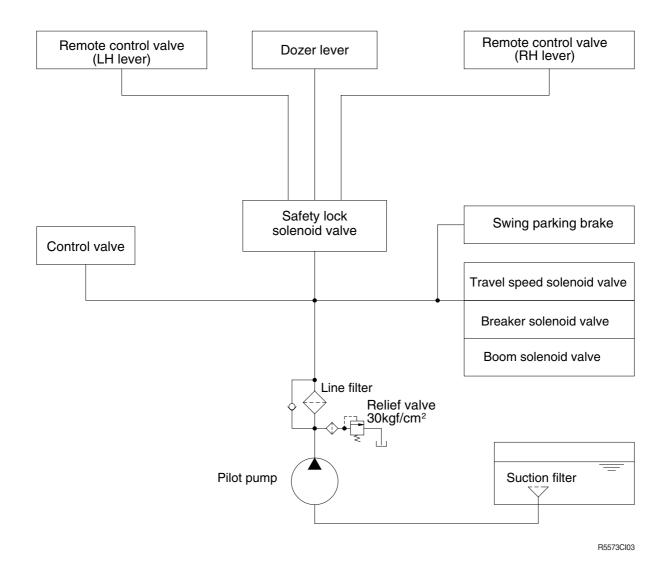
1) TRAVEL MOTOR DRAIN CIRCUIT

Oil leaked from the right and left travel motors comes out of the drain ports provided in the respective motor casing and join with each other. These oils pass through the turning joint and return to the hydraulic tank after being filtered by return filter.

2) SWING MOTOR DRAIN CIRCUIT

Oil leaked from the swing motor returns to the hydraulic tank passing through a return filter with oil drained from the travel circuit .

GROUP 3 PILOT CIRCUIT

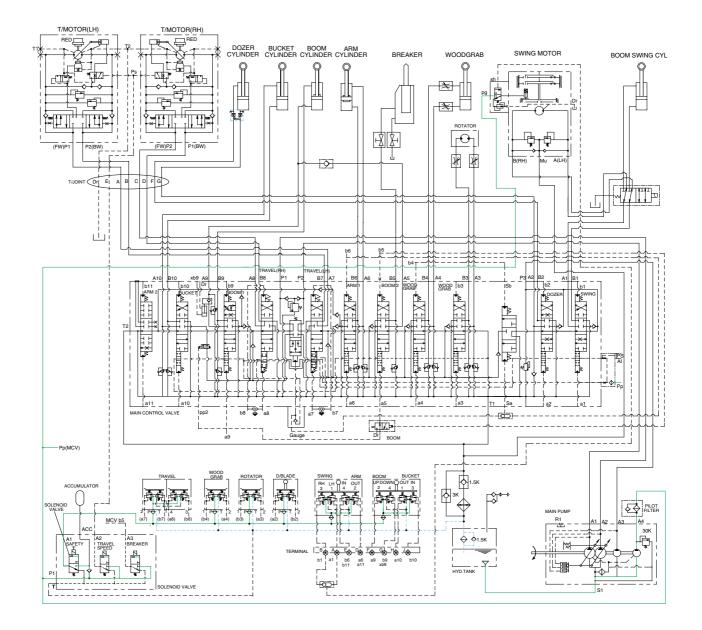


The pilot circuit consists of suction circuit, delivery circuit and return circuit.

The pilot pump is provided with relief valve, receives the oil from the hydraulic tank through the suction filter.

The discharged oil from the pilot pump flows to the remote control valve through line filter, solenoid valve assemblies, swing parking brake, main control valve and safety lock solenoid valve.

1. SUCTION, DELIVERY AND RETURN CIRCUIT



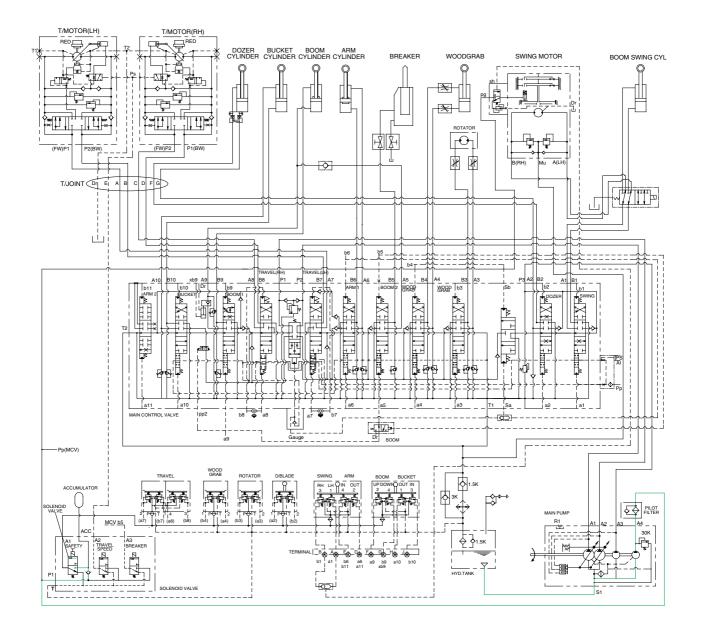
5593HC02

The pilot pump receive oil from the hydraulic tank. The discharged oil from the pilot pump flows to the safety solenoid valve through the line filter. The oil is filtered by the line filter. The pilot relief valve is provided in the pilot pump for limiting the pilot circuit pressure.

The oil filtered by line filter flows remote control valve through safety solenoid valve.

The return oil flow into the hydraulic tank.

2. SAFETY VALVE (SAFETY LEVER)

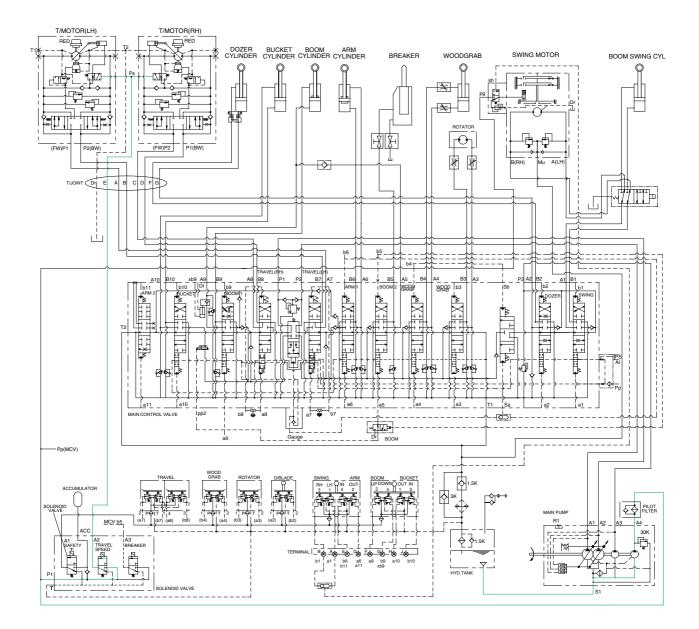


5593HC03

When the lever of the safety solenoid value is moved downward, oil flows into the remote control value through solenoid value and line filter.

When the lever of the safety solenoid valve is moved upward, oil does not flow into the remote control valve, because of the blocked port.

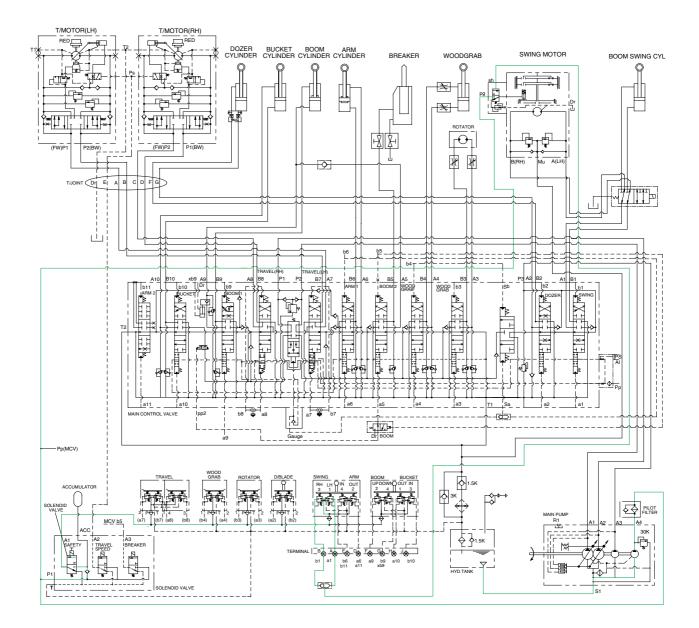
3. TRAVEL SPEED CONTROL SYSTEM



5593HC04

When the travel speed switch is pushed, the travel speed solenoid valve is actuated and the discharged oil from the pilot pump flows to the Ps port of pilot valve in the travel motors. As a result, the control piston is pushed by the main oil flow, thus the displacement is minimized. When the travel speed switch is pushed once more, the travel speed solenoid valve is return to original position by the force of spring, the hydraulic oil of Ps port returns to the hydraulic tank. As a result, the control piston is returned by the main oil flow, thus the displacement is maximized.

4. SWING PARKING BRAKE RELEASE



5593HC05

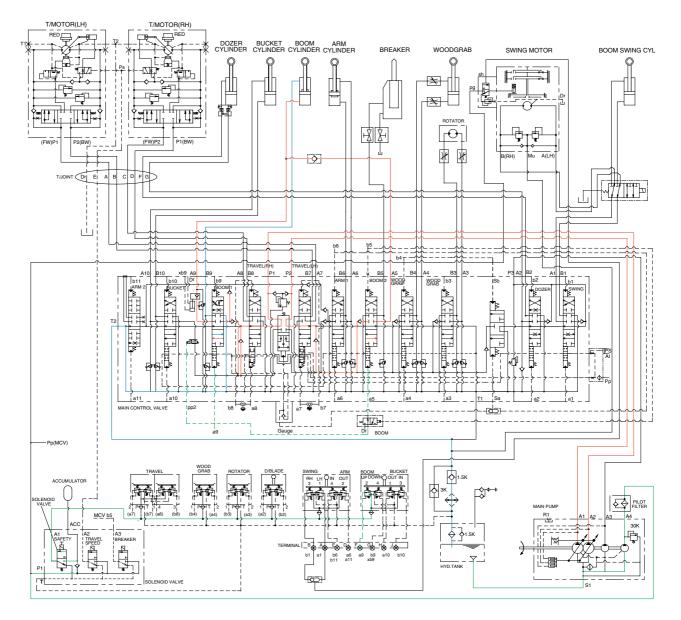
When the swing control lever is tilted, the pilot oil flow into SH port of shuttle valve, this pressure move spool so, discharged oil from pilot valve flow into PG port.

This pressure is applied to swing motor disc, thus the brake is released.

When the swing control lever is set in the neutral position, oil in the swing motor disc cylinder is drained, thus the brake is applied.

GROUP 4 SINGLE OPERATION

1. BOOM UP OPERATION

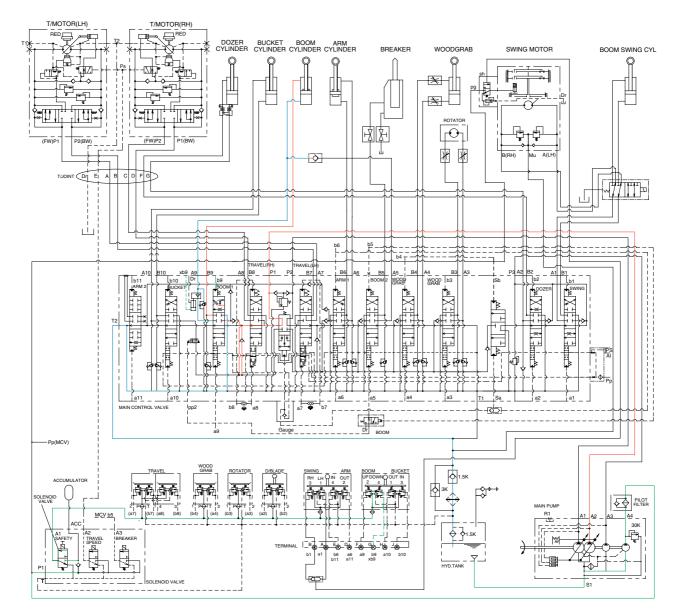


5593HC06

When the right control lever is pulled back, the boom spools in the main control valve are moved to the up position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the main control valve and then goes to the large chamber of boom cylinders. At the same time, the oil from the small chamber of boom cylinders returns to the hydraulic oil tank through the boom spool in the main control valve. When this happens, the boom goes up. The excessive pressure in the boom cylinder bottom end circuit is prevented by relief valve. When the boom is up and the control lever is returned to neutral position, the circuit for the holding pressure at the bottom end of the boom cylinder is closed by the boom holding valve. This prevents the hydraulic drift of boom cylinder.

2. BOOM DOWN OPERATION



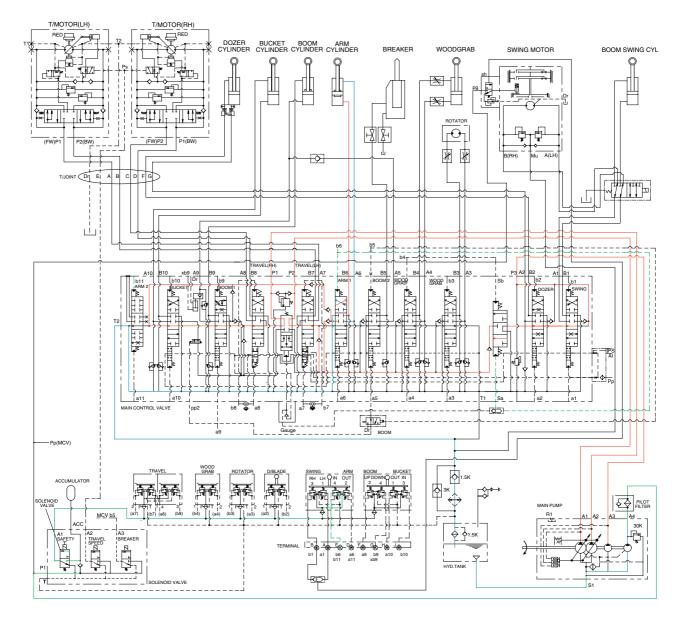
5593HC07

When the right control lever is pushed forward, the boom spools in the main control valve are moved to the down position by the pilot oil pressure from the remote control valve.

The oil from the A2 pump flows into the main control valve and then goes to the small chamber of boom cylinders. At the same time, the oil from the large chamber of boom cylinders returns to the hydraulic tank through the boom spool in the main control valve.

The excessive pressure in the boom cylinder rod end circuit is prevented by the relief valve.

3. ARM ROLL IN OPERATION



5593HC08

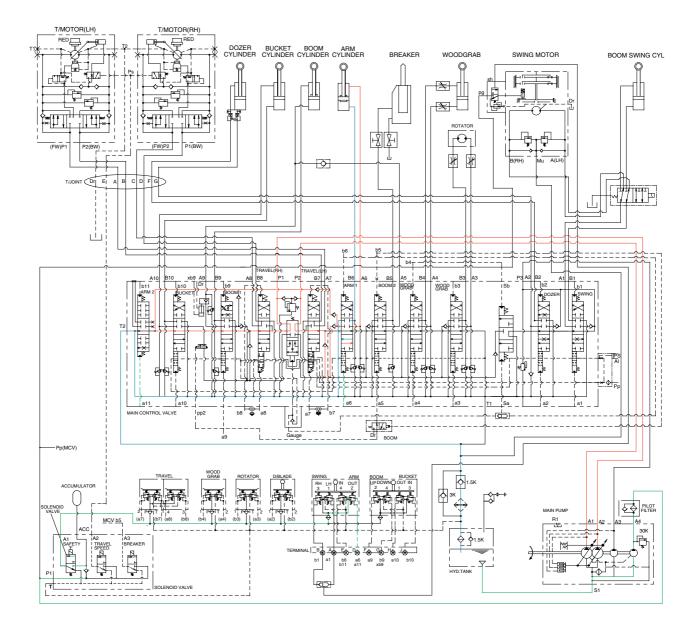
When the left control lever is pulled back, the arm spools in the main control valve are moved the to roll in position by the pilot oil pressure from the remote control valve.

The oil from the A1, A2 and A3 pump flows into the main control valve and then goes to the large chamber of arm cylinder.

At the same time, the oil from small chamber of arm cylinder returns to the hydraulic oil tank through the arm spool in the main control valve. When this happens, the arm rolls in.

The cavitation which will happen to the bottom of the arm cylinder is also prevented by the make-up valve in the main control valve.

4. ARM ROLL OUT OPERATION



5593HC09

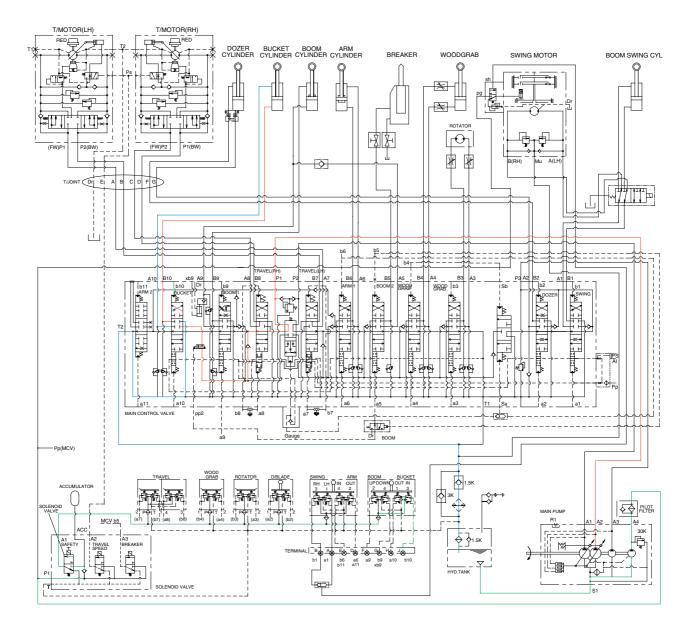
When the left control lever is pushed forward, the arm spool in the main control valve are moved to the roll out position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the main control valve and then goes to the small chamber of arm cylinder.

At the same time, the oil from the large chamber of arm cylinder returns to the hydraulic oil tank through the arm spool in the main control valve. When this happens, the arm rolls out.

The cavitation which will happen to the rod of the arm cylinder is also prevented by the make-up valve in the main control valve.

5. BUCKET ROLL IN OPERATION



5593HC10

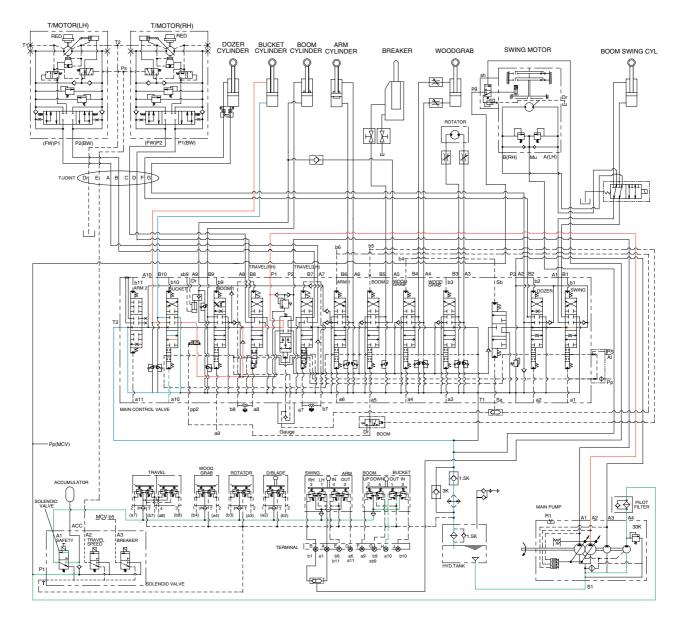
When the right control lever is pulled left, the bucket spool in the main control valve is moved to the roll in position by the pilot oil pressure from the remote control valve.

The oil from the A2 pump flows into the main control valve and then goes to the large chamber of bucket cylinder.

At the same time, the oil from the small chamber of bucket cylinder returns to the hydraulic oil tank through the bucket spool in the main control valve. When this happens, the bucket rolls in.

The cavitation which will happen to the bottom of the bucket cylinder is also prevented by the makeup valve in the main control valve.

6. BUCKET ROLL OUT OPERATION



5593HC11

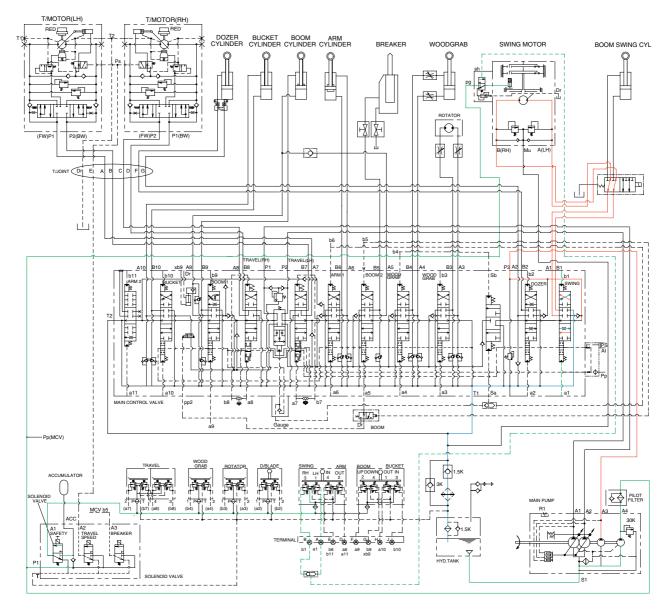
When the right control lever is pushed right, the bucket spool in the main control valve is moved to the roll out position by the pilot oil pressure from the remote control valve.

The oil from the A2 pump flows into the main control valve and then goes to the small chamber of bucket cylinder.

At the same time, the oil from the large chamber of bucket cylinder returns to the hydraulic oil tank through the bucket spool in the main control valve. When this happens, the bucket rolls out.

The cavitation which will happen to the rod of the bucket cylinder is also prevented by the make-up valve in the main control valve.

7. SWING OPERATION



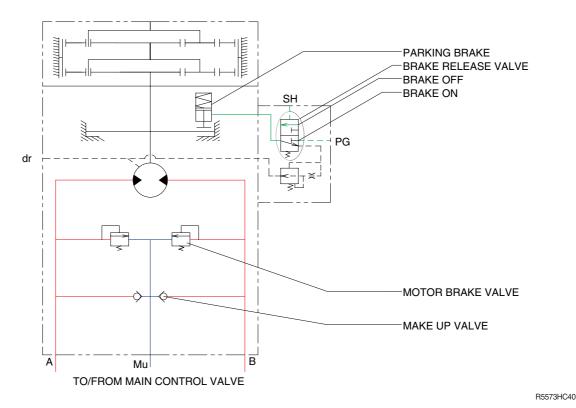
5593HC12

When the left control lever is pushed left or right, the swing spool in the main control valve is moved to the left or right swing position by the pilot oil pressure from the remote control valve.

The oil from the A3 pump flows into the main control valve and then goes to the swing motor.

At the same time, the return oil from the swing motor returns to the hydraulic oil tank through the swing spool in the main control valve. When this happens, the superstructure swings to the left or right. The swing parking brake, make up valve and the overload relief valve are provided in the swing motors. The cavitation which will happen to the swing motor is also prevented by the make up valve in the swing motor itself.

SWING CIRCUIT OPERATION



1) MOTOR BRAKE VALVE

Motor brake valve for the swing motor limits to cushion the starting and stopping pressure of swing operation.

2) MAKE UP VALVE

The make up valves prevent cavitation by supplying return oil to the vacuum side of the motor.

3) PARKING BRAKE

In case that the parking, of the machine at slope is required during operation, there is the danger of involuntary swing caused by the self weight of the machine. The brake is connected to prevent this involuntary swing.

PARKING BRAKE "OFF" OPERATION

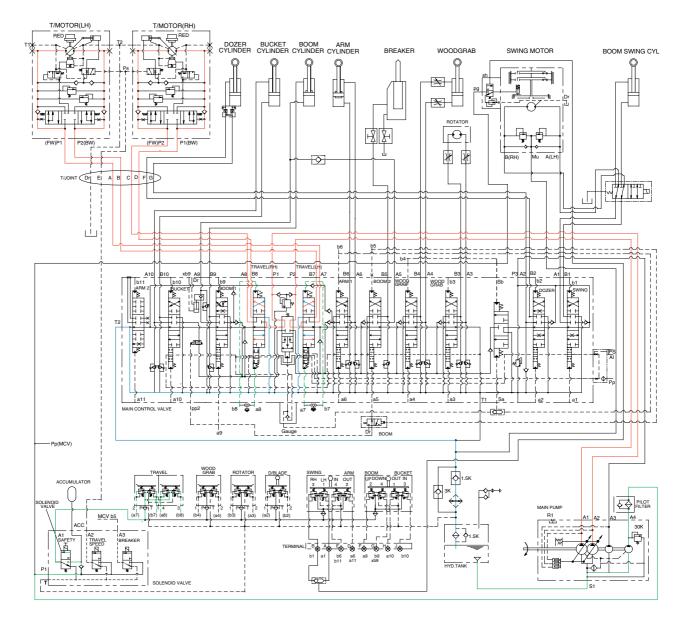
The parking brake is released by the pilot pressure oil from the pilot pump.

When the left control lever placed in the swing position, the pilot pressure at the shuttle valve is transferred to the brake release valve and the brake release valve is change over. Then the pilot pressure lift the brake piston and release the parking brake.

PARKING BRAKE "ON" OPERATION

When the control lever placed in the neutral position, the pressure of the pilot oil passage down. Then the brake release valve returned to the neutral position and the oil is returned from the brake piston to the tank. And the brake is set to 'ON".

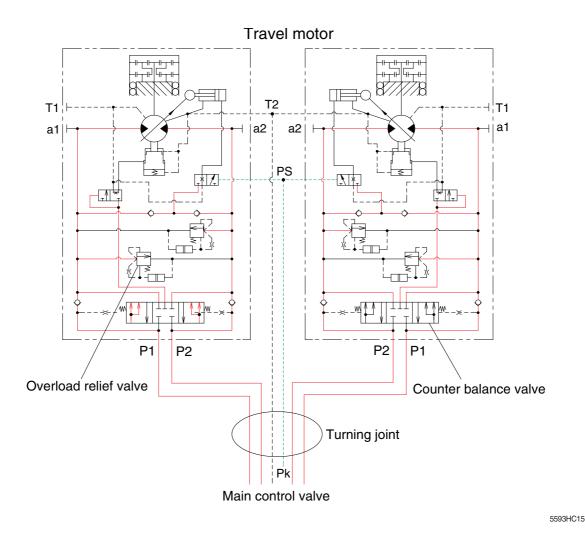
8. TRAVEL FORWARD AND REVERSE OPERATION



5593HC14

When the travel levers are pushed forward or reverse position, the travel spools in the main control valve are moved to the forward or reverse travel position by the link. The oil from the both pumps (A1, A2) flows into the main control valve and then goes to the both travel motors through the turning joint. The return oil from both travel motors returns to the hydraulic oil tank through the turning joint and the travel spools in the main control valve. When this happens, the machine moves to the forward or reverse.

TRAVEL CIRCUIT OPERATION



Valves are provided on travel motors to offer the following functions.

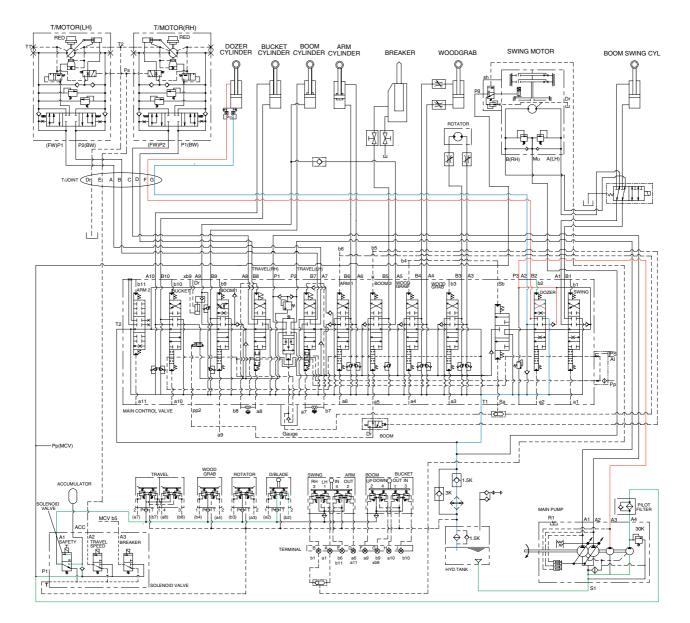
1) COUNTER BALANCE VALVE

When stopping the motor of slope descending, this valve to prevent the motor over run.

2) OVERLOAD RELIEF VALVE

Relief valve limit the circuit pressure below 220 kgf/cm² to prevent high pressure generated at at time of stopping the machine. Stopping the motor, this valve sucks the oil from lower pressure passage for preventing the negative pressure and the cavitation of the motor.

9. DOZER UP OPERATION



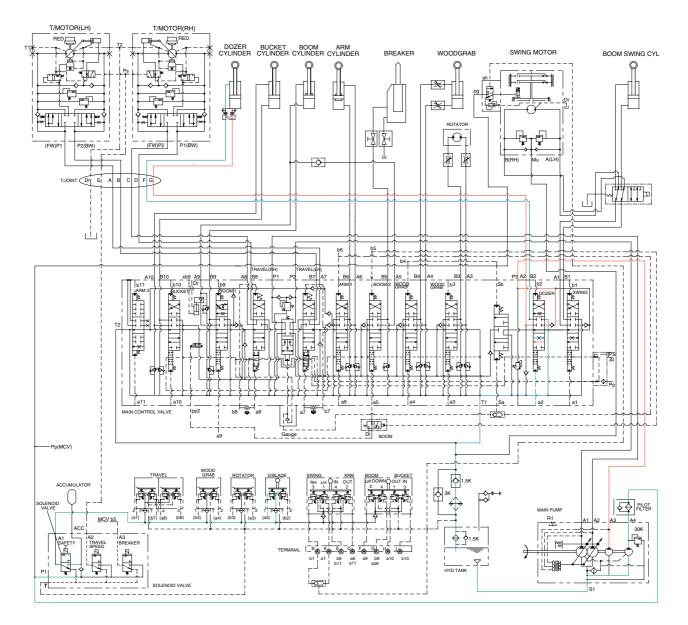
5593HC16

When the dozer control lever is pulled back, the dozer spool in the main control valve is moved to the dozer up position by the pilot oil pressure from the remote control valve.

The oil from the A3 pump flows into the main control valve and then goes to the small chamber of dozer cylinders.

At the same time, the oil from the large chamber of dozer cylinders returns to the hydraulic oil tank through the dozer spool in the main control valve. When this happens, the dozer goes up.

10. DOZER DOWN OPERATION



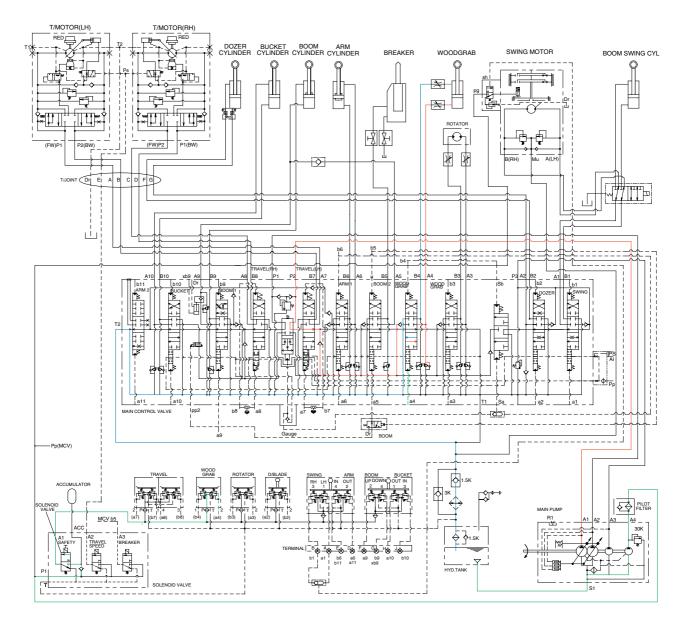
5593HC17

When the dozer control lever is pushed forward, the dozer spool in the main control valve is moved to the dozer down position by the pilot oil pressure from the remote control valve.

The oil from the A3 pump flows into the main control valve and then goes to the large chamber of dozer cylinders.

At the same time, the oil from the small chamber of dozer cylinders returns to the hydraulic oil tank through the dozer spool in the main control valve. When this happens, the dozer blade is down.

11. WOODGRAB CLOSE



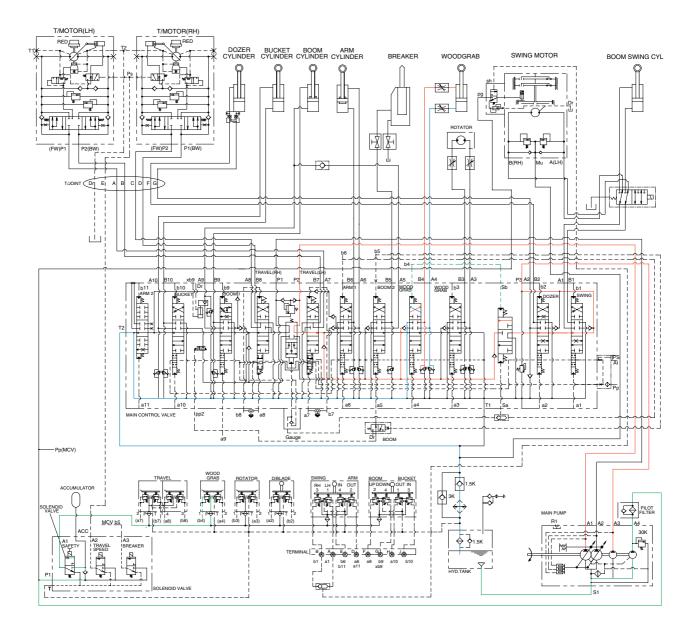
5593HC18

When the left control pedal (OPT) pushed forward, the woodgrab spool in the main control valve is moved to the woodgrab close position by the pilot oil pressure from the remote control valve. The oil from the A1 pump flows into the main control valve and then goes to the large chamber of woodgrab cylinder.

At the same time, the oil from the small chamber of woodgrab cylinder returns to the hydraulic oil tank through the woodgrab spool in the main control valve.

When this happens the woodgrab close. The cavitation which will happen to the large chamber of woodgrab cylinder is also prevented by the make-up valve in the main control valve.

12. WOODGRAB OPEN



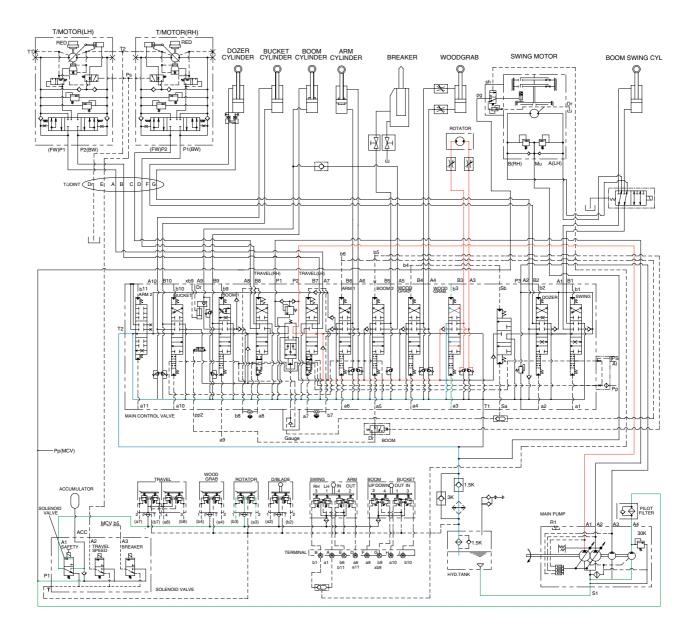
5593HC19

When the left control pedal (OPT) pushed backward, the woodgrab spool in the main control valve is moved to the woodgrab open position by the pilot oil pressure from the remote control valve. The oil from the A1 pump flows into the main control valve and then goes to the small chamber of woodgrab cylinder.

At the same time, the oil from the large chamber of woodgrab cylinder returns to the hydraulic oil tank through the woodgrab spool in the main control valve.

When this happens the woodgrab open. The cavitation which will happen to the small chamber of woodgrab cylinder is also prevented by the make-up valve in the main control valve.

13. WOODGRAB ROTATE OPERATION



5593HC20

When the right control pedal pushed forward or backward, the woodgrab rotate spool in the main control valve is moved to the woodgrab rotate position by the pilot oil pressure from the remote control valve.

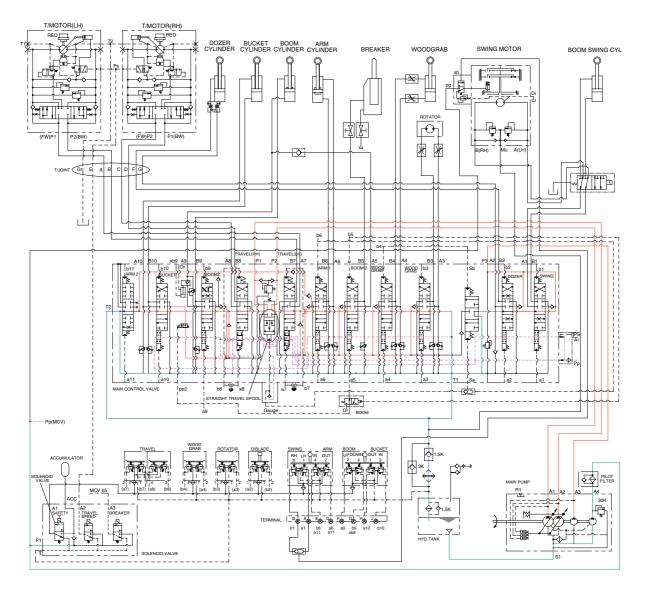
The oil from the A1 pump flows into the main control valve and the goes to the rotator.

At the same time, the oil from rotator returns to the hydraulic tank through to the woodgrab rotate spool in the main control valve. When this happens, the woodgrab rotates counterclockwise or clockwise.

The cavitation which will happen to the rotator is also prevented by the make-up valve in the main control valve.

GROUP 5 COMBINED OPERATION

1. OUTLINE



5593HC21

The oil from the A1, A2, A3 pump flows through the neutral oil passage, bypass oil passage and confluence oil passage in the main control valve. Then the oil goes to each actuator and operates them. Check valves and orifices are located on these oil passage in the main control valve. These control the oil from the main pumps so as to correspond to the operation of each actuator and smooth the combined operation.

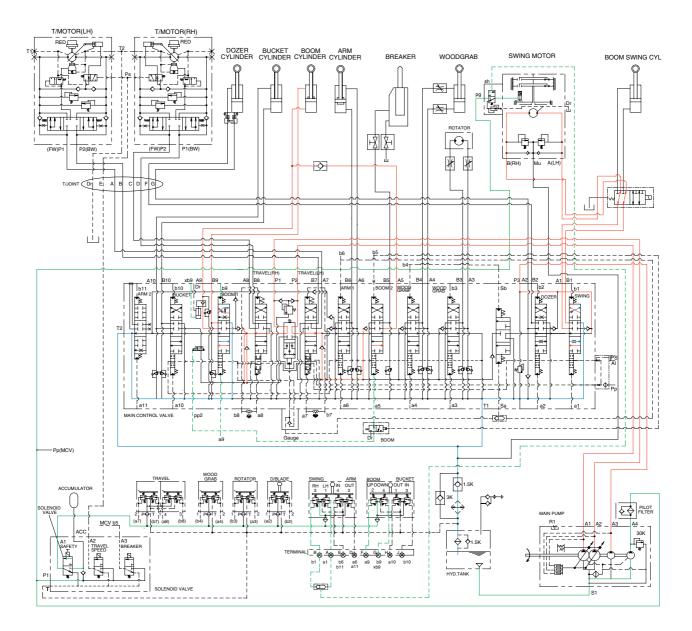
STRAIGHT TRAVEL SPOOL

This straight travel spool for straight travel is provided in the main control valve.

If any actuator is operated when traveling, the straight travel spool is pushed to the up by the pilot oil pressure.

Consequently, the left and right travel oil supply passage are connected, and equivalent amount of oil flows into the left and right travel motors. This keeps the straight travel.

2. COMBINED SWING AND BOOM OPERATION



5593HC22

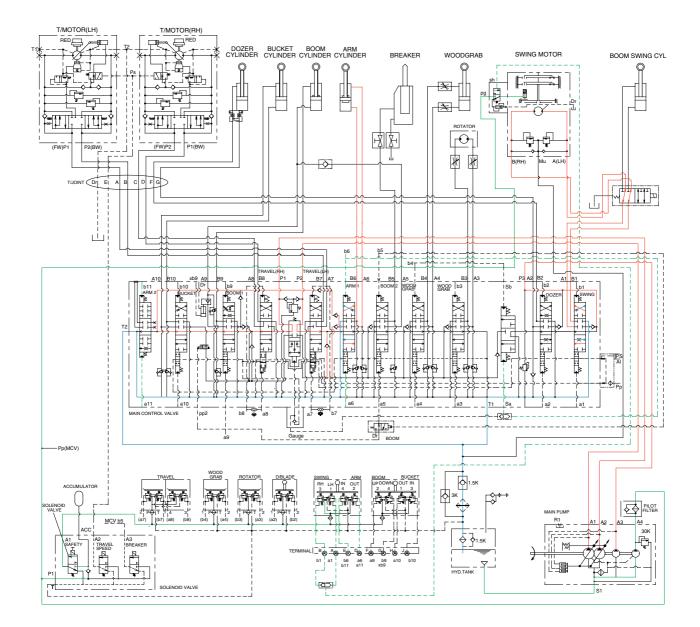
When the swing and boom functions are operated, simultaneously the swing spool and boom spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve.

The oil from the A1 and A2 pump flows into the boom cylinder through boom and boom 2 spool.

The oil from the A3 pump flows into the swing motor through the swing spool.

The superstructure swings and the boom is operated.

3. COMBINED SWING AND ARM OPERATION



5593HC23

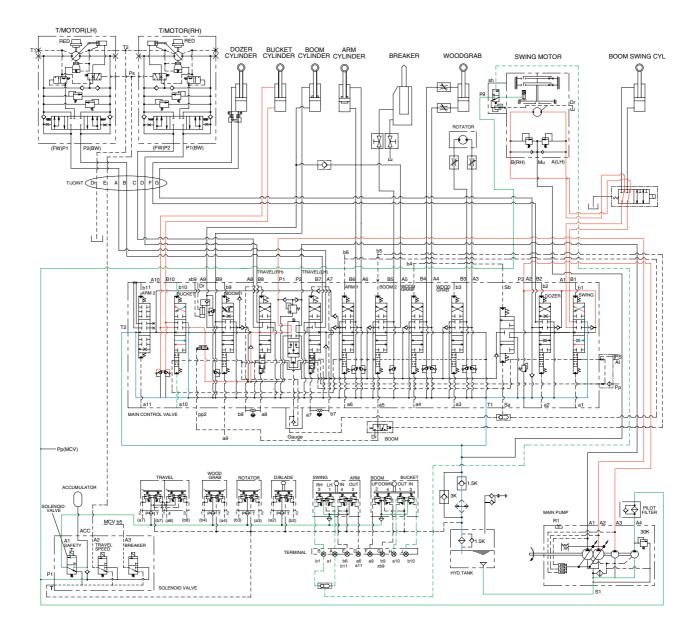
When the swing and arm functions are operated, simultaneously the swing spool and arm spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve.

The oil from the A3 pump flows into the swing motor through swing spool.

The oil from the A1 and A2 pump flows into the arm cylinder through the arm and arm 2 spool.

The superstructure swings and the arm is operated.

4. COMBINED SWING AND BUCKET OPERATION



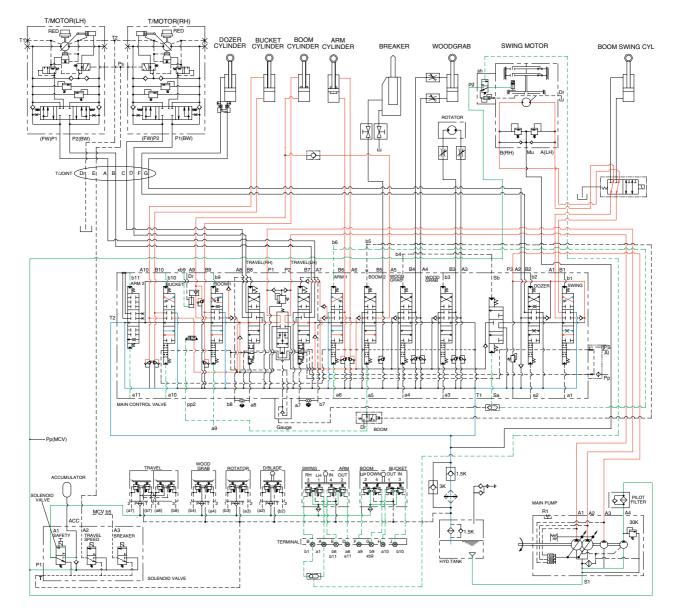
5593HC24

When the swing and bucket functions are operated, simultaneously the swing spool and bucket spool in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve.

The oil from the A3 pump flows into the swing motor through the swing spool.

The oil from the A2 pump flows into the bucket cylinder through the bucket spool.

5. COMBINED SWING, BOOM, ARM AND BUCKET OPERATION



5593HC25

When the swing, boom, arm and bucket functions are operated, simultaneously each spool in the main control valve is moved to the functional position by the pilot oil pressure from the remote control valve.

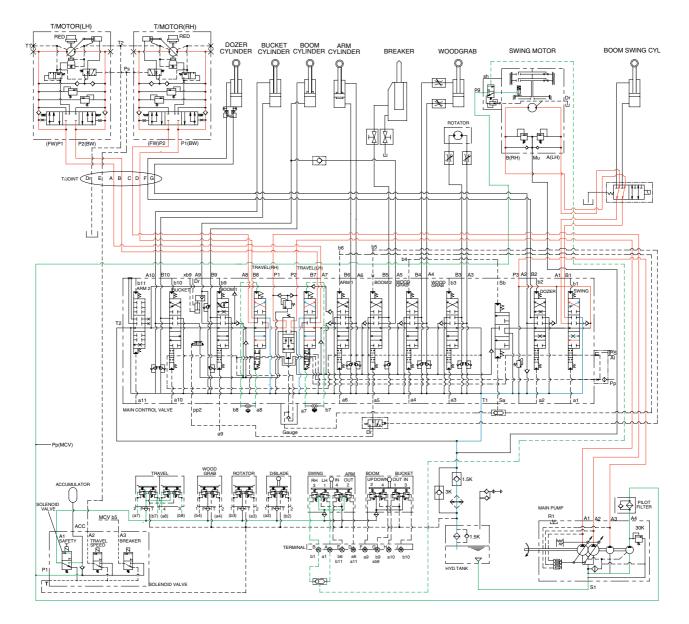
The oil from the A1 pump flows into the boom cylinders and arm cylinder through boom 2 spool, arm spool.

The oil from the A2 pump flows into the boom cylinders, arm cylinder and bucket cylinder through the boom spool, arm 2 spool, bucket spool.

The oil from the A3 pump flows into the swing motor through the swing spool.

The superstructure swings and the boom, arm and bucket are operated.

6. COMBINED SWING AND TRAVEL OPERATION



5593HC26

When the swing and travel functions are operated, simultaneously the swing spool and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve and the travel levers.

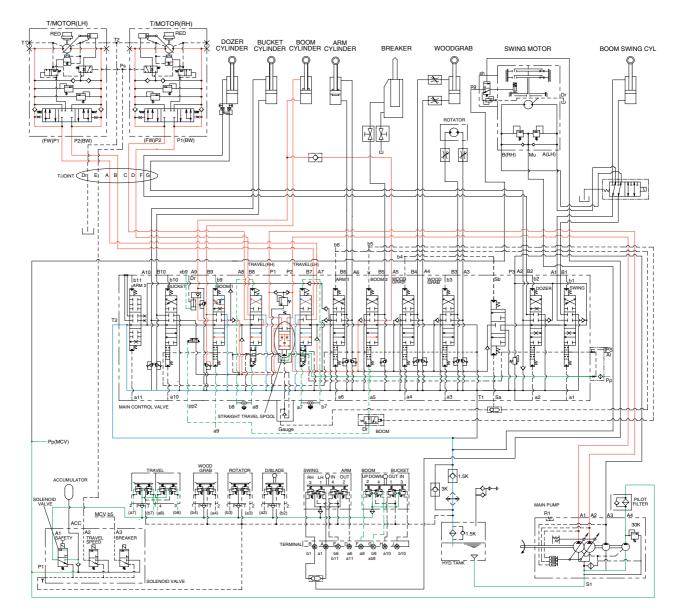
The oil from the A3 pump flows into the swing motor through the swing spool.

The oil from the A1 pump flows into the travel motor through the LH travel spool.

The oil from the A2 pump flows into the travel motor through RH travel spool.

The superstructure swings and the machine travels straight.

7. COMBINED BOOM AND TRAVEL OPERATION



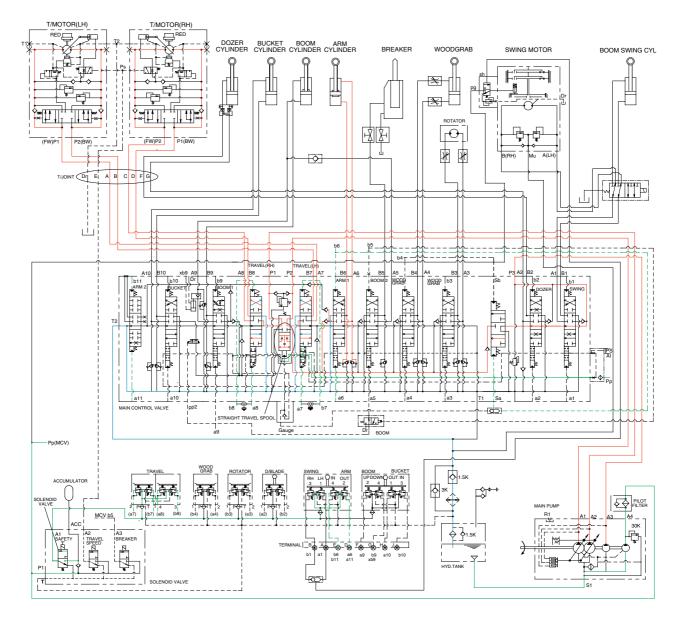
5593HC27

When the boom and travel functions are operated, simultaneously the boom spools and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve and the straight travel spool is pushed to the up by the oil pressure from pilot pump.

The oil from the A1 and A2 pumps flows into the boom cylinders and the travel motors through boom 1, boom 2, travel LH and travel RH spools via the straight travel spool.

The boom is operated and the machine travels straight.

8. COMBINED ARM AND TRAVEL OPERATION



5593HC28

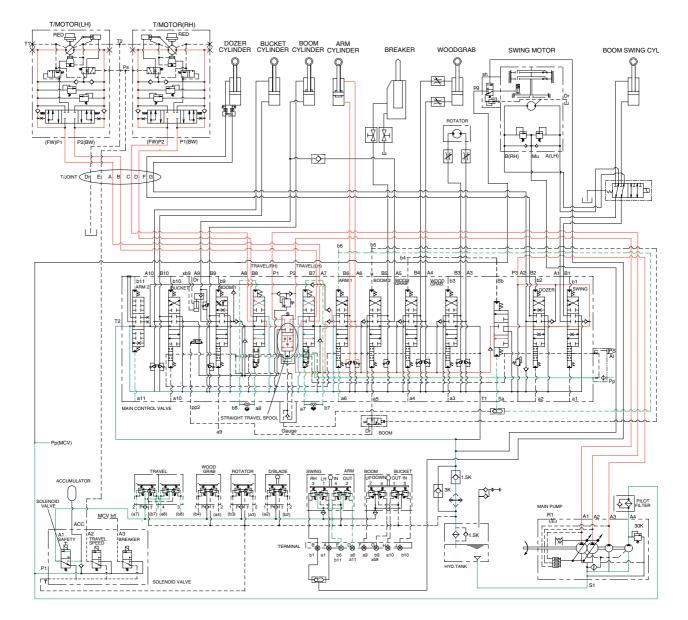
When the arm and travel functions are operated, simultaneously the arm spools and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve and the straight travel spool is pushed to the up by the oil pressure from pilot pump.

The oil from the A1 and A2 pumps flows into the travel motors and the arm cylinder through travel spools and arm spools via the straight travel spool.

At the same time, the oil from the A3 pump flows into the arm cylinder through the arm 1 spool via the selector valve.

The arm is operated and the machine travels straight.

9. COMBINED BUCKET AND TRAVEL OPERATION



5593HC29

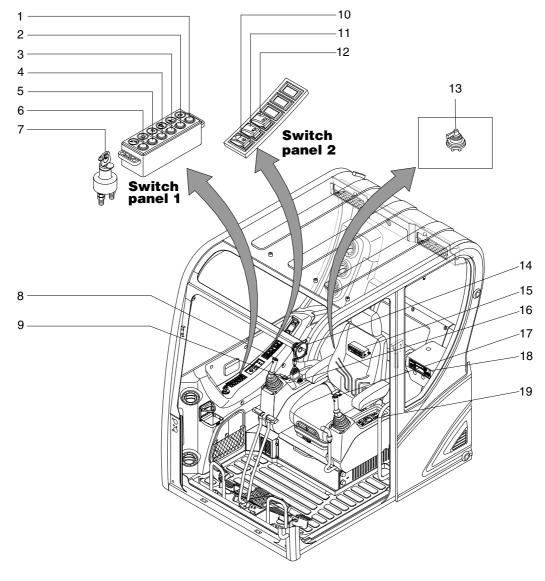
When the bucket and travel functions are operated, simultaneously the bucket spool and travel spools in the main control valve are moved to the functional position by the pilot oil pressure from the remote control valve, and the straight travel spool is pushed to the up by the oil pressure from pilot pump. The oil from the A1 and A2 pumps flows into the travel motors and the bucket cylinder through the travel spools and the bucket spool via the straight travel spool. The bucket is operated and the machine travels straight.

Group	1 Component Location	4-1
Group	2 Monitoring system ·····	4-3
Group	3 Electrical Circuit	4-16
Group	4 Electrical Component Specification	4-32
Group	5 Connectors	4-39

SECTION 4 ELECTRICAL SYSTEM

GROUP 1 COMPONENT LOCATION

1. LOCATION 1



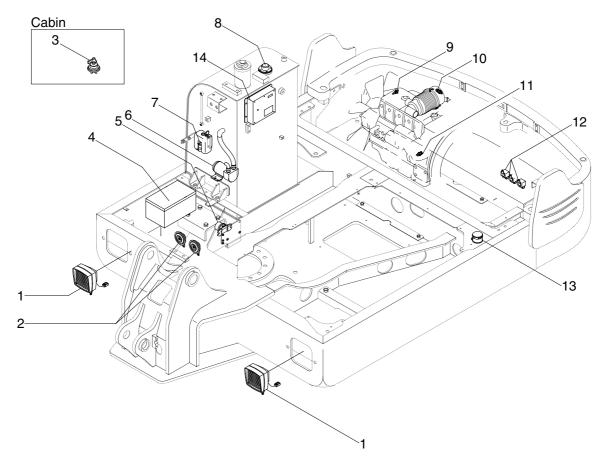
5594EL02

- 1 Head light switch
- 2 Work light switch
- 3 Travel alarm switch
- 4 Cab light switch
- 5 Beacon switch
- 6 Breaker selection switch
- 7 Start switch

- 8 Breaker operation switch
- 9 Accel dial switch
- 10 Quick clamp switch
- 11 Wiper switch
- 12 Washer switch
- 13 Master switch
- 14 Speaker

- 15 Fuse box
- 16 Cigar lighter
- 17 Horn switch
- 18 Radio & CD/MP3 player
- 19 Aircon & heater controller

2. LOCATION 2



5594EL03

- 1 Lamp
- 2 Horn
- 3 Master switch
- 4 Battery
- 5 Battery relay
- 6 Fuel filler pump
- 7 Washer pump
- 8 Fuel sender
- 9 Temperature sender
- 10 Air clearer switch
- 11 Engine oil pressure switch
- 12 Relays
- 13 Travel alarm buzzer
- 14 MCU

GROUP 2 MONITORING SYSTEM

1. OUTLINE

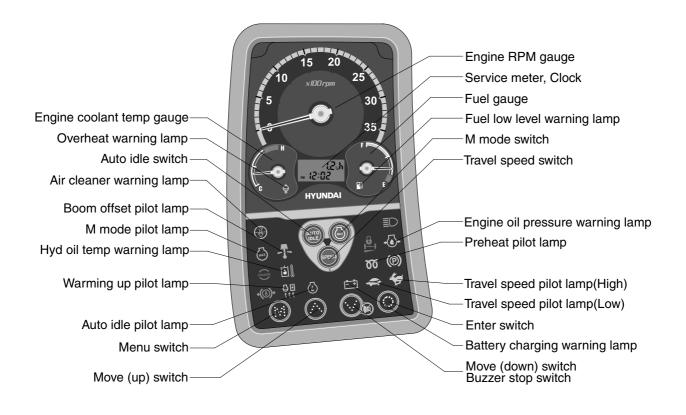
Monitoring system consists of the monitor part and switch part.

The monitor part gives warnings when any abnormality occurs in the machine and informs the condition of the machine.

Various select switches are built into the monitor panel, which act as the control portion of the machine control system.

2. CLUSTER

1) MONITOR PANEL



5593CD02

2) CLUSTER CHECK PROCEDURE

(1) Start key : ON

0 Check monitor initial 6 seconds

- a. All lamps light up.
- b. Buzzer sound.

⁽²⁾ Check monitor after 3 seconds : Indicate machine condition

- a. Tachometer: 0 rpm
- b. Fuel gauge : Pointed at appropriate level
- c. Engine coolant temperature gauge : Pointed at appropriate level
- d. Warning lamp
- * During start key ON the engine oil pressure lamp and battery charging lamp go on, but it is not abnormal.
- * When engine coolant temperature below 30°C, the warming up lamp lights up and then operating the preheat switch.

(2) Start of engine

① Check machine condition

- a. Tachometer pointed at present rpm
- b. Gauge and warning lamp : Indicate at present condition.
- * When normal condition : All warning lamp OFF
- c. Travel speed pilot lamp : Low (turtle)

2 When abnormal condition

- a. The lamp lights up and the buzzer sounds.
- b. If BUZZER STOP switch is pressed, buzzer sound is canceled but the lamp light up until normal condition.

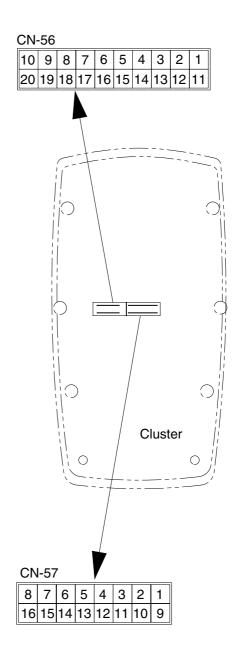
3. CLUSTER CONNECTOR

1) CN-56 CONNECTOR

No.	Signal	Input/ Output
1	Null	-
2	Null	-
3	Alternator signal	Input
4	Null	-
5	Tacho signal	Input
6	Anti-restart signal	Output
7	Pre-heat signal	Output
8	Travel relay	Output
9	Power 12V	-
10	Power IG 12V	-
11	Travel signal	Input
12	Illumination	Input
13	Null	-
14	Null	-
15	Fuel level sender	Input
16	Hyd oil temp sendor	Input
17	Water temp sender	Input
18	GND	-
19	GND	-
20	GND	-

2) CN-57 CONNECTOR

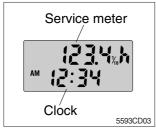
No.	Signal	Input/ Output
1	Null	-
2	Engine oil pressure switch	Input
3	Hyd oil temp sendor	Input
4	Boom swing signal	-
5	Null	-
6	Null	-
7	Null	-
8	Null	-
9	Program dump	-
10	Null	-
11	COM-GND	Input
12	RS232-RX	Input
13	RS232-TX	Output
14	RS485-RX	Input
15	RS485-TX	Output
16	Over heat signal	Input



4. CLUSTER FUNCTION

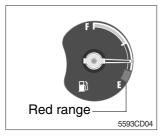
1) GAUGES AND DISPLAYS

(1) LCD display



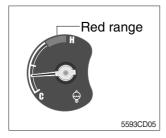
- ① Service meter : This meter shows the total operation hours of the machine.
- * Always ensure the operating condition of the meter during the machine operation.
- * The last unit 4_{χ_0} indicates 1/10 of 4 hours.
 - (for example : \int_{10}^{1} indicates 6 minutes)
- ② Clock : This displays the current time.
- * Refer to the "menu switch" for the setting time/ESL switch.

(2) Fuel gauge



- ${\rm I}\!{\rm D}$ This gauge indicates the amount of fuel in the fuel tank.
- 2 Fill the fuel when the red range or warning lamp \blacksquare blinks.
- ※ If the gauge indicate the red range or warning lamp → ON. Even though the machine is on the normal condition, check the electric device as that can be caused by the poor connection of electricity or sensor.

(3) Engine coolant temperature gauge



- ① This indicates the temperature of coolant.
- ② When the red range pointed or warning lamp blinks, engine do not abruptly stop but run it at medium speed to allow it to cool gradually, then stop it.
- Check the radiator and engine.
- * If the engine is stopped without cooled down running, the temperature of engine parts will rise suddenly, this could cause severe engine trouble.

(4) Engine rpm gauge



 $\ensuremath{\textcircled{}}$ This gauge displays the number of engine revolutions per minute.

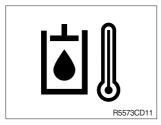
2) WARNING AND PILOT LAMPS

(1) Fuel low level warning lamp



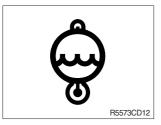
- 1 This lamp blinks and the buzzer sounds when the level of fuel is below 18 l (4.8 U.S. gal).
- $\ensuremath{\textcircled{}^{2}}$ Fill the fuel immediately when the lamp blinks.

(2) Hydraulic oil temperature warning lamp



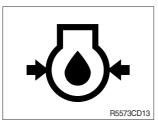
- ① This warning lamp operates and the buzzer sounds when the temperature of hydraulic oil is over 105°C (221°F).
- ⁽²⁾ Check the hydraulic oil level when the lamp blinks.
- ③ Check for debris between oil cooler and radiator.

(3) Overheat warning lamp



 This lamp blinks and the buzzer sounds when the temperature of coolant is over the normal temperature 110°C (230°F).
 Check the cooling system when the lamp blinks.

(4) Engine oil pressure warning lamp



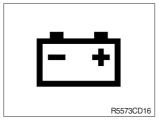
- ${\rm (I)}$ This lamp blinks and the buzzer sounds after starting the engine because of the low oil pressure.
- ⁽²⁾ If the lamp blinks during engine operation, shut OFF engine immediately. Check oil level.

(5) Air cleaner warning lamp



- ① This lamp blinks and the buzzer sounds when the filter of air cleaner is clogged.
- $\ensuremath{\textcircled{}^{\texttt{O}}}$ Check the filter and clean or replace it.

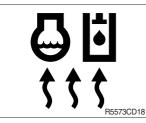
(6) Battery charging warning lamp



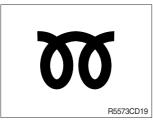
① This lamp blinks and the buzzer sounds when the starting switch is ON, it is turned OFF after starting the engine.

⁽²⁾ Check the battery charging circuit when this lamp blinks during engine operation.

(7) Warming up pilot lamp



(8) Preheat pilot lamp



 $30^{\circ}C$ (86°F). ⁽²⁾ The automatic warming up is cancelled when the engine

① This lamp is turned ON when the coolant temperature is below

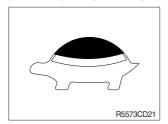
- coolant temperature is above 30°C, or when 10 minutes have passed since starting.
- 0 When engine preheating switch is turned ON, pilot lamp cames ON.
- $\ensuremath{\textcircled{}^{2}}$ Refer to the preheating switch for details.

(9) Travel speed pilot lamp (high)



When this lamp turned ON, the machine travel high speed.
 Refer to the travel speed select switch for details.

(10) Travel speed pilot lamp (low)



When this lamp turned ON, the machine travel low speed.
 Refer to the travel speed select switch for details.

(11) Auto idel pilot lamp



(12) M mode pilot lamp



① This lamp is ON when the M mode switch is pressed.

⁽²⁾ Engine is operated with a maximum speed.

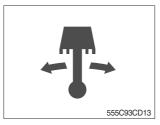
engine revolution is turned to the previous condition.

and engine speed is decelerated.

① If the control lever and pedal are not moved for several seconds with auto idle switch pressed, the indicator illuminates

2 If the auto idle switch is pressed once more or the control lever or pedal is moved, the indicator turns off and the number of

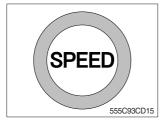
(13) Boom offset pilot lamp



1 This lamp is ON when the boom offset switch is pressed.

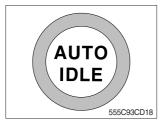
3) SWITCHES

(1) Travel speed control switch



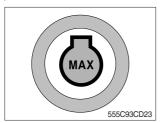
① This switch is to control the travel speed which is changed to high speed (rabbit mark) by pressing the switch and low speed (turtle mark) by pressing it again.

(2) Auto idle switch



 This switch is used to actuate or cancel the auto idle function.
 When the switch actuated and all control levers and pedals are at neutral position, engine speed will be lowered automatically to save fuel consumption.

(3) M mode switch



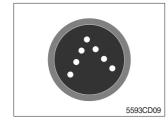
- $\ensuremath{\textcircled{}}$ This switch is used to maximum power.
- ② When this switch is pressed, the M mode pilot lamp is ON or OFF.

(4) Move (down) & buzzer stop switch



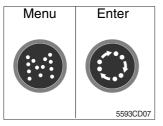
- ① When the starting switch is turned ON first, normally the alarm buzzer sounds for 6 seconds during lamp check operation.
- ② The lamp lights ON and the buzzer sounds when the machine has a problem.
- In this case, press this switch and buzzer stops, but the lamp lights until the problem is cleared.
- ③ This switch is used to move down or decrease input value.
- * Refer to page 4-11.

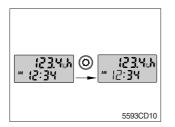
(5) Move (up) switch



- ① This switch is used to move up or increase input value.
- * Refer to page 4-11.

(6) Menu and enter switch





- ① These switches are used to set time or set ESL (Engine Start Limit) function.
 - -The Enter button (\bigcirc) is used to select a function.
 - -The Menu button (()) is used to select a menu or return to the time display menu.

② Setting time

- -Press Enter button (((i)) to set time, then the screen will be changed to a display for time setting as a following picture and time cipher will blink.
- Set hours : When the cipher for hour blinks, press up (\bigcirc) or down (\bigcirc) button and set the hour.
- Set minutes: When the cipher for minute blinks, press up (⊘) or down (⊙) button and set the minute.

③ Set ESL (Engine Start Limit) function

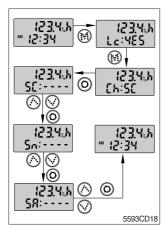
- Press Menu button (), the display is changed from the time display menu to ESL function menu.
- -Select YES or NO by Move button (\bigcirc , \bigcirc) and set the ESL function by the Enter button (O).
 - · YES : ESL function is activated.
 - \cdot NO $\,$: ESL function is cancelled.

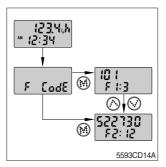
④ Set the interval time

- Select ESL function to YES and press the Enter button (③), then the display is changed to the interval time set menu.
- Set the interval time by move button (\bigcirc , \bigcirc) and press the Enter button (\bigcirc).
- -You can finish setting the interval time by inputting the password and pressing the Enter button (③) once more.
- Interval times : 5 kinds (0, 10, 30, 60 minutes, 1day)
- * If the ESL function is set to YES, the password is required when a operator starting engine first.

But the operator can restart the engine within the interval time period without inputting the password.

(23,4%), ₩ (2:34 ₩	haves:
123.4.5 Lc:465	√ - 1234xh Lc:no
© 234.h 64: 0	
Ed: U ⊙∳⊙	™ (2:34 ● ↓ - (23.4%)
F9: 10 O	5593CD16





(5) Change password

- -Select ESL function to YES and press the Menu button (()), the display is shifted to the password change menu.
 - Input a new password (Sn : - -) after enter the current password successfully (SC : - - -).
 - Push enter (③) button for a second to finish the setting after the new password is entered once again (SA : - -).
 - When the setting is done, the display will blink 3 times and return to the time display screen.

⑥ Check machine and engine diagnostic codes

- If the F : Code is displayed on the LCD display, you can check faults of the machine and/or engine.
- -The machine fault code is displayed by pressing the Menu button ((*)) and the engine fault code is displayed by pressing the Menu button ((*)) once more.
- -Other fault codes can be displayed by using the Move up/ down button (\bigodot , \bigodot).
- * Refer to the following pages for the fault codes.

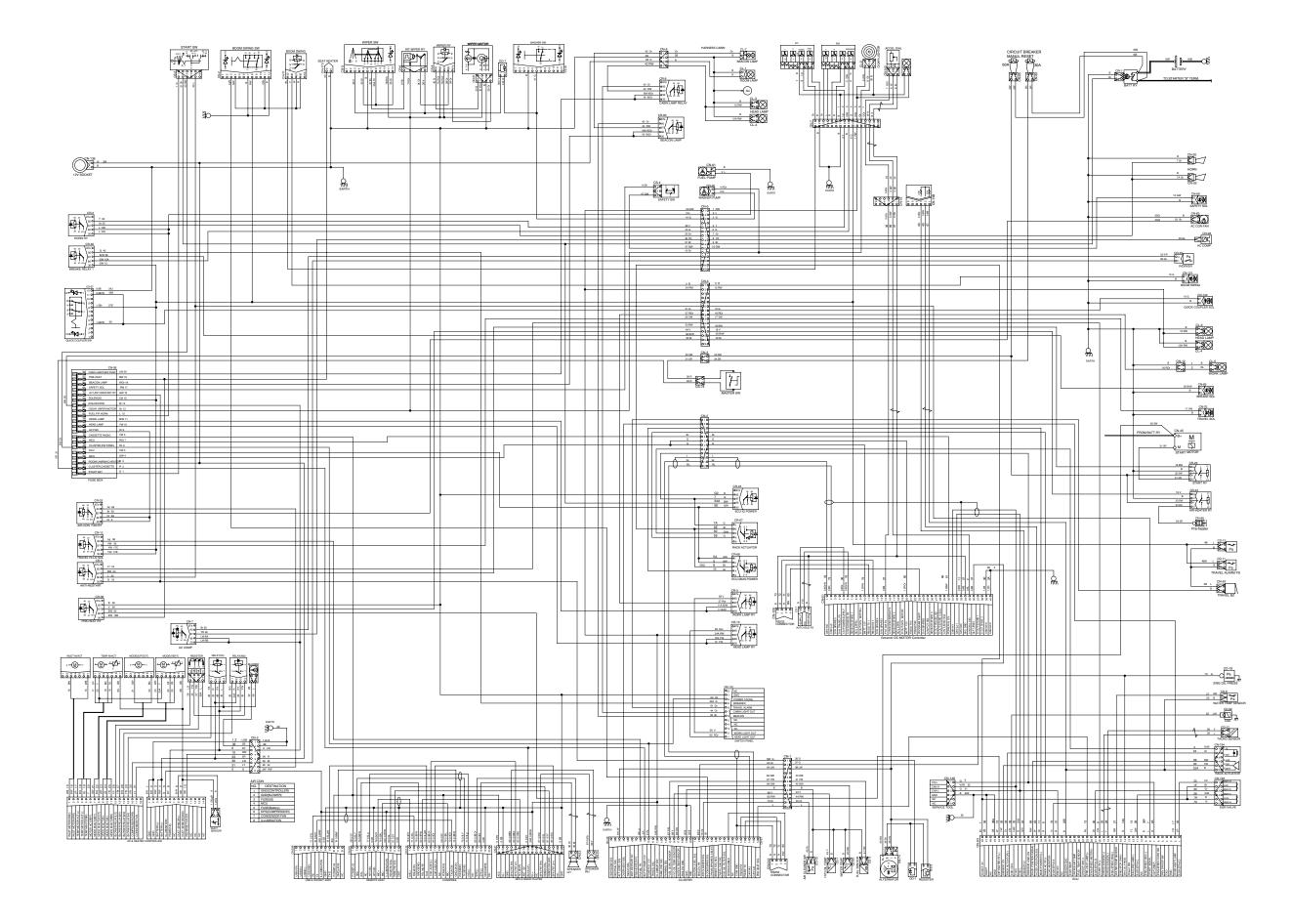
⑦ Machine fault code

Fault code		Description
HCESPN	FMI	Description
101 3		Hydraulic oil temperature sensor circuit - voltage above normal or shorted to high source (or open circuit)
	4	Hydraulic oil temperature sensor circuit - voltage below normal or shorted to low source
	0	Working pressure sensor data above normal range (or open circuit)
105	1	Working pressure sensor data below normal range
105	2	Working pressure sensor data error
	4	Working pressure sensor circuit - voltage below normal, or shorted to low source
	0	Travel oil pressure sensor data above normal range (or open circuit)
100	1	Travel oil pressure sensor data below normal range
108	2	Travel oil pressure sensor data error
	4	Travel oil pressure sensor circuit - voltage below normal or shorted to low source
	0	Overload pressure sensor data above normal range (or open circuit)
100	1	Overload pressure sensor data below normal range
122	2	Overload pressure sensor data error
	3	Overload pressure sensor circuit - voltage below normal or shorted to low source
	3	Fuel level sensor circuit - voltage above normal or shorted to high source (or open circuit)
301	4	Fuel level sensor circuit - voltage below normal or shorted to low source
	0	Brake pressure sensor data above normal range (or open circuit)
	1	Brake pressure sensor data below normal range
503	2	Brake pressure sensor data error
	4	Brake pressure sensor data - voltage below normal or shorted to low source
	0	Working brake pressure sensor data above normal range (or open circuit)
	1	Working brake pressure sensor data below normal range
505	2	Working brake pressure sensor data error
	4	Working brake pressure sensor circuit - voltage below normal, or shorted to low source
	0	Travel fwd pilot pressure sensor data above normal range (or open circuit)
	1	Travel fwd pilot pressure sensor data below normal range
	2	Travel fwd pilot pressure sensor data error
530	4	Travel fwd pilot pressure sensor circuit - voltage below normal, or shorted to low source
	14	Travel fwd pilot pressure sensor circuit - special instructions
	16	Travel fwd pilot pressure sensor circuit - voltage valid but above normal operational range
701	4	Hour meter circuit - voltage below normal, or shorted to low source
	0	MCU input voltage high
705	1	MCU input voltage low
707	1	Alternator node I voltage low (or open circuit)
	3	Acc. dial circuit - voltage above normal, or shorted to high source (or open circuit)
714	4	Acc. dial circuit - voltage below normal, or shorted to low source
840	2	Cluster communication data error
		ECM communication data error

⑧ Engine fault code

Fault cod	de.	
YANMAR SPN	FMI	Description
	4	Engine fuel rack position sensor : shorted to low source
1210	3	Engine fuel rack position sensor : shorted to high source
	4	Accelerator pedal position sensor "A" : shorted to low source
	3	Accelerator pedal position sensor "A" : shorted to high source
	2	Accelerator pedal position sensor "A" : intermittent fault
91	1	Accelerator pedal position sensor "A" : below normal operational range (SAE J1843)
	0	Accelerator pedal position sensor "A" : above normal operational range (SAE J1843)
	15	Accelerator pedal position sensor "A" : not available (SAE J1843)
	4	Accelerator pedal position sensor "B" : shorted to low source
	3	Accelerator pedal position sensor "B" : shorted to high source
	2	Accelerator pedal position sensor "B" : intermittent fault
29	1	Accelerator pedal position sensor "B" : below normal operational range (SAE J1843)
	0	Accelerator pedal position sensor "B" : above normal operational range (SAE J1843)
	8	Accelerator pedal position sensor "B" : communication fault
	15	Accelerator pedal position sensor "B" : not available (SAE J1843)
	4	Barometric pressure sensor : shorted to low source
108	3	Barometric pressure sensor : shorted to high source
-	2	Barometric pressure sensor : intermittent fault
	4	E-ECU internal temperature sensor : shorted to low source
1100	3	E-ECU internal temperature sensor : shorted to high source
1136	2	E-ECU internal temperature sensor : intermittent fault
	0	E-ECU internal temperature : too high
	4	Engine coolant temperature sensor : shorted to low source
110	3	Engine coolant temperature sensor : shorted to high source
110	2	Engine coolant temperature sensor : intermittent fault
	0	Engine coolant temperature : too high
	4	Sensor 5V : shorted to low source
1079	3	Sensor 5V : shorted to high source
	2	Sensor 5V : intermittent fault
158	1	E-ECU system voltage : too low
150	0	E-ECU system voltage : too high
1078	4	Engine fuel injection pump speed sensor : shorted to low source
522402	4	Auxiliary speed sensor : shorted to low source
	4	Engine fuel rack actuator relay : open circuit
522241	3	Engine fuel rack actuator relay : short circuit
	7	Engine fuel rack actuator relay : mechanical malfunction
	2	Engine fuel rack actuator relay : intermittent fault
	4	Air heater relay : open circuit
522243	3	Air heater relay : short circuit
	2	Air heater relay : intermittent fault

Fault code		Description	
YANMAR SPN	FMI	Description	
	4	Cold start device : open circuit	
522242	3	Cold start device : short circuit	
-	2	Cold start device : intermittent fault	
500054	4	EGR stepping motor "A" : open circuit	
522251	3	EGR stepping motor "A" : short circuit	
500050	4	EGR stepping motor "B" : open circuit	
522252	3	EGR stepping motor "B" : short circuit	
500050	4	EGR stepping motor "C" : open circuit	
522253	3	EGR stepping motor "C" : short circuit	
500054	4	EGR stepping motor "D" : open circuit	
522254	3	EGR stepping motor "D" : short circuit	
100	4	Oil pressure switch : shorted to low source	
100	1	Oil pressure : too low	
167	4	Battery charge switch : shorted to low source	
107	1	Battery charge : charge warning	
522314	0	Engine coolant temperature : abnormal temperature	
522323	0	Air cleaner : mechanical malfunction	
522329	0	Oily water separator : mechanical malfunction	
190	0	Engine speed : over speed condition	
	4	Engine fuel rack actuator : shorted to low source	
638	3	Engine fuel rack actuator : shorted to high source	
-	7	Engine fuel rack actuator : mechanical malfunction	
639	12	High speed CAN communication : communication fault	
630	2	E-ECU internal fault : EEPROM check sum error (data set 2)	
030	12	E-ECU internal fault : EEPROM error	
	12	E-ECU internal fault : flashROM check sum error (main software)	
628	2	E-ECU internal fault : flashROM check sum error (data set 1)	
	2	E-ECU internal fault : flashROM check sum error (data set 2)	
1485	4	E-ECU main relay : shorted to low source	
522727	12	E-ECU internal fault : cyclic redundancy check of sub-CPU error	
	12	E-ECU internal fault : acknowledgement of sub-CPU error	
	12	E-ECU internal fault : communication with sub-CPU error	
522728	12	E-ECU internal fault : engine map data version error	
522730	12	Immobilizer : CAN communication fault	
522130	8	Immobilizer : pulse communication fault	
1202	2	Immobilizer : system fault	



MEMORANDUM

1. POWER CIRCUIT

The negative terminal of battery is grounded to the machine chassis.

When the start switch is in the OFF position, the current flows from the positive battery terminal as shown below.

1) OPERATING FLOW

Battery — Battery relay — Fusible link (CN-60) — I/conn [CN-3 (2)] — Master switch [CS-74]

Fuse box [No.1] - Start switch [CS-2 (1)]
 Fuse box [No.2] - MP3 & Radio player [CN-27 (8)]
 Cluster [CN-56 (9)]
 Fuse box [No.3] - I/conn [CN-2 (5)] - AC & Heater controller
 I/conn [CN-6 (3)] - Room lamp [CL-1 (2)]
 12V socket [CN-139 (2)]
 Fuse box [No.4] - I/conn [CN-2 (7)] - DC motor controller [CN-51 (10)]
 I/conn [CN-2 (6)] - DC motor controller [CN-51 (20)]

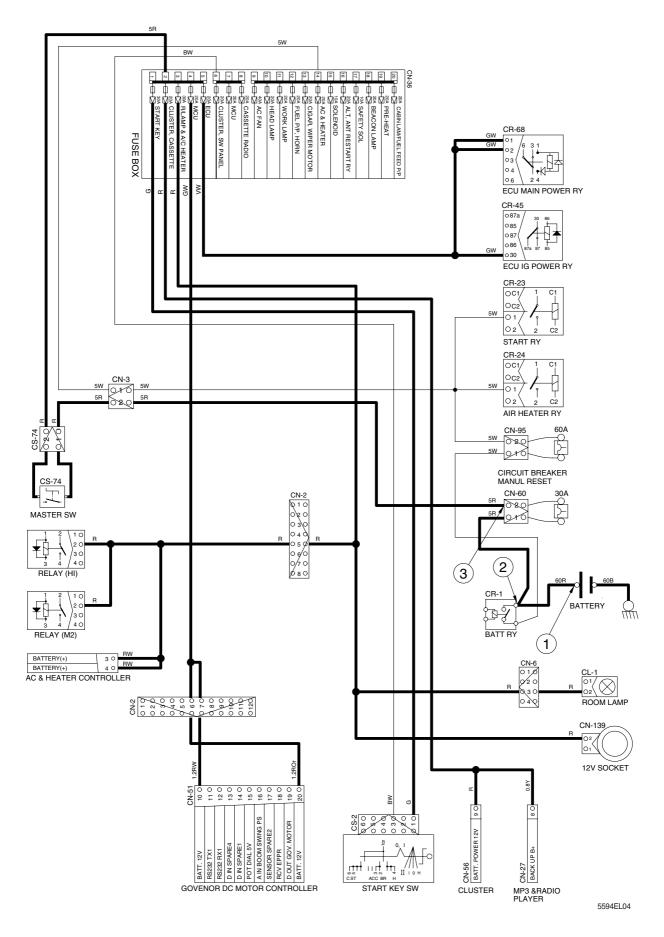
* I/conn : Intermediate connector

2) CHECK POINT

Engine	Start switch	Check point	Voltage
		① - GND (battery)	
OFF	OFF	② - GND (battery relay)	10~12.5V
		③ - GND (fusible link)	

* GND : Ground

POWER CIRCUIT



2. STARTING CIRCUIT

1) OPERATING FLOW

Battery (+) terminal — Battery relay [CR-1] — Fusible link [CN-60] — I/conn [CN-3 (2)] — Master switch [CS-74] — Fuse box No.1 — Start key [CS-2 (1)]

* Start switch : ON

Start switch ON [CS-2 (2)]
 ECU IG power relay [CR-45 (86)]
 I/conn [CN-5 (9)]
 Battery relay [CR-1]:Battery relay operating (all power is supplied with the electric component)
 Start switch ON [CS-2 (3)]
 Fuse box (all power is supplied with electric component)

* Start switch : START

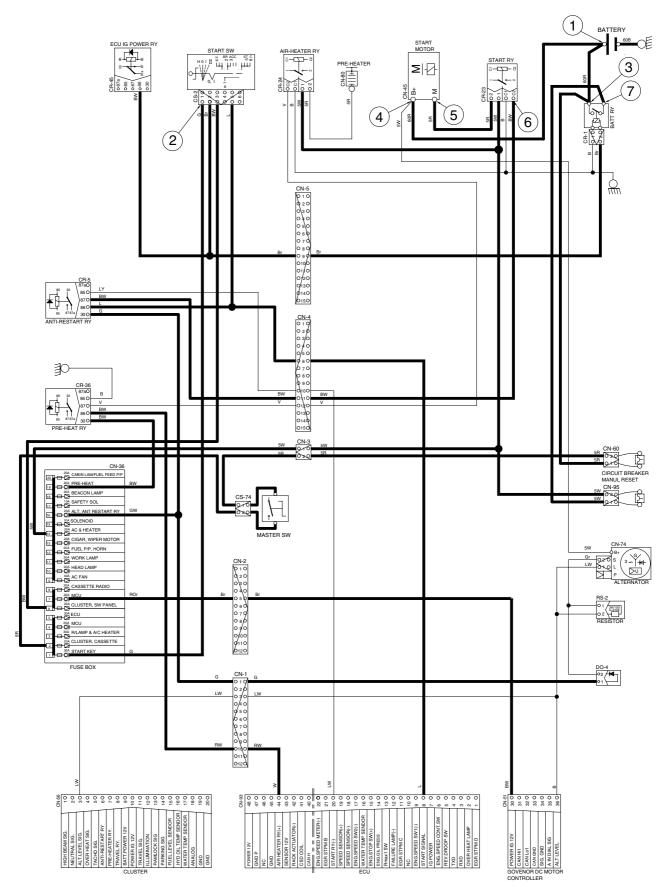
```
Start switch START [CS-2 (5)] \rightarrow Anti-restart relay [CR-5 (86) \rightarrow (87)] \rightarrow I/conn [CN-4 (11)]
\rightarrow Start relay [CR-23 (C2) \rightarrow (2)] \rightarrow Starter motor operating
I/conn [CN-4 (6)] \rightarrow ECU [CN-93 (8)]
```

2) CHECK POINT

Engine	Start switch	Check point	Voltage
		① - GND (battery)	
		② - GND (start key)	
		③ - GND (battery relay M4)	
Operating	Start	④ - GND (starter B ⁺)	10~12.5V
		5 - GND (starter M)	
		⑥ - GND (start relay)	
		⑦ - GND (battery relay M8)	

 \ast GND : Ground

STARTING CIRCUIT



3. CHARGING CIRCUIT

When the starter is activated and the engine is started, the operator releases the key switch to the ON position.

Charging current generated by operating alternator flows into the battery through the Battery relay (CR-1).

The current also flows from alternator to each electrical component and controller through the fuse box.

1) OPERATING FLOW

(1) Warning flow

Alternator "L" terminal ____ I/conn [CN-1 (3)] -- Cluster [CN-56 (3)] -- Cluster warning lamp Governor DC motor controller [CN-51 (36)]

(2) Charging flow

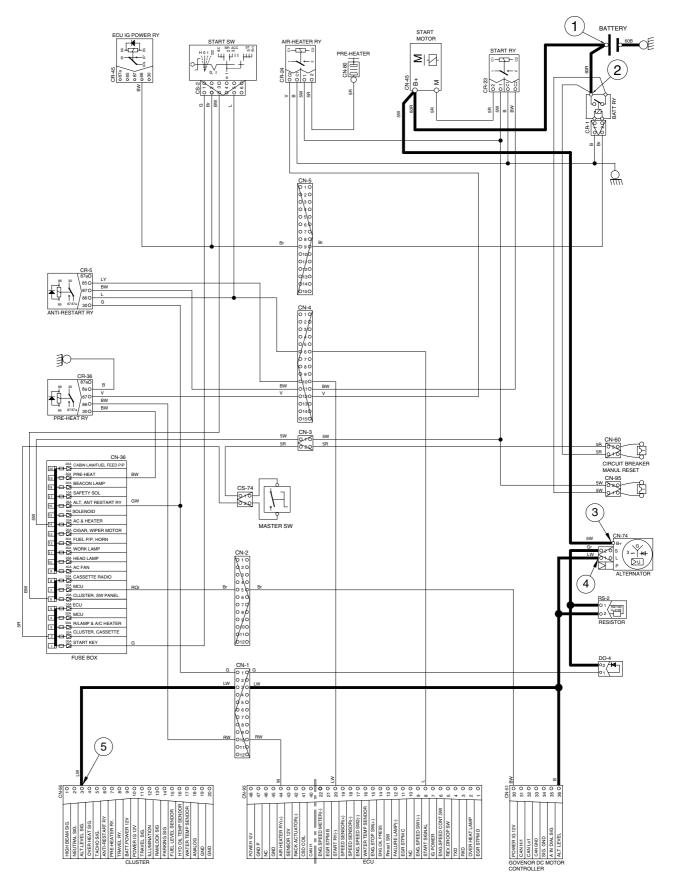
Alternator "B+" terminal — Battery relay — Battery (+) terminal

2) CHECK POINT

Engine	Start switch	Check point	Voltage
		① - GND (battery voltage)	
		② - GND (battery relay)	
Operating	Start	③ - GND (alternator B ⁺ terminal)	10~12.5V
		④ - GND (alternator L terminal)	
		5 - GND (cluster)	

* GND : Ground

CHARGING CIRCUIT



4. HEAD AND WORK LAMP CIRCUIT

1) OPERATING FLOW

Fuse box (No.10) \longrightarrow Head lamp relay [CR-13 (86) \rightarrow (85)] \longrightarrow Switch panel [CN-116 (1)] Fuse box (No.11) \longrightarrow Work lamp relay [CR-3 (86) \rightarrow (85)] \longrightarrow Switch panel [CN-116 (21)]

(1) Head lamp switch ON

Head lamp switch ON [CN-116(1)] \longrightarrow Head lamp relay [CR-13 (85) \rightarrow (87)]

- → I/conn [CN-4 (2)] → Head lamp ON [CL-3, 4 (2)]
- → I/conn [CN-5 (1)] → I/conn [CN-7 (11)] → Cigar lighter [CL-2 (1)]
- → Remote controller illumination ON [CN-245 (9)]
- → MP3 & Radio player illumination ON [CN-27 (9)]
- -- USB & Socket illumination ON [CN-246 (7)
- -- Cluster illumination ON [CN-56 (12)]
- └- I/conn [CN-2 (8)] AC/Heater controller illumination ON

(2) Work lamp switch ON

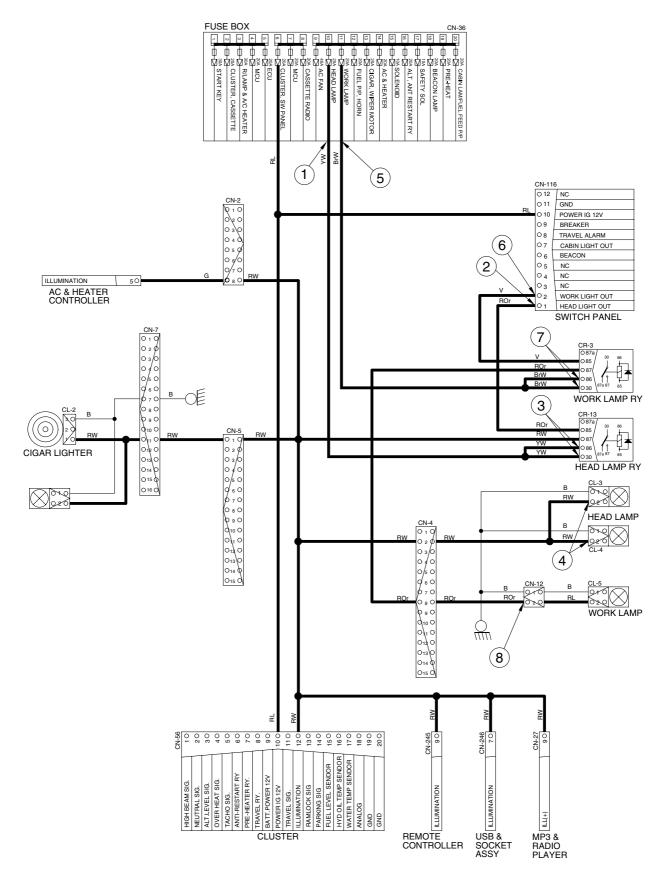
Work light switch ON [CN-116 (2)] \rightarrow Work lamp [CR-3 (85) \rightarrow (87)] \rightarrow I/conn [CN-4 (8)] I/conn [CN-12 (2)] \rightarrow Work lamp ON [CL-5 (2)]

2) CHECK POINT

Engine	Start switch	Check point	Voltage
	ON	① - GND (fuse box)	
STOP		② - GND (switch power input)	10~12.5V
510P		③ - GND (switch power output)	10~12.5V
		④ - GND (head light)	
STOP	ON	⑤ - GND (fuse box)	
		6 - GND (switch power input)	10~12.5V
		⑦- GND (switch power output)	10~12.5V
		⑧ - GND (work light)	

* GND : Ground

HEAD AND WORK LAMP CIRCUIT



5. BEACON LAMP AND CAB LAMP CIRCUIT

1) OPERATING FLOW

Fuse box (No.18) \longrightarrow Beacon lamp relay [CR-85(30) \rightarrow (85)] \longrightarrow Switch panel [CN-116 (6)] Fuse box (No.20) \longrightarrow Cab lamp relay [CR-9 (30) \rightarrow (85)] \longrightarrow Switch panel [CN-116 (7)]

(1) Beacon lamp switch ON

Beacon lamp switch ON [CN-116 (6)] -- Beacon lamp relay [CR-85 (87)] -- I/conn [CN-6 (1)] -- Beacon lamp ON [CL-7]

(2) Cab lamp switch ON

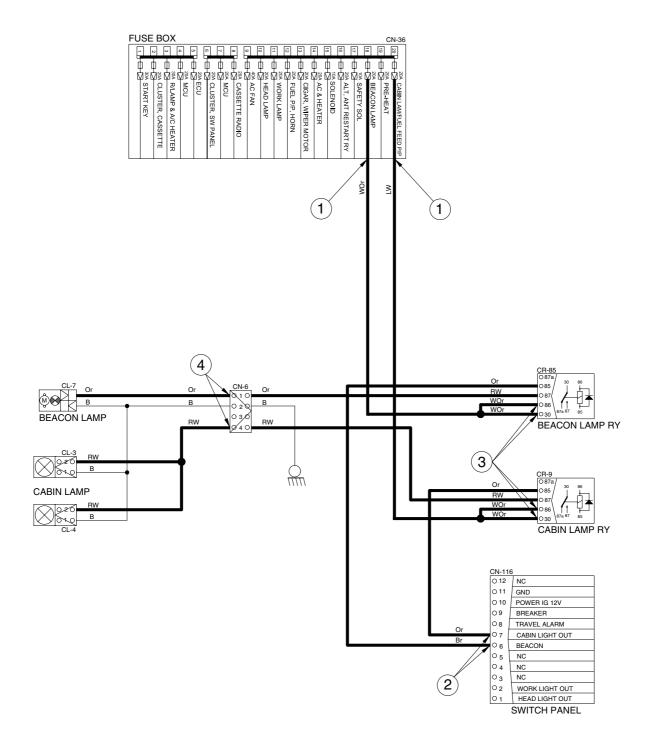
Cab lamp switch ON [CN-116 (7)] → Cab lamp relay [CR-9 (87)] → I/conn [CN-6 (4)] → Cab lamp ON [CL-3, 4]

2) CHECK POINT

Engine	Start switch	Check point	Voltage
STOP	TOP ON	① - GND (fuse box)	
		② - GND (switch power input)	10~12.5V
		③ - GND (switch power output)	10~12.5V
		④ - GND (beacon & cab lamp)	

* GND : Ground

BEACON LAMP CIRCUIT



6. WIPER AND WASHER CIRCUIT

1) OPERATING FLOW

(1) Key switch ON

Fuse box (No.13) Wiper relay [CR-4 (86)]

- → Int wiper relay [CR-6 (4)]
- → Wiper switch [CS-3 (11)]
- Wiper motor [CN-21 (3)]
- → I/conn [CN-5 (11)] → Washer pump [CN-22 (2)]

(2) Wipe switch ON : 1st step (low speed)

Wiper switch ON [CS-3 (8) \rightarrow (7)] — Int wiper relay [CR-6 (6) \rightarrow (3)] — Wiper relay [CR-4 (85) \rightarrow (30)] — Washer motor operating [CN-21 (4)]

(3) Wiper switch ON : 2nd step (washer)

Wiper switch ON [CS-3 (7)] -- Int wiper relay [CR-6 (1)] -- Washer switch [CS-30 (6)]

→ Wiper relay [CR-4 (85) \rightarrow (30)]

--- Wiper motor operating[CN-21(1)]

Washer switch ON [CS-30 (6)] - I/conn [CN-5 (3)] - Washer pump operating [CN-22 (1)]

(4) Auto parking (when switch OFF)

Switch OFF -- Wiper motor [CN-21 (1)] -- Wiper switch [CS-3 (5) \rightarrow (8)] -- Int wiper relay [CR-6 (6) \rightarrow (3)]

→ Wiper relay [CR-4 (85) \rightarrow (30)] → Wiper motor [CN-21 (4)]

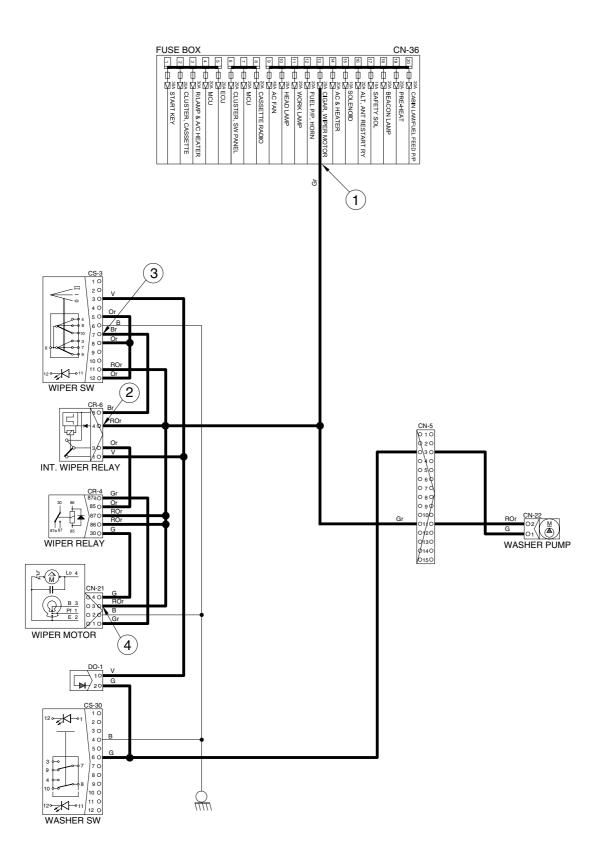
--- Wiper motor parking position by wiper motor controller

2) CHECK POINT

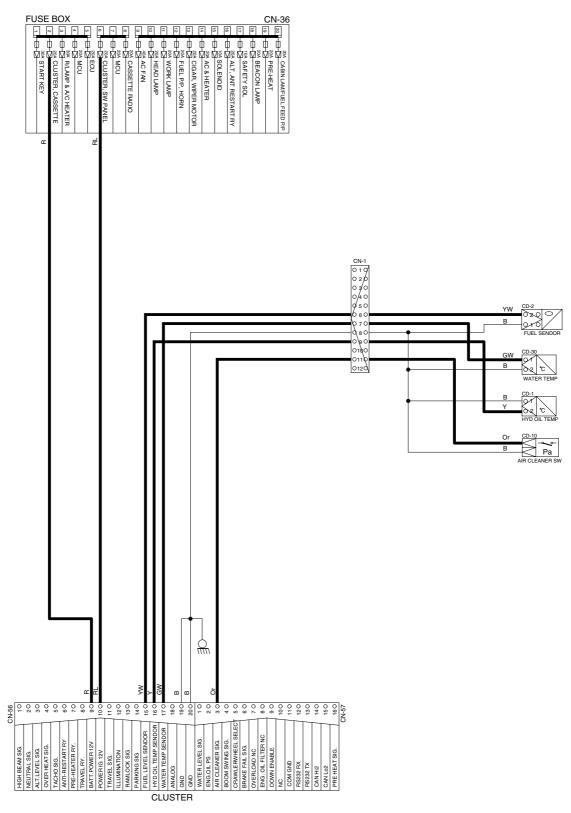
Engine	Start switch	Check point	Voltage
STOP	STOP ON	① - GND (fuse box)	
		② - GND (switch power input)	10~12.5V
		③ - GND (switch power output)	10~12.5V
		④ - GND (wiper motor)	

* GND : Ground

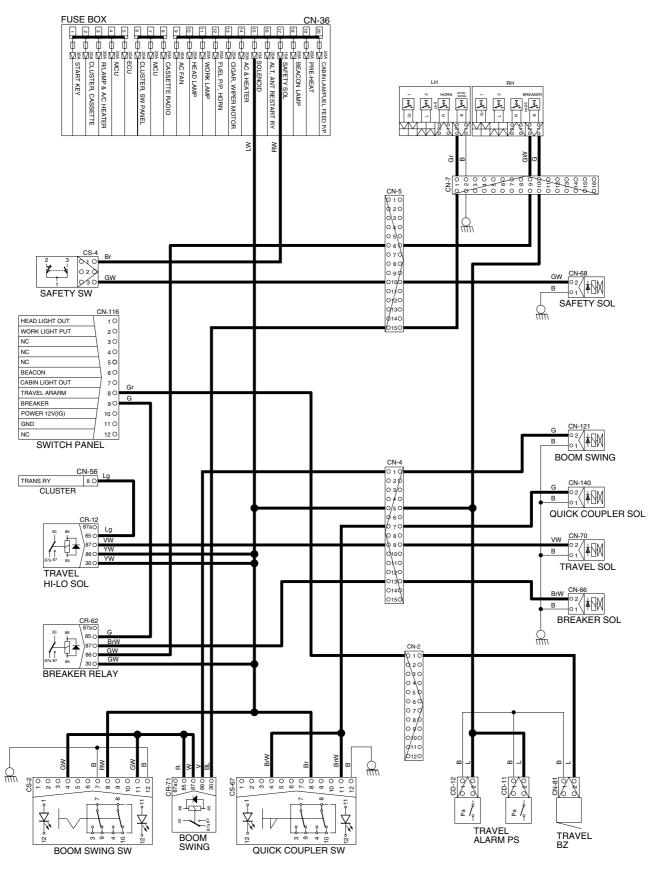
WIPER AND WASHER CIRCUIT



MONITORING CIRCUIT



ELECTRIC CIRCUIT FOR HYDRAULIC



GROUP 4 ELECTRICAL COMPONENT SPECIFICATION

Part name	Symbol	Specification	Check		
Battery		12V × 100Ah	 Check specific gravity 1.280 over : over charged 1.280 ~ 1.250 : normal 1.250 below : recharging 		
Battery relay	CR-1	Rated load : 12V 100A (continuity) 1000A (30 second)	Normal: about 12 0		
Start key		12V	* Check contact OFF : $\infty \Omega$ (for each terminal) ON : 0Ω (for terminal 1-3 and 1-2) START : 0Ω (for terminal 1-5)		
Pressure switch (for engine oil)	Pa 	0.5 kgf/cm ² (N.C TYPE)	 % Check resistance Normal : 0 Ω (CLOSE) 		
Temperature sensor	CD-8	0.5 kgf/cm ² (N.C TYPE)	 * Check resistance 50°C : 804 Ω 80°C : 310 Ω 100°C : 180 Ω 		

Part name	Symbol	Specification	Check
Air cleaner pressure switch	Pa CD-10	Pressure: 635mmH₂O (N.O TYPE)	* Check contact Normal : ∞ Ω
Fuel sender	CD-2	-	 Check resistance Full : 100 Ω Low : 500 Ω Empty warning :700 Ω
Relay	CR-2 CR-3 CR-4 CR-5 CR-7 CR-9 CR-12 CR-13 CR33 CR-36 CR-62 CR-85	12V 20A	 Check resistance Normal : about 200 Ω (for terminal 85-86) : 0 Ω (for terminal 30-87a) : ∞ Ω (for terminal 30-87)
Relay	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	12V 60A	* Rated coil current 1.2±0.3A
Solenoid valve	$ \begin{array}{c c} 2 \\ 0 1 \end{array} $ CN-66 CN-68 CN-70 CN-140	12V 1A	 * Check resistance Normal : 15~25 Ω (for terminal 1-2)
Speaker	0 2 0 1 CN-23(LH) CN-24(RH)	4 Ω 20W	* Check resistance Normal : 4 Ω

Part name	Symbol	Specification	Check
Boom swing switch	CS-5	12V 16A	* Check contact Normal OFF - ∞ Ω (for terminal 1-5,2-6) - 0 Ω (for terminal 5-7,6-8)
Quick clamp switch	CS-67	12V 16A	 * Check contact Normal OFF - ∞ Ω (for terminal 1-5,2-6) - 0 Ω (for terminal 5-7,6-8)
Lamp	CL-3 CL-4 CL-5	12V 55W (H3 TYPE)	* Check disconnection Normal : 1.2 Ω
Room lamp	□ 1 0 2 0 CL-1	12V 10W	 % Check disconnection Normal : a few Ω
Fuel filler pump	010 M 2 CN-145	12V 35 <i>l</i> /min	* Check operation Supply power (for terminal 1) : 12V
Horn	CN-20 CN-25	12V	100±5dB

Part name	Symbol	Specification	Check
Safety switch	2 3 0 1 0 2 3 0 2 0 1 3 0 CS-4	Micro	** Check contact Normal : 0Ω (for terminal A-B) : $\infty \Omega$ (for terminal A-C) Operating : $\infty \Omega$ (for terminal A-B) : 0Ω (for terminal A-C)
Pressure switch	O 2 O 1 Pa CD-7 CD-11 CD-12	10bar (N.C type)	* Check contact Normal : 0.1 Ω
Beacon lamp	CL-7	12V (Strobe type)	* Check disconnection Normal : a few Ω
Wiper switch		12V 16A	* Check contact Normal : ∞ Ω
Fuel cut-off	H A C F B B E C C CN-79	12V	 * Check operation Rated full current : 12V 33A Rated hold current : 12V 0.8A
Washer pump	M 20 10 CN-22	12V 3.8A	* Check contact Normal : 3 Ω (for terminal 1-2)

Part name	Symbol	Specification	Check
Cigar lighter	CL-2	12V 10A 1.4W	 * Check coil resistance Normal : about 1MΩ * Check contact Normal : ∞ Ω Operating time : 5~15sec
Wiper motor	$ \begin{array}{c} 4 \\ 6 \\ 4 \\ 3 \\ 2 \\ 0 \\ 1 \\ \hline \end{array} $ $ \begin{array}{c} 4 \\ 4 \\ \hline \end{array} $ $ \begin{array}{c} 4 \\ 4 \\ \hline \end{array} $ $ \begin{array}{c} 4 \\ 3 \\ 1 \\ 2 \\ \hline \end{array} $ $ \begin{array}{c} 3 \\ 1 \\ 2 \\ 2 \\ \hline \end{array} $ $ \begin{array}{c} 3 \\ 1 \\ 2 \\ 2 \\ \hline \end{array} $ $ \begin{array}{c} 3 \\ 1 \\ 2 \\ 2 \\ \hline \end{array} $ $ \begin{array}{c} 3 \\ 2 \\ 2 \\ \hline \end{array} $ $ \begin{array}{c} 3 \\ 2 \\ 2 \\ \end{array} $ $ \begin{array}{c} 3 \\ 2 \\ \end{array} $ $ \begin{array}{c} 3 \\ 2 \\ \end{array} $ $ \begin{array}{c} 3 \\ \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $ $ \begin{array}{c} \end{array} $ $ \end{array} $	12V 3A	* Check contact Normal : 6 Ω (for terminal 2-6)
Radio & CD/MP3 player	CN-22	24V 2A	 Check voltage 20 ~ 25V (for terminal 1-3, 3-8)
Receiver dryer	O 2 O 1 CN-29	12V	* Check contact Normal : 0 Ω
Starter	M B+ M M CN-45	12V	 % Check contact Normal : 0.1 Ω
Alternator	$ \begin{array}{c} B_{+} \\ G_{-} \\ S_{-} \\ B_{+} \\ S_{-} \\ D_{-} \\ D_{$	12V 55A	 Check contact Normal : 0 Ω (for terminal B⁺-1) Normal : 24 ~ 27.5V

Part name	Symbol	Specification	Check
Travel buzzer	CN-81	12V	-
Compressor	CN-28	12V 38W	-
Air con fan motor	0 1 0 <u>M</u> 0 2 0 0 CN-83	12V 8.5A	-
Fuel feed pump	M 2 CN-145	12V	-
Master switch		12V 1000A	-
Timer	IG 4 OUT 1 0 2 0 30 GND3 OUT 4 0	12V	-

Part name	Symbol	Specification	Check
Preheater	CN-80	12V 42A 500W	-
12V socket	CN-139	12V 120W	-
Duct sensor		1°C OFF 4°C ON	 Check resistance Normal : 0 Ω (for terminal 1-2) the atmosphere temp : over 4°C
Accel dial	A + B S CQ -	-	 * Check resistance Normal : about 5k Ω (for terminal A-C) * Check voltage Normal : about 5V (for terminal A-C)
Int wiper relay	CR-6	12V 12A	-
Circuit breaker manual reset	CN-60 CN-95	12V, 30A (CN-65) 12V, 60A (CN-95)	-

GROUP 5 CONNECTORS

1. CONNECTOR DESTINATION

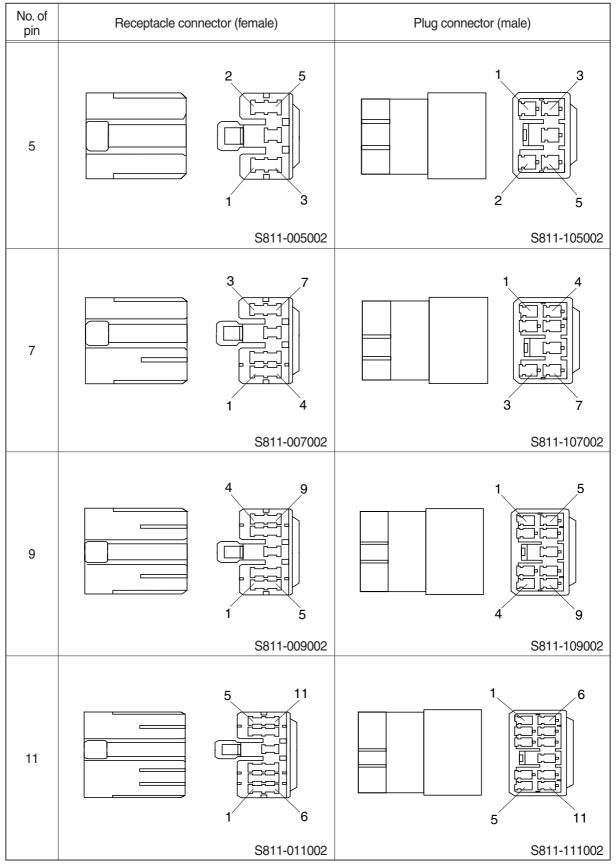
Connector	Туре	No. of	Destination	Connecto	or part No.
number	туре	pin	Destination	Female	Male
CN-1	AMP	12	Cabin room harness - Main harness	S816-012002	S816-112002
CN-2	AMP	12	Aircon harness - Cabin room harness	S816-012002	S816-112002
CN-3	YAZAKI	2	Fusible link - Fuse box	S813-030201	S813-130201
CN-4	AMP	15	Cabin room harness - Main harness	2-85262-1	368301-1
CN-5	AMP	15	Cabin room harness - Main harness	2-85262-1	368301-1
CN-6	DEUTSCH	4	Cabin harness - Cabin room lamp harness	DT06-4S-EP06	DT04-4P-E005
CN-7	AMP	10	Console harness - Main harness	S816-010002	S816-110002
CN-12	AMP	2	Boom harness - Work lamp harness	S816-002002	S816-102002
CN-20	DEUTSCH	2	Horn	DT06-2S-EP06	-
CN-21	AMP	4	Wiper harness	180900-0	-
CN-22	KET	2	Washer tank	MG640605	-
CN-23	MOLEX	2	Speaker LH	MG610070	-
CN-24	MOLEX	2	Speaker RH	MG610070	-
CN-25	DEUTSCH	2	Horn	DT06-2S-EP06	-
CN-27	-	16	Cassette radio	PK145-16017	-
CN-28	AMP	1	Air-con comp	S810-001202	-
CN-29	KET	2	Receiver dryer	MG640795	-
CN-36	-	-	Fuse box	21L7-00250	-
CN-45	TERM	1	Starter	ST710246-2	-
CN-48	AMP	40	MCU	DRC26-40SA	-
CN-51	AMP	3	Hour meter	S816-003002	S816-103002
CN-55	AMP	2	Travel alarm PS	S816-002002	S816-102002
CN-56	AMP	12	Cluster	175967-2	-
CN-57	AMP	16	Cluster	175966-2	-
CN-60	YAZAKI	2	Fusible link	-	7122-4125-50
CN-61	TERM	1	Fuel filler pump	S822-014000	S822-114000
CN-66	DEUTSCH	2	Breaker solenoid	DT06-2S-EP06	-
CN-68	DEUTSCH	2	Safety solenoid	DT06-2S-EP06	-
CN-70	DEUTSCH	2	Travel HI-LO solenoid	DT06-2S-EP06	-
CN-74	KET	2	Alternator	ST710285-2	-
CN-76	KET	6	DC motor	MG640515-4	-
CN-79	YAZAKI	3	Fuel cut-off solenoid	S813-060300	-
CN-80	AMP	1	Pre heater	ST710384-2	-

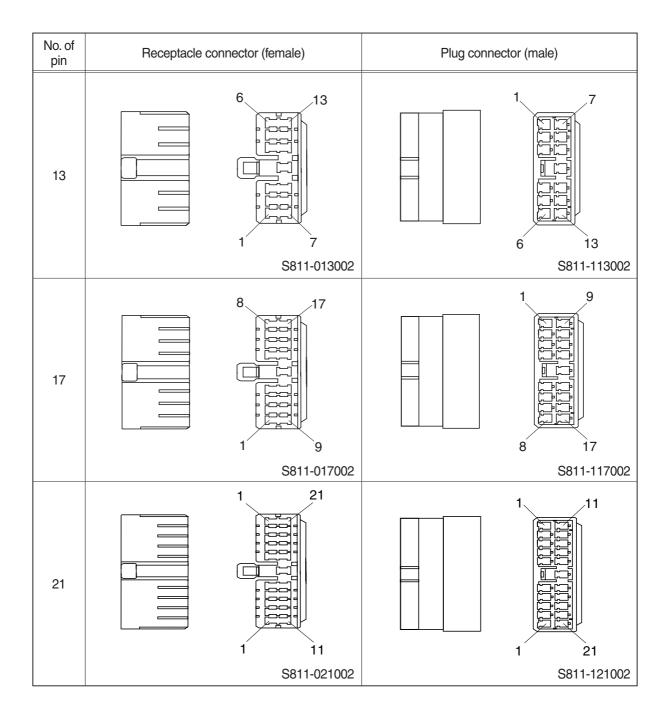
Connector Type		No. of	Liestination	Connector part No.		
number	pin	Destination	Female	Male		
CN-81	DEUTSCH	2	Travel buzzer	DT06-2S-EP06	DT04-2P-E005	
CN-83	AMP	2	Air-con fan	MG640188-5	-	
CN-92	KET	1	Anti-restart relay	S814-001100	-	
CN-95	YAZAKI	2	Fusible link	-	S813-130201	
CN-116	AMP	12	Switch panel	368542-1	-	
CN-139	AMP	2	12V socket	S810-002202	-	
CN-140	DEUTSCH	2	Quick coupler	DT06-2S-EP06	DT04-2P-E005	
CN-142	DEUTSCH	3	Accel dial	DT06-3S-EP06	-	
CN-144	KET	20	Handfree	MG610240	-	
CN-145	KET	2	Fuel feed pump	7123-6423-30	-	
CN-170	AMP	2	Seat heat switch	12162017	-	
CN-245	AMP	12	Remote controller assy	368542-1	-	
CN-246	AMP	12	USB & Socket assy	174045-2	-	
CN-258	KET	1	Aircon comp power	MG640944-5	MG650943-5	
CN-263	DEUTSCH	2	Aircon comp relay	DT06-2S-EP06	DT04-2P-E005	
· LAMP		1		1	1	
CL-1	KET	2	Room lamp	MG610392	-	
CL-2	AMP	3	Cigar light	S810-003202	-	
CL-3	DEUTSCH	2	Head lamp	DT06-2S-EP06	DT04-2P-E005	
CL-4	DEUTSCH	2	Head lamp	DT06-2S-EP06	DT04-2P-E005	
CL-5	DEUTSCH	2	Work lamp	180923-0	-	
CL-7	-	1	Beacon lamp	-	S822-114000	
CL-9	DEUTSCH	1	Cabin lamp	DT06-2S-EP06	-	
CL-10	DEUTSCH	1	Cabin lamp	DT06-2S-EP06	-	
· RELAY						
CR-1	AMP	2	Battery relay	S816-002002	S816-102002	
CR-2	AMP	4	Horn relay	S810-004002	-	
CR-5	AMP	4	Anti-restart relay	S810-004002	-	
CR-6	AMP	6	Int wiper relay	S810-006002	-	
CR-12	AMP	4	Travel relay	S810-004002	-	
CR-23	KET	2	Start relay	S814-002001	-	
CR-24	KET	2	Air heater relay	S814-002001	-	
CR-33	AMP	4	Air-con fan relay	S810-004002	-	
CR-36	AMP	4	Pre-heater relay	S810-004002	-	
CR-47	KET	2	Fuel cut-off relay	S814-002001	-	
CR-50	KET	4	Timer relay	MG610047-5	-	
· SENDEF	3	1		1	1	
CD-1	AMP	2	Hydraulic temp sender	85202-1	-	
CD-2	AMP	2	Fuel sender	-	S816-102002	

Connector	No. of	No. of	Destination	Connector part No.	
number	Туре	pin	Destination	Female	Male
CD-7	DEUTSCH	3	Auto idle pressure switch	DT06-3S-EP06	-
CD-10	KET	1	Air cleaner switch	ST730057-2	-
CD-11	-	2	Travel pressure switch	MG640795	-
CD-12	-	2	Travel pressure switch	MG640795	-
CD-18	AMP	1	Engine oil pressure	ST710345-1	-
CD-30	AMP	2	Water temp	85202-1	-
CD-45	-	2	WIF sensor	-	S816-102003
DO-1	-	2	Diode	21EA-50570	-
DO-2	-	2	Diode	21EA-50570	-
DO-3	-	2	Diode	21EA-50570	-
· SWITCH					
CS-2	KET	6	Start key switch	S814-006000	-
CS-3	SWF	12	Wiper switch	585790	-
CS-4	AMP	3	Safety switch	S816-003002	-
CS-5	-	1	Horn-LH switch	-	DT04-2P-E005
CS-26	DEUTSCH	2	Breaker switch	DT06-2S-EP06	-
CS-67	SWF	10	Quick coupler switch	589790	-
CS-74	YAZAKI	2	Master switch	S813-030201	S813-130201
CS-99	SWF	12	Auto idle switch	589790	-

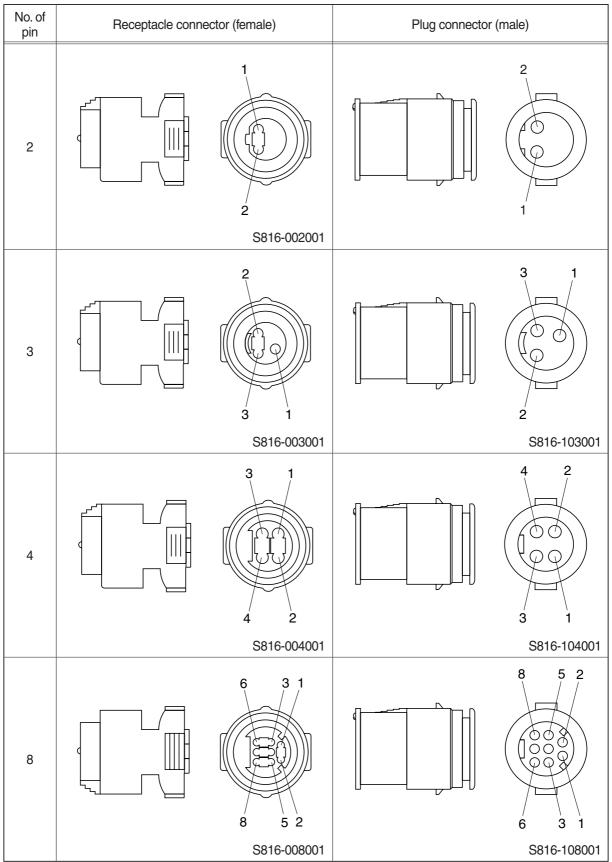
2. CONNECTION TABLE FOR CONNECTORS

1) PA TYPE CONNECTOR

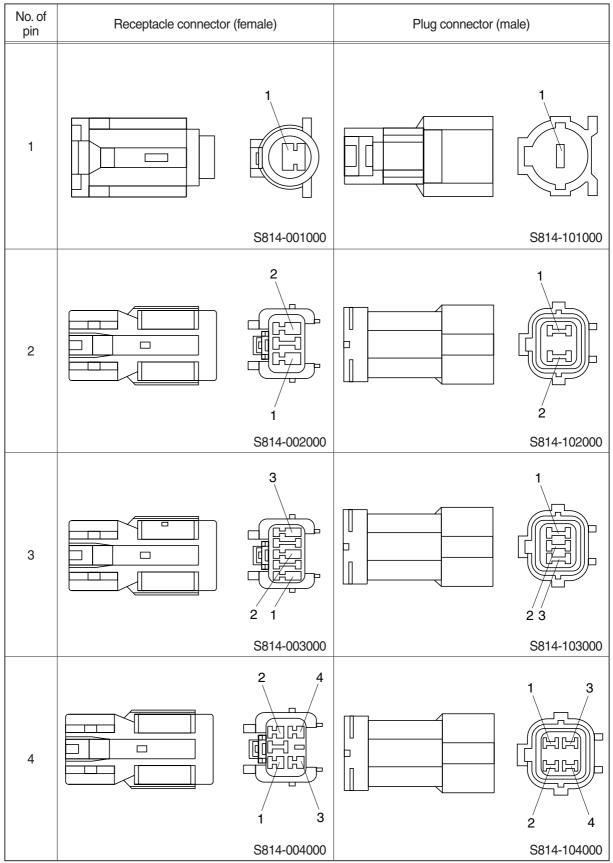


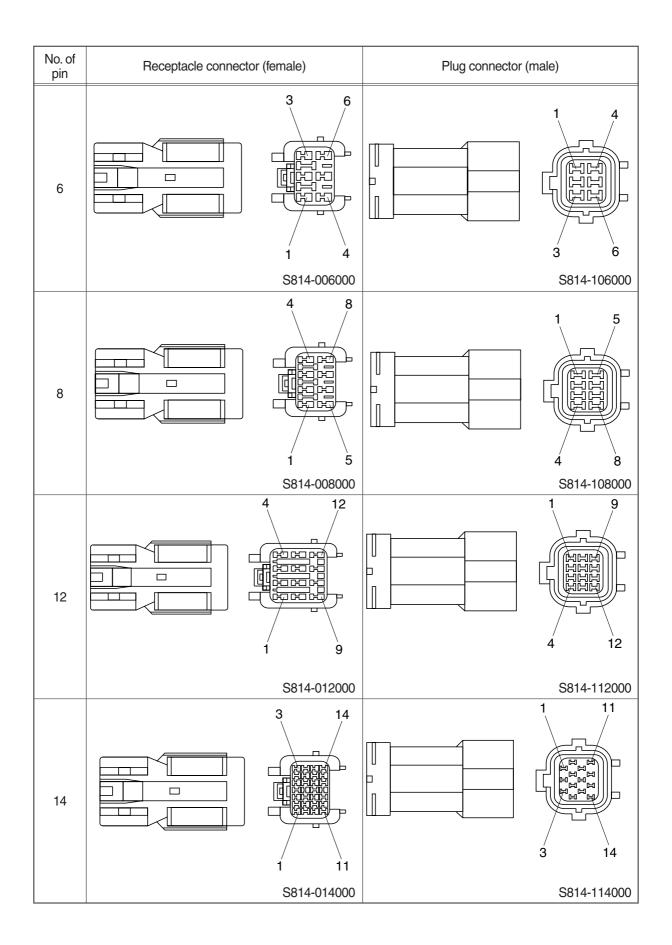


2) J TYPE CONNECTOR

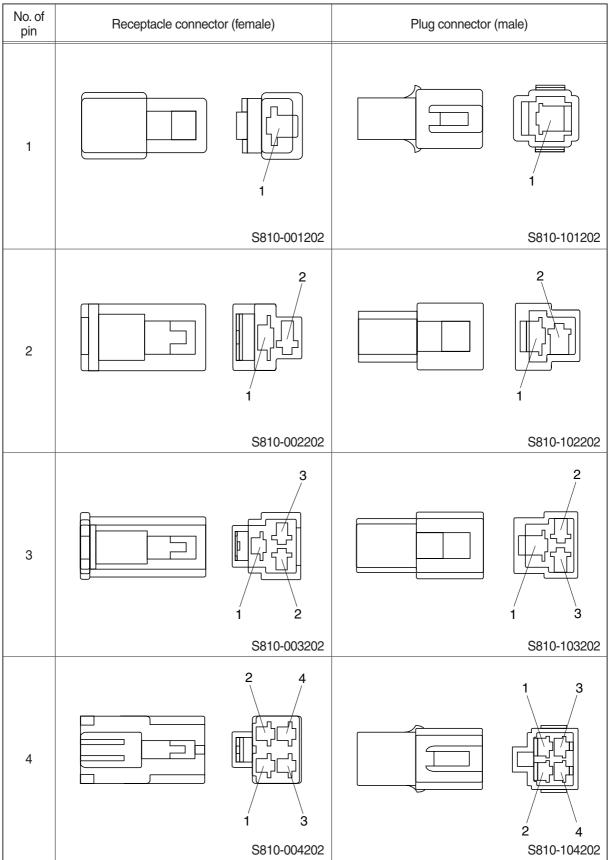


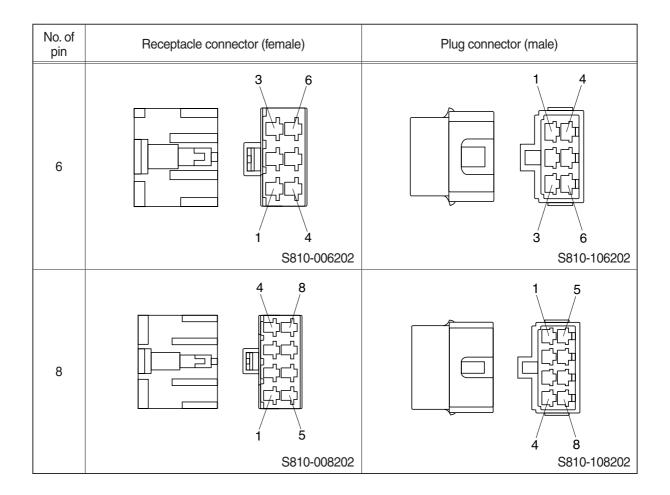
3) SWP TYPE CONNECTOR



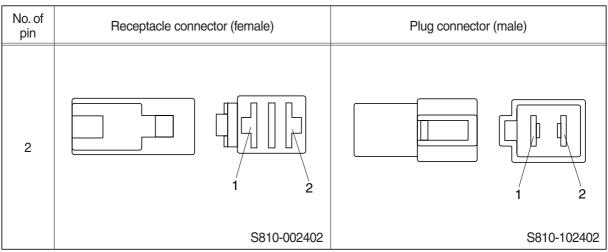


4) CN TYPE CONNECTOR

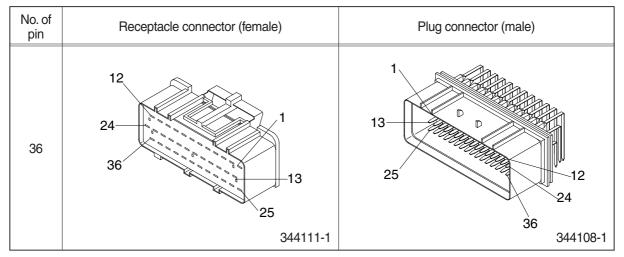




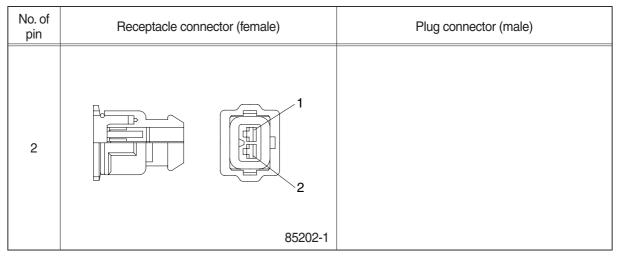
5) 375 FASTEN TYPE CONNECTOR



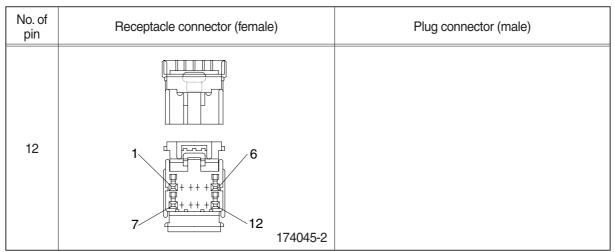
6) AMP ECONOSEAL CONNECTOR



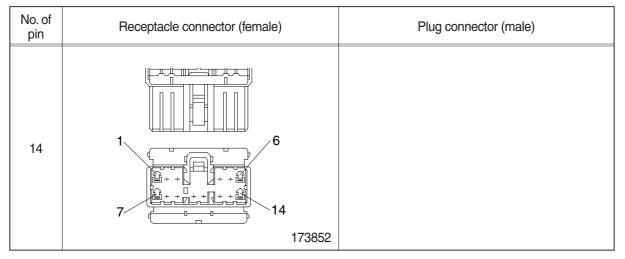
7) AMP TIMER CONNECTOR



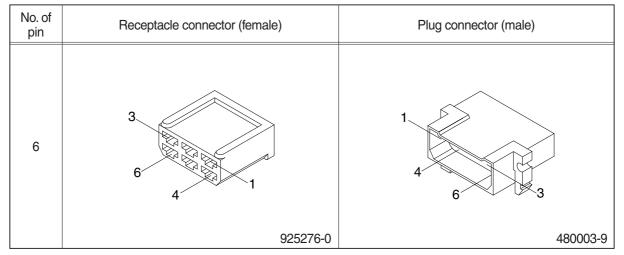
8) AMP 040 MULTILOCK CONNECTOR



9) AMP 070 MULTILOCK CONNECTOR



10) AMP FASTIN - FASTON CONNECTOR



11) KET 090 CONNECTOR

No. of pin	Receptacle connector (female)	Plug connector (male)
6		
	MG610070	

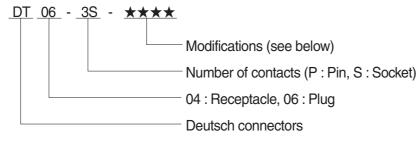
12) KET 090 WP CONNECTORS

No. of pin	Receptacle connector (female)	Plug connector (male)
2	1 2 MG640605	
2	1 2 MG640795	

13) KET SDL CONNECTOR

No. of pin	Receptacle connector (female)	Plug connector (male)
14	1 7 1 1 1 1 1 4 6 MG610406	

14) DEUTSCH DT CONNECTORS



* Modification

E003 : Standard end cap - gray

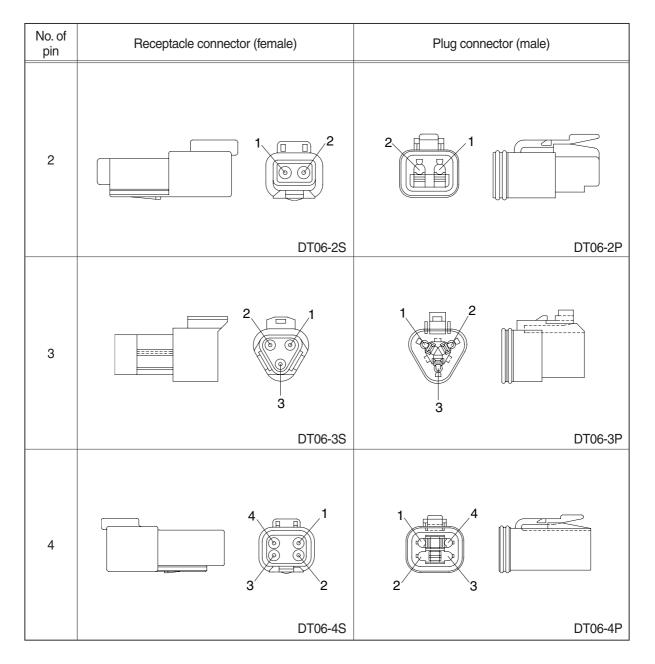
E004 : Color of connector to be black

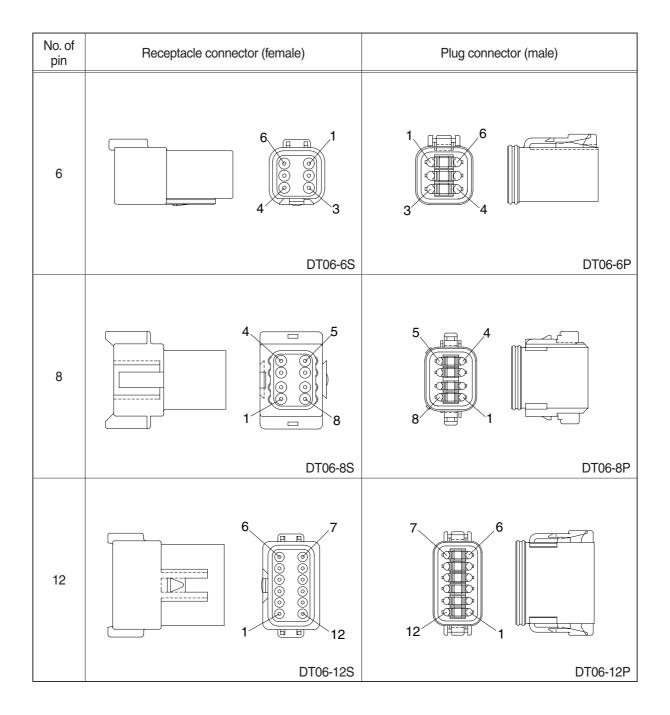
E005 : Combination - E004 & E003

EP04 : End cap

EP06 : Combination P012 & EP04

P012 : Front seal enhancement - connectors color to black for 2, 3, 4 & 6pin

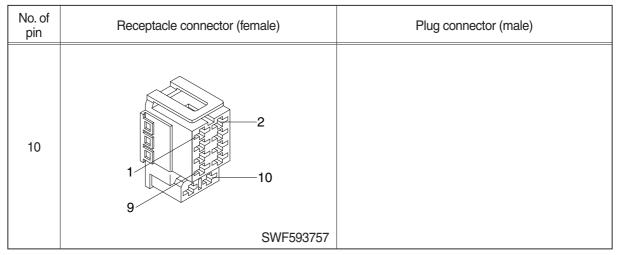




15) MOLEX 2CKTS CONNECTOR

No. of pin	Receptacle connector (female)	Plug connector (male)
2		
	35215-0200	

16) ITT SWF CONNECTOR



17) MWP NMWP CONNECTOR

No. of pin	Receptacle connector (female)	Plug connector (male)
1	1	
	NMWP01F-B	

Group	1 Before Troubleshooting	 5-1
Group	2 Hydraulic and Mechanical System	 5-4
Group	3 Electrical System	 5-24

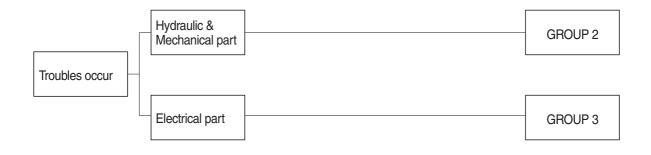
GROUP 1 BEFORE TROUBLESHOOTING

1. INTRODUCTION

When a trouble is occurred in the machine, this section will help an operator to maintain the machine with easy.

The trouble of machine is parted Hydraulic & Mechanical system and Electrical system system.

At each system part, an operator can check the machine according to the troubleshooting process diagram.



2. DIAGNOSING PROCEDURE

To carry out troubleshooting efficiently, the following steps must be observed.

STEP 1. Study the machine system

Study and know how the machine is operating, how the system is composing, what kinds of function are installed in the machine and what are specifications of the system components by the machine service manual.

Especially, deepen the knowledge for the related parts of the trouble.

STEP 2. Ask the operator

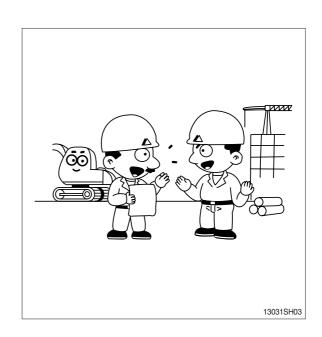
Before inspecting, get the full story of malfunctions from a witness --- the operator.

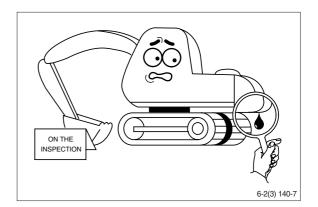
- 1) How the machine is used and when it is serviced?
- 2) When the trouble was noticed and what work the machine was doing at that time?
- 3) What is the phenomenon of the trouble? Was the trouble getting worse, or did it come out suddenly for the first time?
- Did the machine have any troubles previously? If so, which parts were repaired before.

STEP 3. Inspect the machine

Before starting troubleshooting, check the machine for the daily maintenance points as shown in the operator's manual.

And also check the electrical system including batteries, as the troubles in the electrical system such as low battery voltage, loose connections and blown out fuses will result in malfunction of the controllers causing total operational failures of the machine.

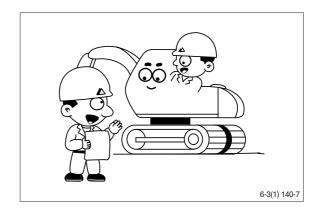




STEP 4. Inspect the trouble actually on the machine

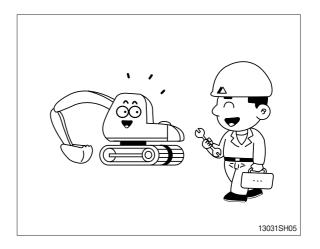
In case that some trouble cannot be confirmed, obtain the details of the malfunction from the operator.

Also, check if there are any in complete connections of the wire harnesses are or not.



STEP 5. Perform troubleshooting

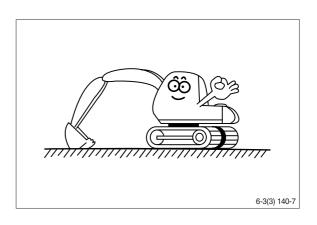
According to where the trouble parts are located, hydraulic & mechanical system part or electrical system part or mechatronics system part, perform troubleshooting the machine refer to the each system part's troubleshooting process diagram.



STEP 6. Trace a cause

Before reaching a conclusion, check the most suspectible causes again. Try to trace what the real cause of the trouble is.

Make a plan of the appropriate repairing procedure to avoid consequential malfunctions.



GROUP 2 HYDRAULIC AND MECHANICAL SYSTEM

1. INTRODUCTION

1) MACHINE IN GENERAL

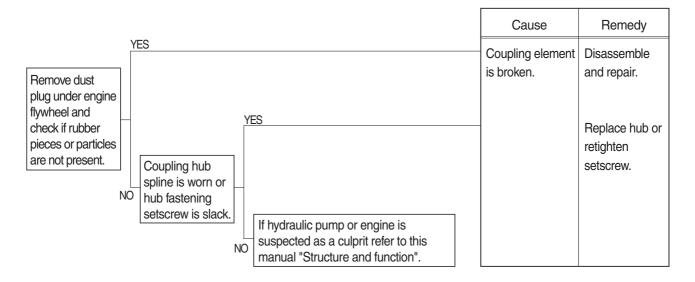
(1) If even a minor fault is left intact and operation is continued, a fatal failure may be caused, entailing a large sum of expenses and long hours of restoration.

Therefore when even a small trouble occurs, do not rely on your intuition and experience, but look for the cause based on the troubleshooting principle and perform maintenance and adjustment to prevent major failure from occurring. Keep in mind that a fault results from a combination of different causes.

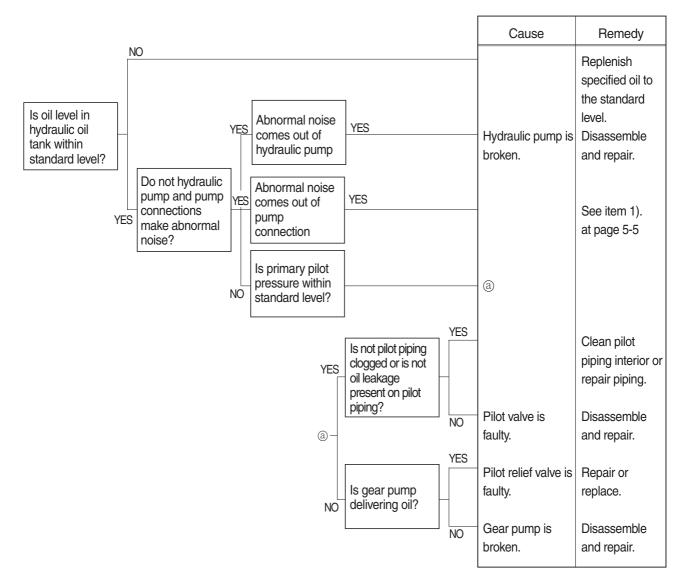
- (2) The following lists up commonly occurring faults and possible causes with this machine. For the troubleshooting of the engine, refer to the coming troubleshooting and repair.
- (3) When carrying out troubleshooting, do not hurry to disassemble the components. It will become impossible to find the cause of the problem.
- (4) Ask user or operator the following.
- ① Was there any strange thing about machine before failure occurred?
- ② Under what conditions did the failure occur?
- ③ Have any repairs been carried out before the failure?
- (5) Check before troubleshooting.
- 0 Check oil and fuel level.
- ② Check for any external leakage of oil from components.
- ③ Check for loose or damage of wiring and connections.

2. DRIVE SYSTEM

1) UNUSUAL NOISE COMES OUT OF PUMP CONNECTION

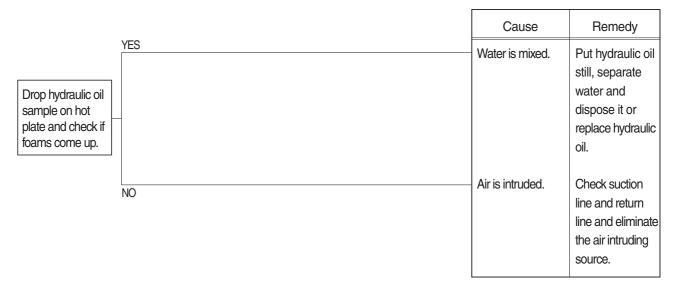


2) ENGINE STARTS BUT MACHINE DOES NOT OPERATE AT ALL

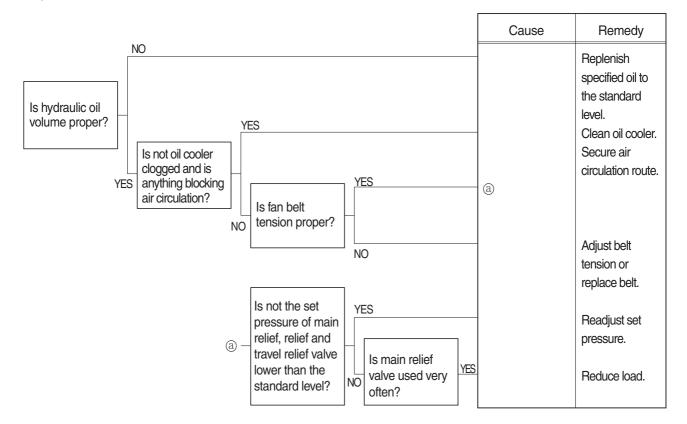


3. HYDRAULIC SYSTEM

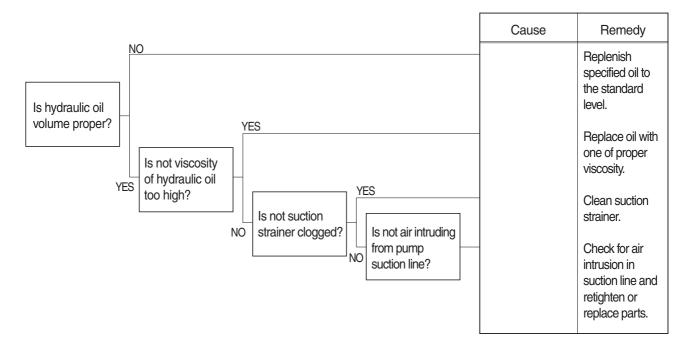
1) HYDRAULIC OIL IS CLOUDY



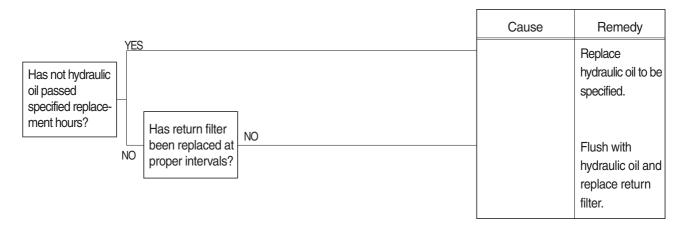
2) HYDRAULIC OIL TEMPERATURE HAS RISEN ABNORMALLY



3) CAVITATION OCCURS WITH PUMP

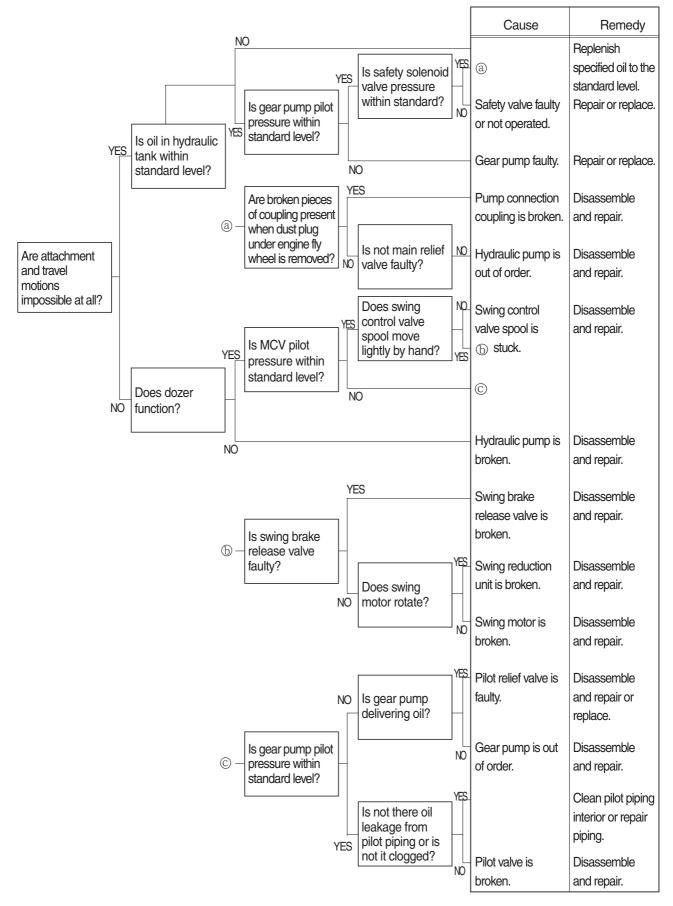


4) HYDRAULIC OIL IS CONTAMINATED

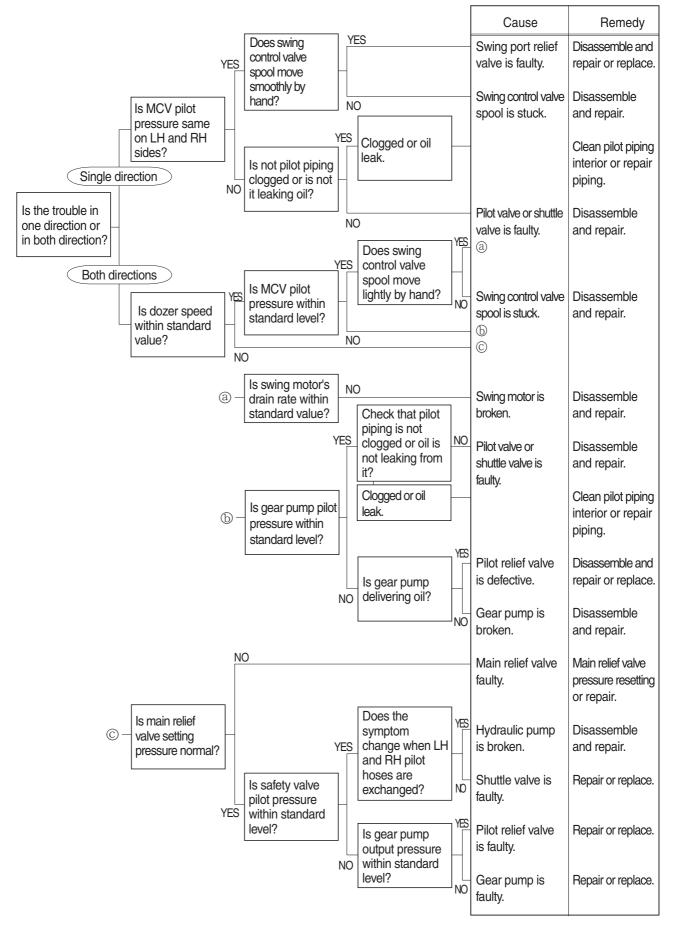


4. SWING SYSTEM

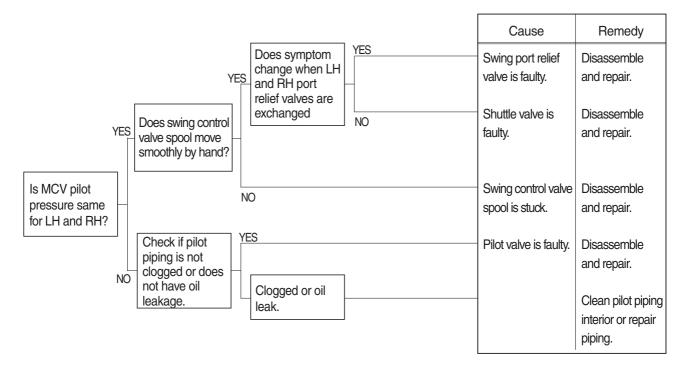
1) BOTH LH AND RH SWING ACTIONS ARE IMPOSSIBLE



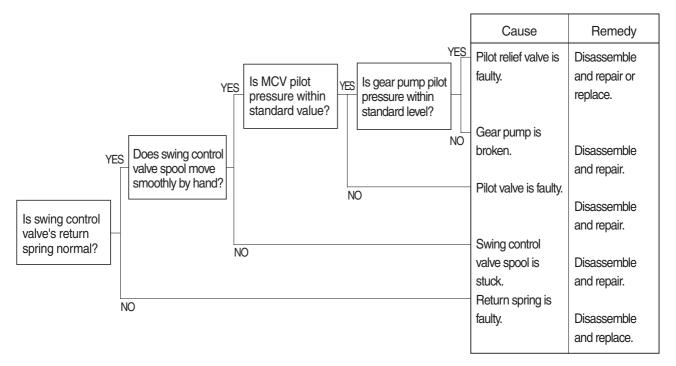
2) SWING SPEED IS LOW



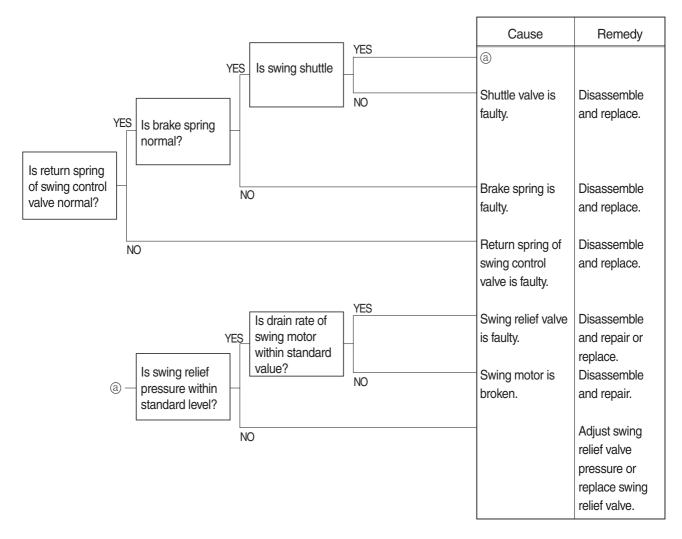
3) SWING MOTION IS IMPOSSIBLE IN ONE DIRECTION



4) MACHINE SWINGS BUT DOES NOT STOP

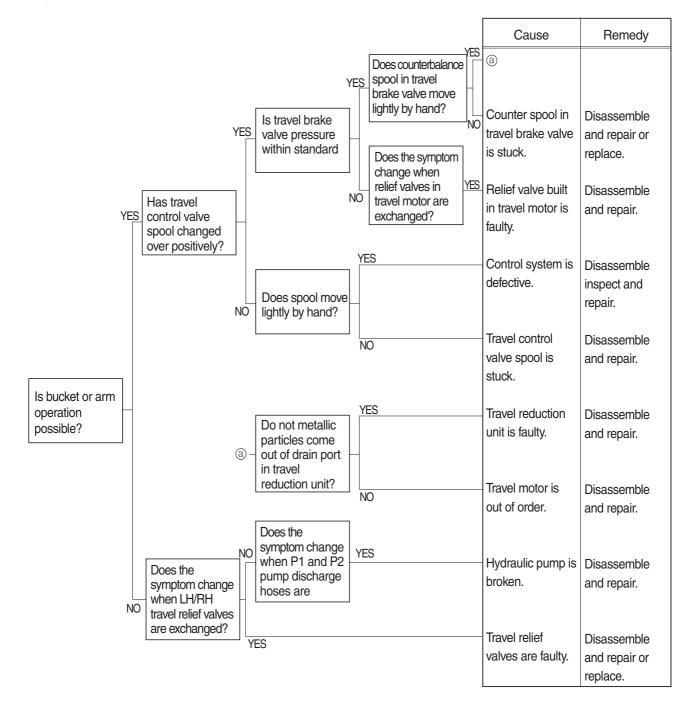


5) THE SWING UNIT DRIFTS WHEN THE MACHINE IS AT REST ON A SLOPE

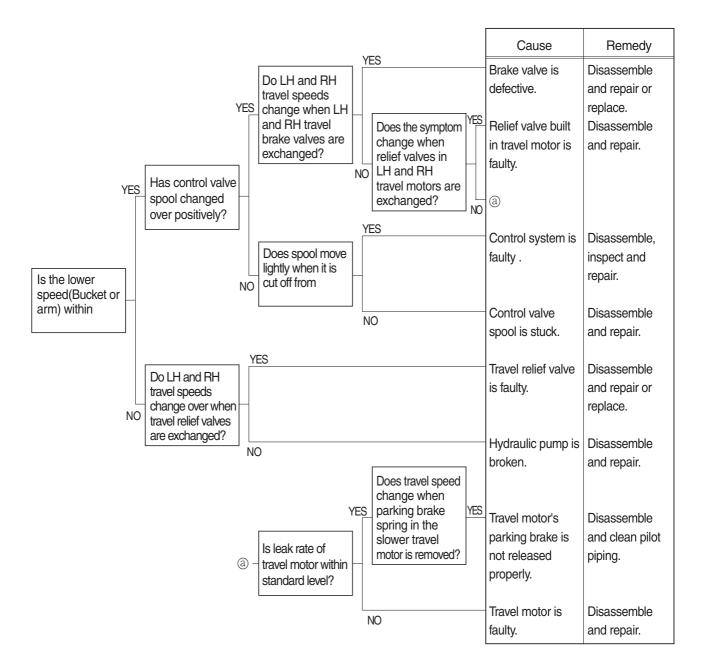


5. TRAVEL SYSTEM

1) TRAVEL DOES NOT FUNCTION AT ALL ON ONE SIDE

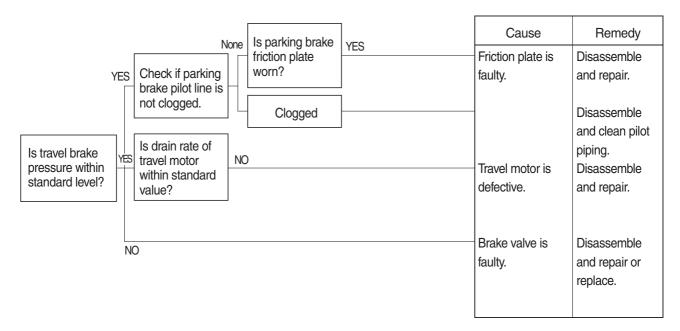


2) SPEED ON ONE SIDE FALLS AND THE MACHINE CURVES

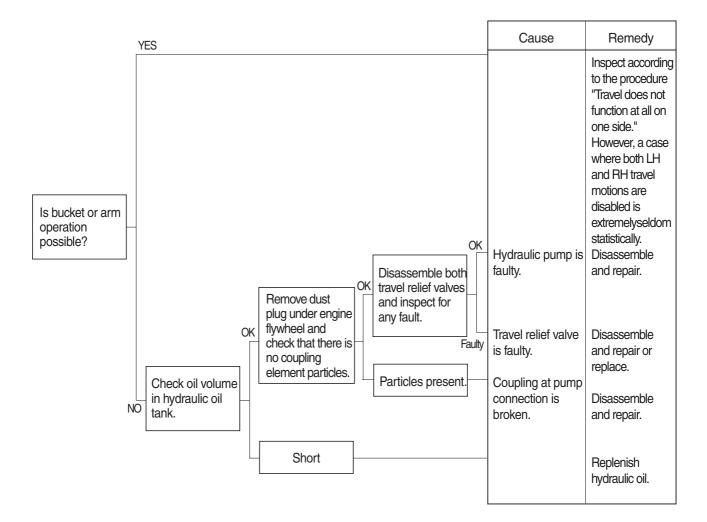


3) MACHINE DOES NOT STOP ON A SLOPE

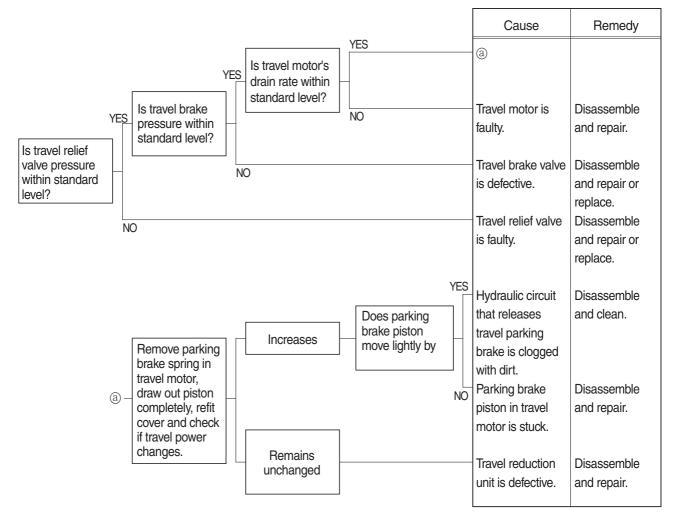
Machine is pulled forward as sprocket rotates during digging operation.



4) LH AND RH TRAVEL MOTIONS ARE IMPOSSIBLE



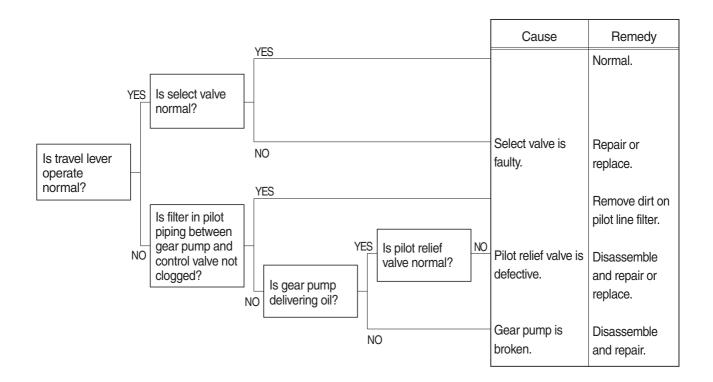
5) TRAVEL ACTION IS POWERLESS (travel only)



6) MACHINE RUNS RECKLESSLY ON A SLOPE

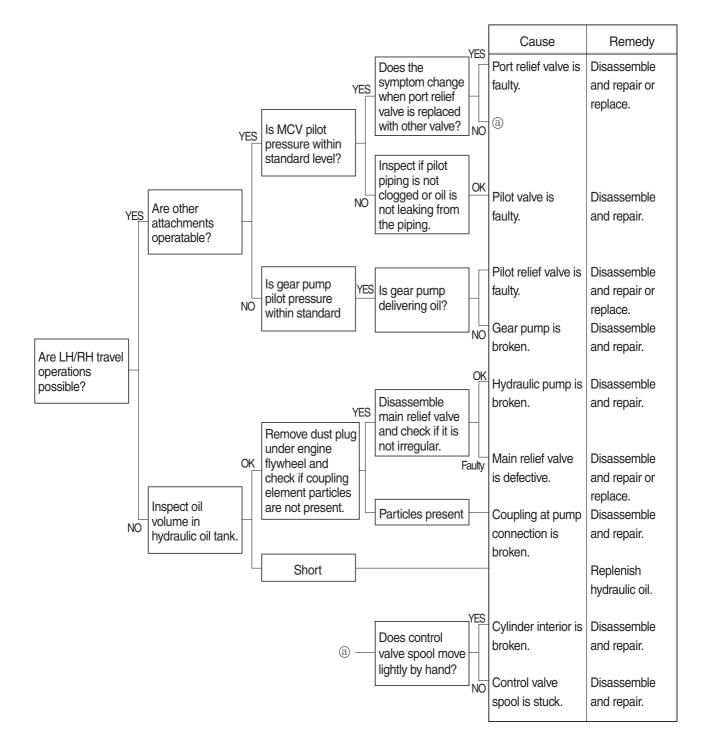
Travel brake valve	Cause	Remedy
(counterbalance valve) is faulty.		Disassemble and repair or replace.

7) MACHINE MAKES A CURVED TRAVEL OR DOES NOT TRAVEL AT ALL WHEN TRAVEL AND ATTACHMENT OPERATIONS ARE EXECUTED AT THE SAME TIME

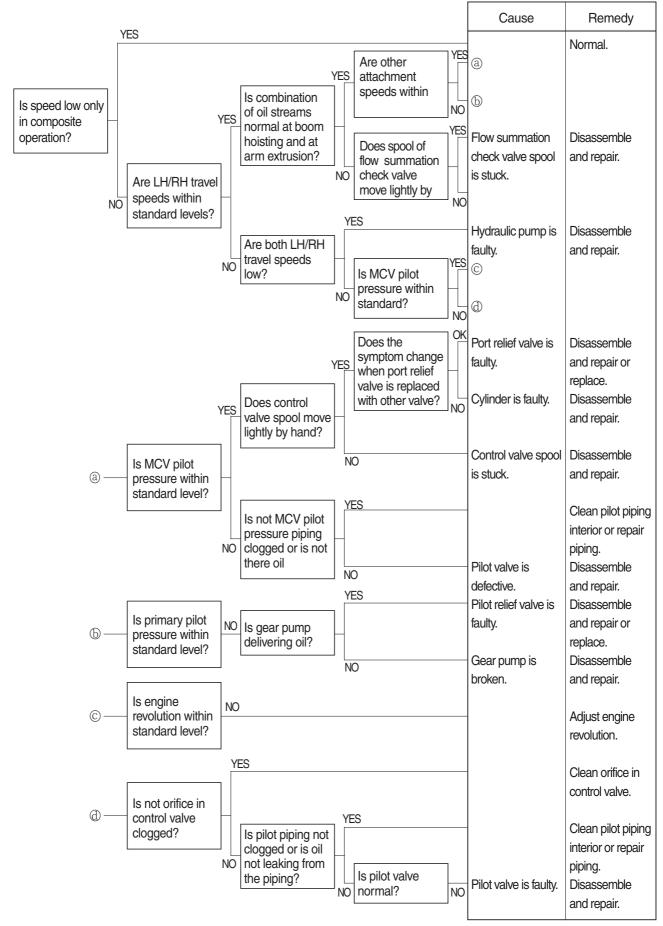


6. ATTACHMENT SYSTEM

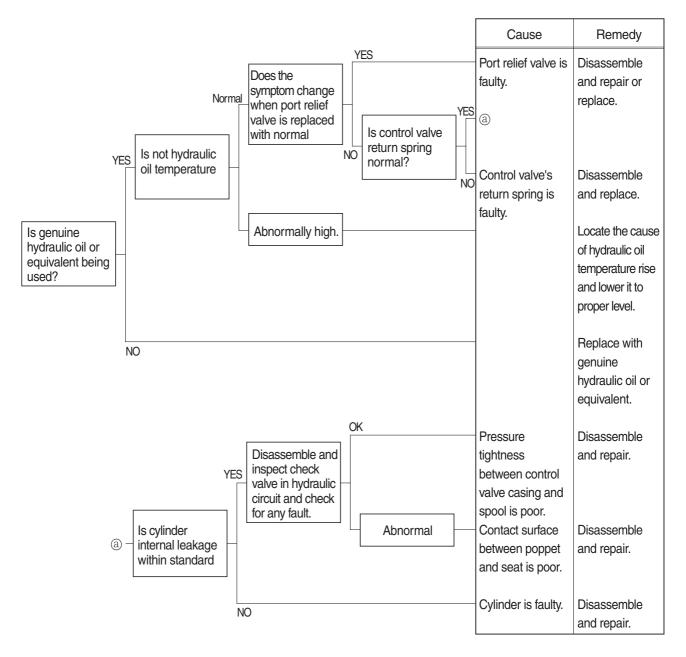
1) BOOM OR ARM ACTION IS IMPOSSIBLE AT ALL



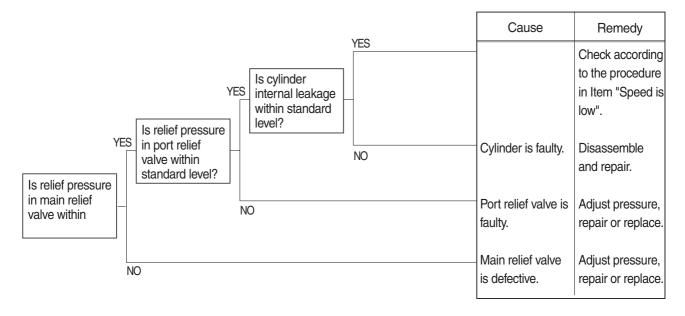
2) BOOM, ARM OR BUCKET SPEED IS LOW



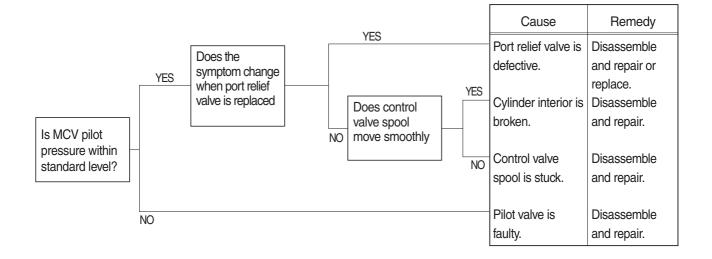
3) BOOM, ARM OR BUCKET CYLINDER EXTENDS OR CONTRACTS ITSELF AND ATTACHMENT FALLS



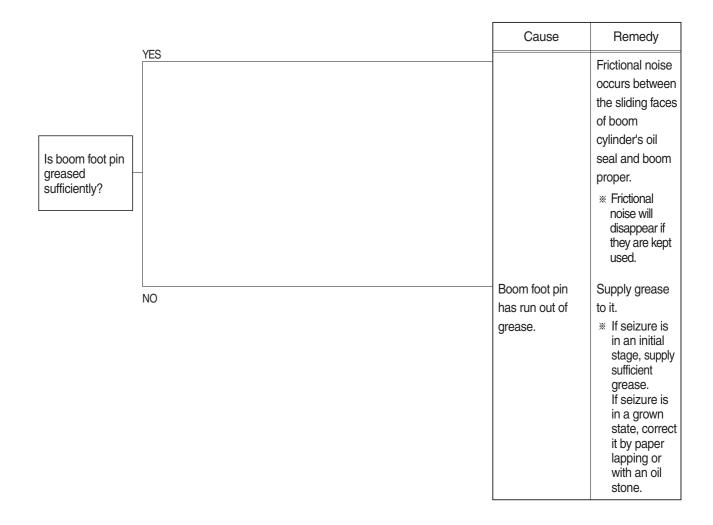
4) BOOM, ARM OR BUCKET POWER IS WEAK



5) ONLY BUCKET OPERATION IS TOTALLY IMPOSSIBLE

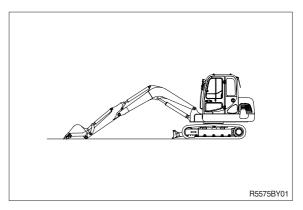


6) BOOM MAKES A SQUEAKING NOISE WHEN BOOM IS OPERATED

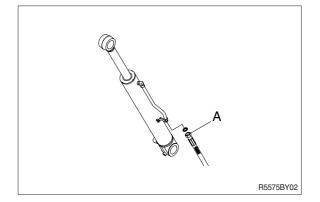


**** HOW TO CHECK INTERNAL BOOM CYLINDER LEAKAGE**

1. Lower the bucket teeth to the ground with bucket cylinder fully retracted and arm cylinder rod retracted almost in full.



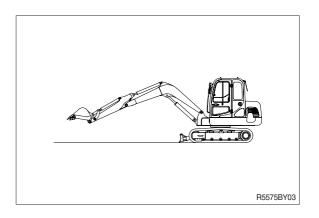
 Disconnect hose(A) from rod side of boom cylinder and drain oil from cylinders and hose.(Put cups on piping and hose ends)



3. Raise bucket OFF the ground by retracting the arm cylinder rod.

If oil leaks from piping side and boom cylinder rod is retracted there is an internal leak in the cylinder.

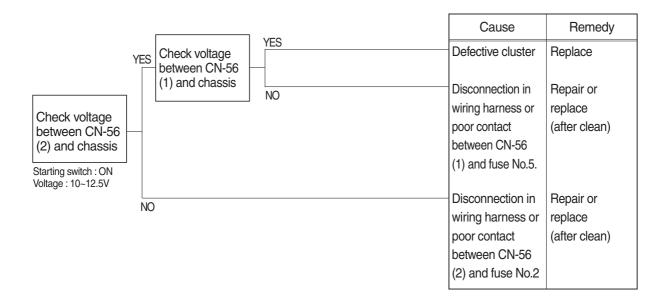
If no oil leaks from piping side and boom cylinder rod is retracted, there is an internal leak in the control valve.

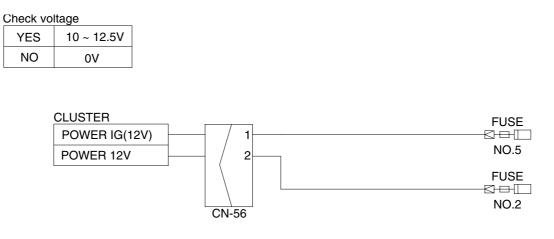


GROUP 3 ELECTRICAL SYSTEM

1. WHEN STARTING SWITCH IS TURNED ON, MONITOR PANEL DISPLAY DOES NOT APPEAR

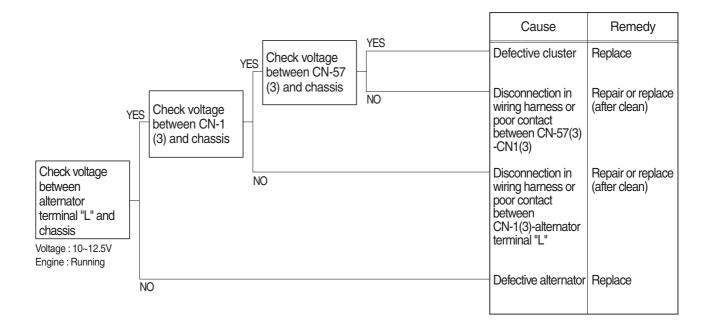
- · Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and short of fuse No.2 and No.5.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.





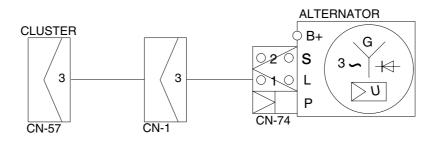
2. - + BATTERY CHARGING WARNING LAMP LIGHTS UP (starting switch : ON)

- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- \cdot Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



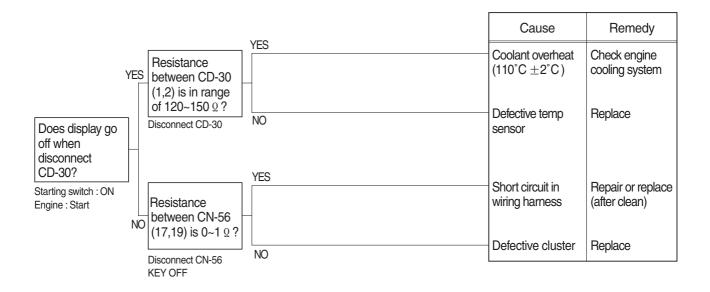
Check voltage

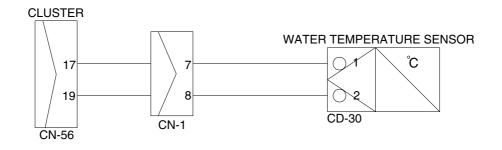
YES	10 ~ 12.5V
NO	0V



3. 💬 WHEN COOLANT OVERHEAT WARNING LAMP LIGHTS UP (engine is started)

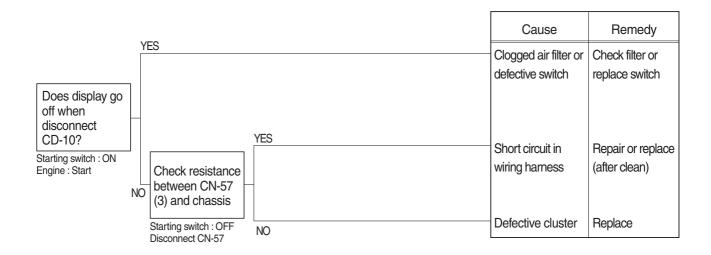
- · Before disconnecting the connector, always turn the starting switch OFF.
- · Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.





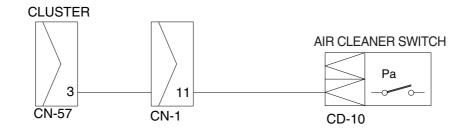
4. WHEN AIR CLEANER WARNING LAMP LIGHTS UP (engine is started)

- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- · Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



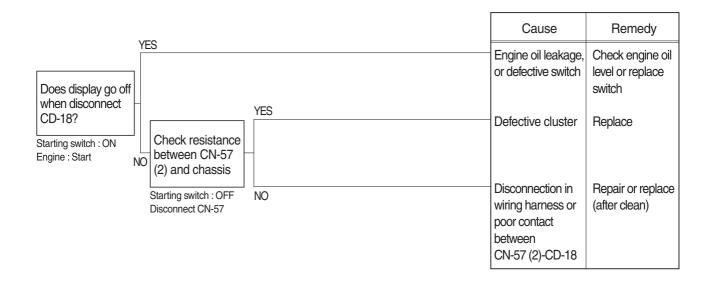
Check resistance

YES	ΜΑΧ 1 Ω
NO	$\textbf{MIN 1M} \ \boldsymbol{\Omega}$



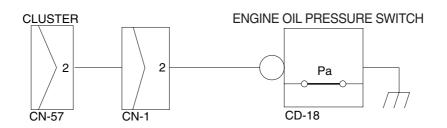
5. → (→) ← WHEN ENGINE OIL PRESSURE WARNING LAMP LIGHTS UP (engine is started)

- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- \cdot Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



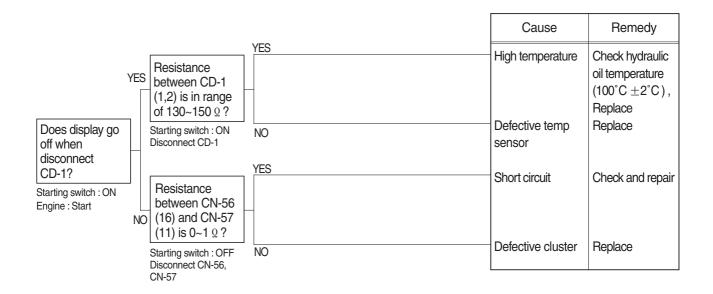
Check resistance

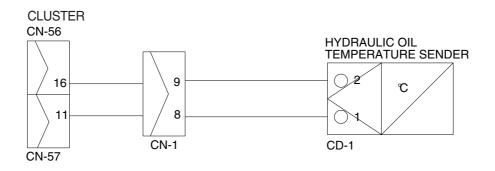
YES	ΜΑΧ 1 Ω
NO	MIN 1MΩ



6. WHEN HYDRAULIC OIL TEMPERATURE WARNING LAMP LIGHTS UP (engine is started)

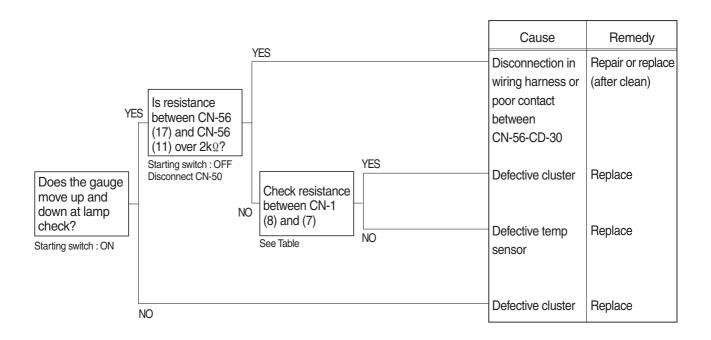
- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.

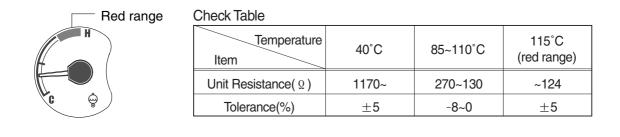


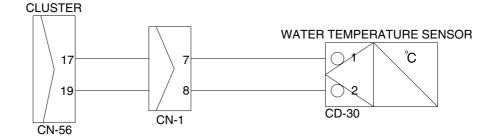


7. WHEN COOLANT TEMPERATURE GAUGE DOES NOT OPERATE

- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- · Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



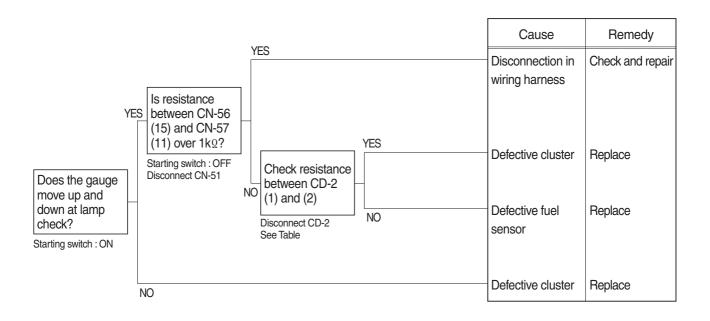


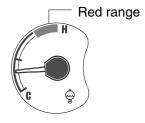


8. WHEN FUEL GAUGE DOES NOT OPERATE (check warning lamp ON/OFF)

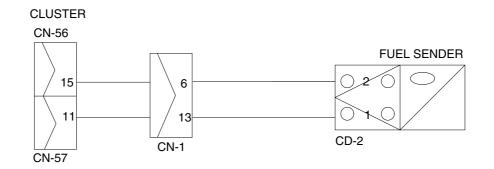
Check Table

- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- \cdot Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



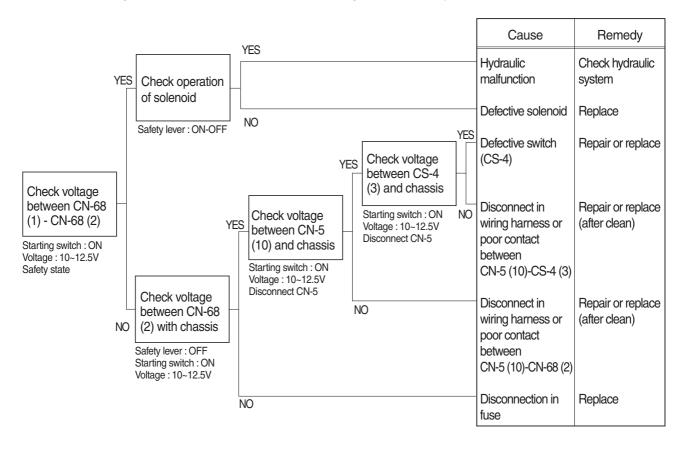


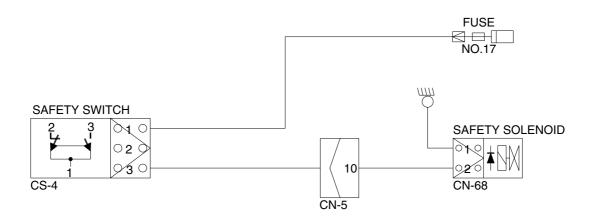
Level	Empty	1/2	Full
Unit Resistance (Ω)	700	300	~100
Tolerance (%)	±5	±8	±5



9. WHEN SAFETY SOLENOID DOES NOT OPERATE

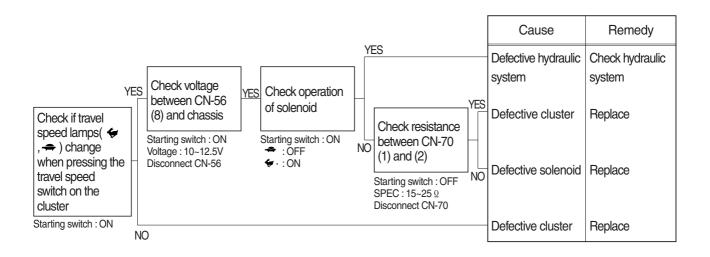
- · Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and short of fuse No.14.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.

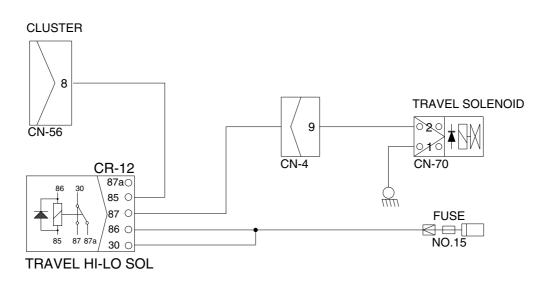




10. WHEN TRAVEL SPEED 1, 2 DOES NOT OPERATE

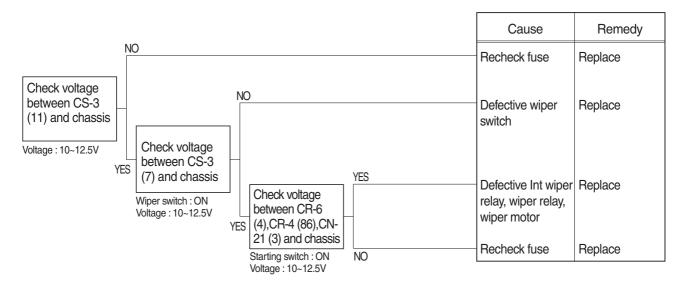
- \cdot Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and short of fuse No.15.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.

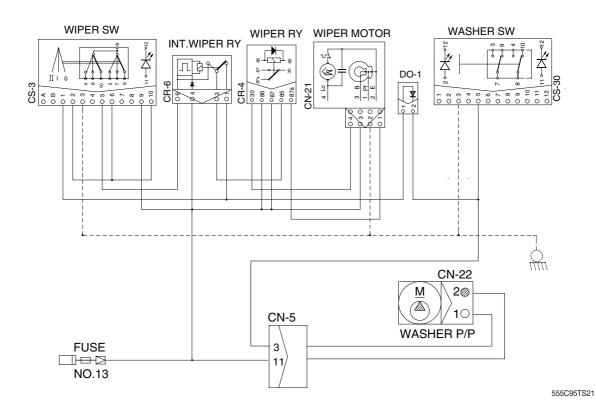




11. WHEN STARTING SWITCH IS TURNED ON, WIPER MOTOR DOES NOT OPERATE

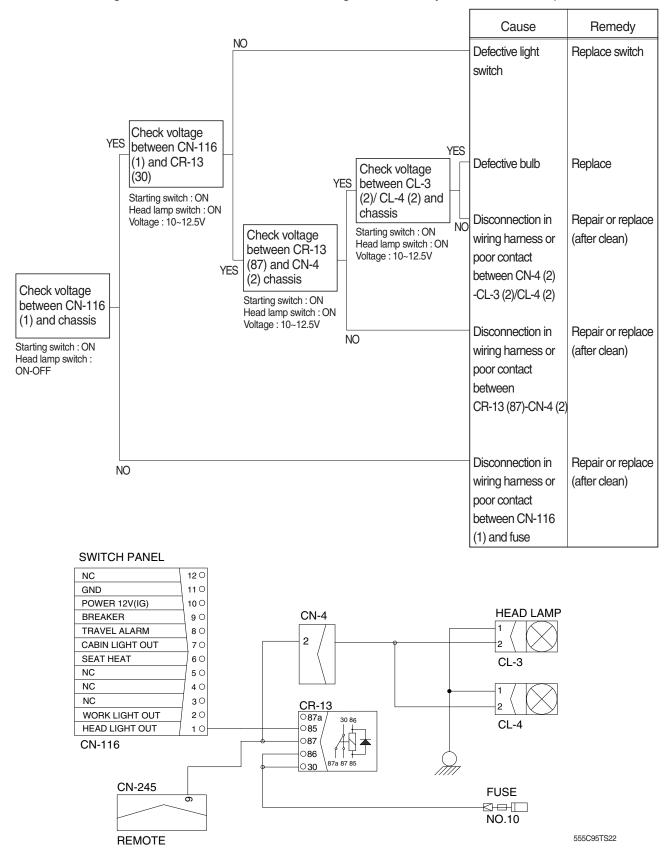
- · Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and the fuse No.13 is not blown out.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.





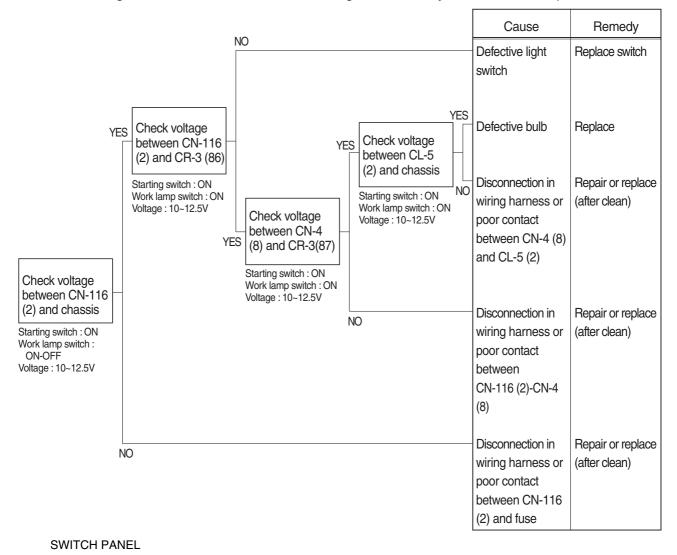
12. WHEN STARTING SWITCH IS TURNED ON, HEAD LAMP DOES NOT LIGHTS UP

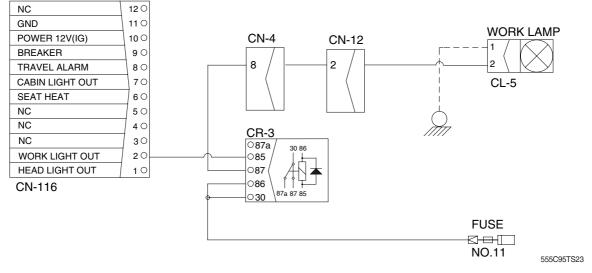
- · Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and short of fuse No.10.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.



13. WHEN STARTING SWITCH IS TURNED ON, WORK LAMP DOES NOT LIGHTS UP

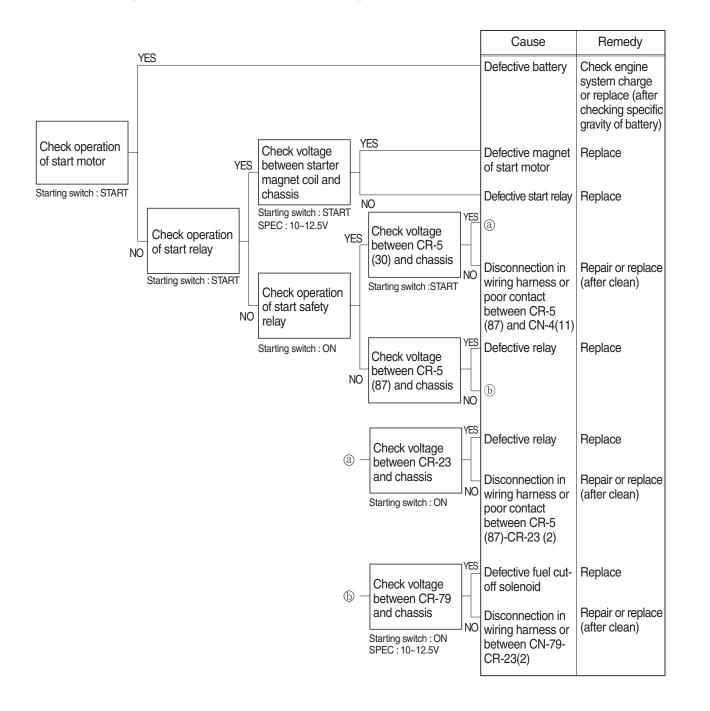
- · Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and short of fuse No.11.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.

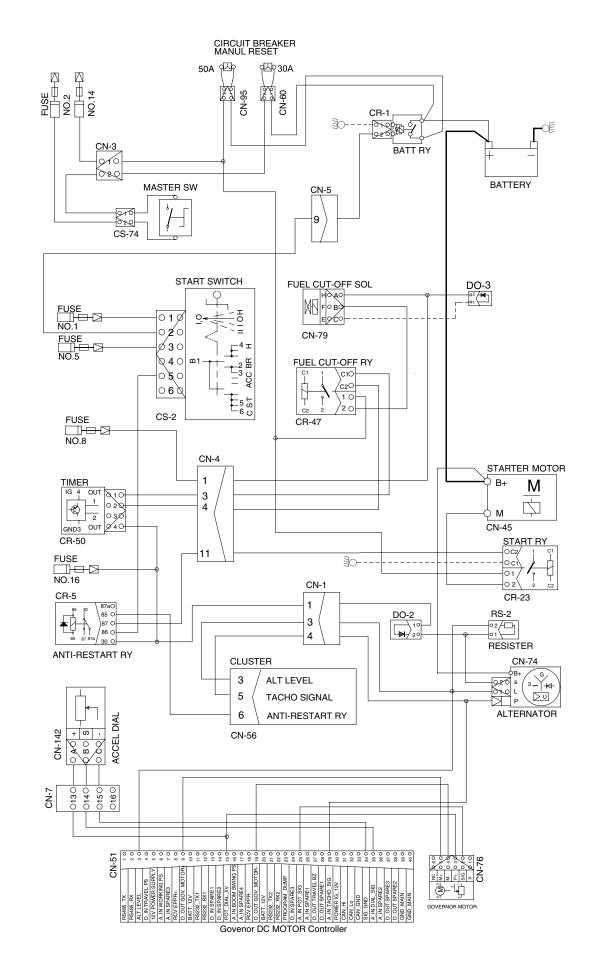




14. WHEN ENGINE DOES NOT START

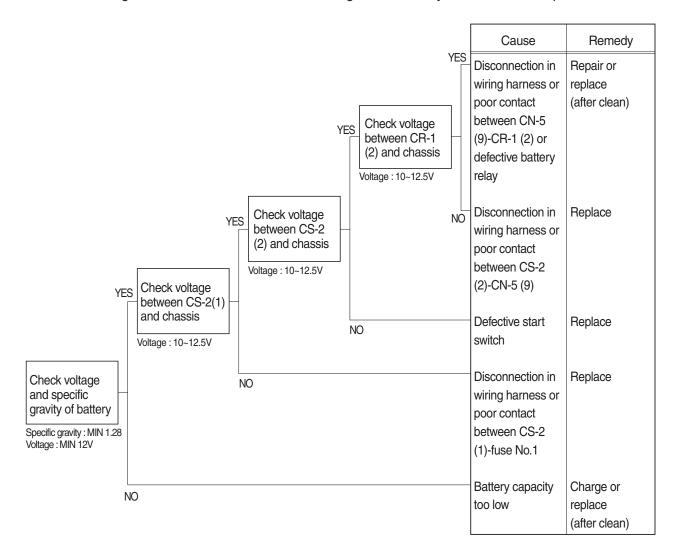
- \cdot Check supply of the power at engine stop solenoid while starting switch is ON.
- · Before disconnecting the connector, always turn the starting switch OFF.
- · Before carrying out below procedure, check all the related connectors are properly inserted.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.

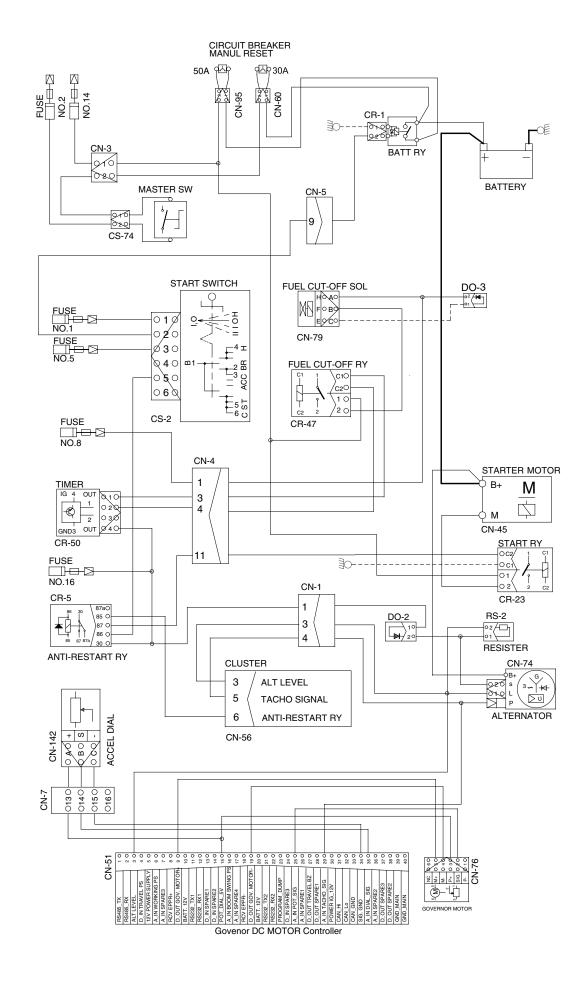




15. WHEN STARTING SWITCH ON DOES NOT OPERATE

- Before disconnecting the connector, always turn the starting switch OFF.
- Before carrying out below procedure, check all the related connectors are properly inserted and master switch ON.
- · After checking, insert the disconnected connectors again immediately unless otherwise specified.





Group	1	Operational Performance Test	6-1
Group	2	Major Components	6-21
Group	3	Track and Work Equipment	6-30

SECTION 6 MAINTENANCE STANDARD

GROUP 1 OPERATIONAL PERFORMANCE TEST

1. PURPOSE

Performance tests are used to check:

1) OPERATIONAL PERFORMANCE OF A NEW MACHINE

Whenever a new machine is delivered in parts and reassembled at a customer's site, it must be tested to confirm that the operational performance of the machine meets Hyundai spec.

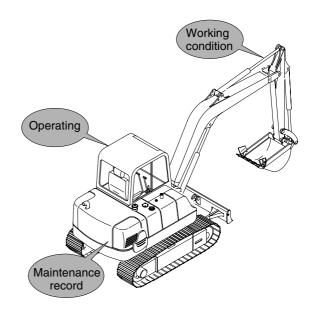
2) OPERATIONAL PERFORMANCE OF A WORKING MACHINE

With the passage of time, the machine's operational performance deteriorates, so that the machine needs to be serviced periodically to restore it to its original performance level.

Before servicing the machine, conduct performance tests to check the extent of deterioration, and to decide what kind of service needs to be done (by referring to the "Service Limits" in this manual).

3) OPERATIONAL PERFORMANCE OF A REPAIRED MACHINE

After the machine is repaired or serviced, it must be tested to confirm that its operational performance was restored by the repair and/or service work done.

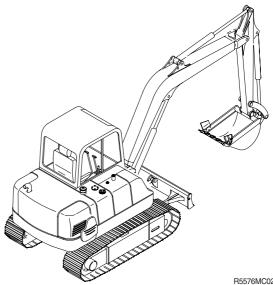


R5576MC01

2. TERMINOLOGY

1) STANDARD

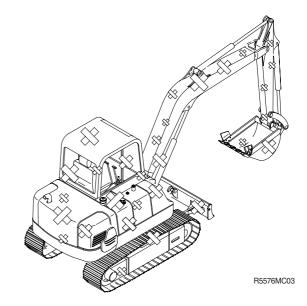
Specifications applied to the brand-new machine, components and parts.



R5576MC02

2) SERVICE LIMIT

The lowest acceptable performance level. When the performance level of the machine falls below this level, the machine must be removed from work and repaired. Necessary parts and components must be replaced.



3. OPERATION FOR PERFORMANCE TESTS

 Observe the following rules in order to carry out performance tests accurately and safely.

(1) The machine

Repair any defects and damage found, such as oil or water leaks, loose bolts, cracks and so on, before starting to test.

(2) Test area

- 1 Select a hard, flat surface.
- ② Secure enough space to allow the machine to run straight more than 20m, and to make a full swing with the front attachment extended.
- ③ If required, rope off the test area and provide signboards to keep unauthorized personnel away.

(3) Precautions

- Before starting to test, agree upon the signals to be employed for communication among coworkers. Once the test is started, be sure to communicate with each other using these signals, and to follow them without fail.
- ② Operate the machine carefully and always give first priority to safety.
- ③ While testing, always take care to avoid accidents due to landslides or contact with high voltage power lines. Always confirm that there is sufficient space for full swings.
- ④ Avoid polluting the machine and the ground with leaking oil. Use oil pans to catch escaping oil. Pay special attention to this when removing hydraulic pipings.

(4) Make precise measurements

- ① Accurately calibrate test instruments in advance to obtain correct data.
- ⁽²⁾ Carry out tests under the exact test conditions prescribed for each test item.
- ③ Repeat the same test and confirm that the test data obtained can be procured repeatedly. Use mean values of measurements if necessary.

7-3 (140-7)

2) ENGINE SPEED

- (1) Measure the engine speed at the maximum RPM.
- * The engine speed must meet standard RPM; if not, all other operational performance data will be unreliable. It is essential to perform this test first.

(2) Preparation and measurement

- Warm up the machine, until the engine coolant temperature reaches 50°C or more, and the hydraulic oil is 50±5°C.
- ② Set the M mode at the cluster
- ③ Measure the engine RPM.

(3) Evaluation

The measured speeds should meet the following specifications.

Unit : rpm

Model	Engine speed	Standard	Remark
R55-9	Low idle	1000±30	
	High idle	2200±30	M mode

3) TRAVEL SPEED

(1) Measure the time required for the excavator to travel a 20m test track.

(2) Preparation

- ① Adjust the tension of both tracks to be equal.
- ⁽²⁾ Prepare a flat and solid test track 20m in length, with extra length of 3 to 5m on both ends for machine acceleration and deceleration.
- ^③ Hold the bucket 0.3 to 0.5m above the ground with the arm and bucket rolled in.
- (4) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

- ① Measure both the low and high speeds of the machine.
- ② Before starting either the low or high speed tests, adjust the travel mode switch to the speed to be tested.
- ③ Start traveling the machine in the acceleration zone with the travel levers at full stroke.
- 4 Measure the time required to travel 20m.
- ⑤ After measuring the forward travel speed, turn the upperstructure 180° and measure the reverse travel speed.
- 6 Repeat steps ④ and ⑤ three times in each direction and calculate the average values.

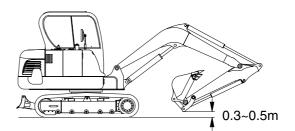
(4) Evaluation

The average measured time should meet the following specifications.

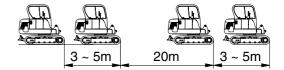
Unit : Seconds / 20m

555C96MC05

Model	Travel speed	Standard	Maximum allowable	Remarks
DEE O	1 Speed	32.7±2.0	41	
R55-9	2 Speed	18.0±1.0	23	



555C96MC04



4) TRACK REVOLUTION SPEED

(1) Measure the track revolution cycle time with the track raised off ground.

(2) Preparation

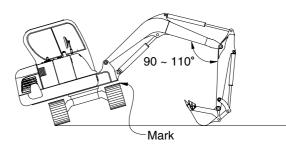
- Adjust the tension of both side tracks to be equal.
- ② On the track to be measured, mark one shoe with chalk.
- ③ Swing the upperstructure 90° and lower the bucket to raise the track off ground. Keep the boom-arm angle between 90 to 110° as shown. Place blocks under machine frame.
- (4) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

- ① Select the following switch positions.
 Travel mode switch : 1 or 2 speed
- ② Operate the travel control lever of the raised track in full forward and reverse.
- ③ Rotate 1 turn, then measure time taken for next 3 revolutions.
- ④ Raise the other side of machine and repeat the procedure.
- ⑤ Repeat steps ③ and ④ three times and calculate the average values.

(4) Evaluation

The revolution cycle time of each track should meet the following specifications.



555C96MC06

Unit : Seconds / 3 revolutions

Model	Travel speed	Standard	Maximum allowable
DEE 0	1 Speed	26.5±1.5	33.1
R55-9	2 Speed	14.6±1.5	18.3

5) TRAVEL DEVIATION

 Measure the deviation by the tracks from a 20m straight line.

(2) Preparation

- ① Adjust the tension of both tracks to be equal.
- ② Provide a flat, solid test yard 20m in length, with extra length of 3 to 5m on both ends for machine acceleration and deceleration.
- ③ Hold the bucket 0.3 to 0.5m above the ground with the arm and bucket rolled in.
- (4) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

- ① Measure the amount of mistracking at high and low travel speeds.
- ⁽²⁾ Start traveling the machine in the acceleration zone with the travel levers at full stroke.
- ⁽³⁾ Measure the distance between a straight 20m line and the track made by the machine. (dimension a)
- ④ After measuring the tracking in forward travel, turn the upperstructure 180° and measure that in reverse travel.
- ⑤ Repeat steps ③ and ④ three times and calculate the average values.

(4) Evaluation

Mistrack should be within the following specifications.

to 5m on ration and		0.5m
above the t rolled in. ure at	55	5C96MC04
acking at		
ne in the el levers at	3~5m extra le	ngth
a straight le by the		
n forward 180° and	3~5m extra length	
times and	-	7-7(2) 140-7

			Unit : mm / 20m
Model	Standard	Maximum allowable	Remarks
R55-9	200 below	240	

6) SWING SPEED

(1) Measure the time required to swing three complete turns.

(2) Preparation

- ① Check the lubrication of the swing gear and swing bearing.
- ② Place the machine on flat, solid ground with ample space for swinging. Do not conduct this test on slopes.
- ③ With the arm rolled out and bucket rolled in, hold the bucket so that the height of the bucket pin is the same as the boom foot pin. The bucket must be empty.
- (4) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

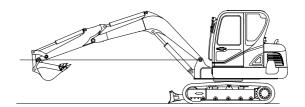
- ① Operate swing control lever fully.
- ② Swing 1 turn and measure time taken to swing next 2 revolutions.
- ③ Repeat steps ① and ② three time and calculate the average values.

(4) Evaluation

The time required for 2 swings should meet the following specifications.

Unit : Seconds / 2 revolutions

Model	Standard	Maximum allowable	Remarks
R55-9	12.9±1.0	16	



555C96MC07

7) SWING FUNCTION DRIFT CHECK

 Measure the swing drift on the bearing outer circumference when stopping after a 360° full speed swing.

(2) Preparation

- Check the lubrication of the swing gear and swing bearing.
- ⁽²⁾ Place the machine on flat, solid ground with ample space for swinging. Do not conduct this test on slopes.
- ^③ With the arm rolled out and bucket rolled in, hold the bucket so that the height of the bucket pin is the same as the boom foot pin. The bucket must be empty.
- ④ Make two chalk marks: one on the swing bearing and one directly below it on the track frame.
- ⁽⁵⁾ Swing the upperstructure 360°.
- ⁽⁶⁾ Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

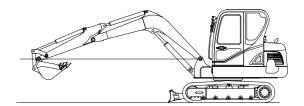
- Operate the swing control lever fully and return it to the neutral position when the mark on the upperstructure aligns with that on track frame after swinging 360°.
- ② Measure the distance between the two marks.
- ③ Align the marks again, swing 360°, then test the opposite direction.
- ④ Repeat steps ② and ③ three times each and calculate the average values.

(4) Evaluation

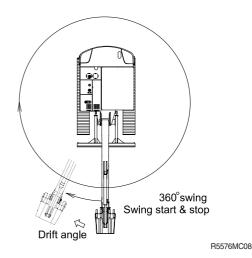
The measured drift angle should be within the following specifications.

Unit : Degree

Model	Standard	Maximum allowable	Remarks
R55-9	40 below	70	



555C96MC07



8) SWING BEARING PLAY

 Measure the swing bearing play using a dial gauge to check the wear of bearing races and balls.

(2) Preparation

- ① Check swing bearing mounting cap screws for loosening.
- ⁽²⁾ Check the lubrication of the swing bearing. Confirm that bearing rotation is smooth and without noise.
- ③ Install a dial gauge on the track frame as shown, using a magnetic base.
- ④ Position the upperstructure so that the boom aligns with the tracks facing towards the front idlers.
- ⑤ Position the dial gauge so that its needle point comes into contact with the bottom face of the bearing outer race.
- 6 Bucket should be empty.

(3) Measurement

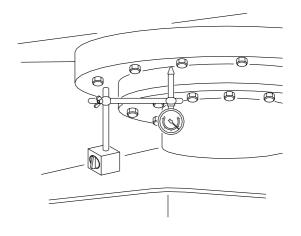
- With the arm rolled out and bucket rolled in, hold the bottom face of the bucket to the same height of the boom foot pin. Record the dial gauge reading (h1).
- ② Lower the bucket to the ground and use it to raise the front idler 50 cm.
 - Record the dial gauge reading (h2).
- ③ Calculate bearing play (H) from this data (h1 and h2) as follows.
 H=h2-h1

(4) Evaluation

The measured drift should be within the following specifications.

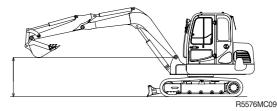
Unit : mm

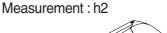
Model	Standard	Maximum allow	able Remarks
R55-9	0.5 ~ 1.2	2.4	

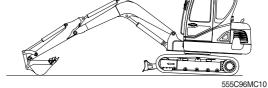


7-10(1) 140-7

Measurement : h1







6-10

9) HYDRAULIC CYLINDER CYCLE TIME

(1) Measure the cycle time of the boom, standard arm, and standard bucket cylinders.

(2) Preparation

① To measure the cycle time of the boom cylinders:

With the arm rolled out and the empty bucket rolled out, lower the bucket to the ground, as shown.

② To measure the cycle time of the arm cylinder.

With the empty bucket rolled in, position the arm so that it is vertical to the ground. Lower the boom until the bucket is 0.5m above the ground.

③ To measure the cycle time of the bucket cylinder.

The empty bucket should be positioned at midstroke between roll-in and roll-out, so that the sideplate edges are vertical to the ground.

(4) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

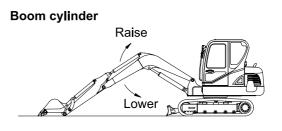
1 To measure cylinder cycle times.

-Boom cylinders.

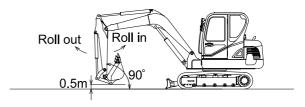
Measure the time it takes to raise the boom, and the time it takes to lower the boom. To do so, position the boom at one stroke end then move the control lever to the other stroke end as quickly as possible.

-Arm cylinder.

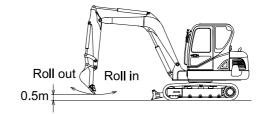
Measure the time it takes to roll in the arm, and the time it takes to roll out the arm. To do so, position the bucket at one stroke end, then move the control lever to the other stroke end as quickly as possible.



Arm cylinder



Bucket cylinder



555C96MC11

-Bucket cylinders

Measure the time it takes to roll in the bucket, and the time it takes to roll out the bucket. To do so, position the bucket at one stroke end, then move the control lever to the other stroke end as quickly as possible.

- Repeat each measurement 3 times and calculate the average values.

(4) Evaluation

The average measured time should meet the following specifications.

Unit : Seconds

Model	Function	Standard	Maximum allowable	Remarks
	Boom raise	2.6±0.4	3.2	
	Boom lower	2.3±0.4	2.9	
	Arm in	2.5±0.4	3.1	
	Arm out	$2.7\!\pm\!0.3$	3.1	
R55-9	Bucket load	3.7±0.4	4.3	
-00-9	Bucket dump	$2.4\!\pm\!0.3$	2.8	
	Boom swing (LH)	6.8±0.4	8.2	
	Boom swing (RH)	5.6±0.4	6.8	
	Dozer up (raise)	1.4±0.3	1.7	
	Dozer down (lower)	1.4±0.3	1.7	

10) DIG FUNCTION DRIFT CHECK

 Measure dig function drift, which can be caused by oil leakage in the control valve and boom, standard arm, and standard bucket cylinders, with the loaded bucket.
 When testing the dig function drift just after cylinder replacement, slowly operate each cylinder to its stroke end to purge air.

(2) Preparation

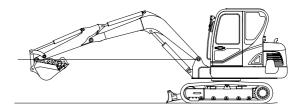
- Load bucket fully. Instead of loading the bucket, weight (W) of the following specification can be used.
- $W = M^3 \times 1.5$

Where :

- M³ = Bucket heaped capacity (m³)
- 1.5 = Soil specific gravity
- ⁽²⁾ Position the arm cylinder with the rod 20 to 30mm extended from the fully retracted position.
- ③ Position the bucket cylinder with the rod 20 to 30mm retracted from the fully extended position.
- ④ With the arm rolled out and bucket rolled in, hold the bucket so that the height of the bucket pin is the same as the boom foot pin.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

- ① Stop the engine.
- ⁽²⁾ Five minutes after the engine has been stopped, measure the changes in the positions of the boom, arm and bucket cylinders.
- ^③ Repeat step ^② three times and calculate the average values.
- (4) The measured drift should be within the following specifications.



555C96MC12

Unit : m	1m / 5i	min
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Model	Drift to be measured	Standard	Maximum allowable	Remarks
	Boom cylinder	10 below	20	
R55-9	Arm cylinder	20 below	30	
	Bucket cylinder	20 below	30	

11) CONTROL LEVER OPERATING FORCE

(1) Use a spring scale to measure the maximum resistance of each control lever at the middle of the grip.

(2) Preparation

① Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

-) Start the engine.
- ⁽²⁾ Operate each boom, arm, bucket and swing lever at full stroke and measure the maximum operating force for each.
- ③ Lower the bucket to the ground to raise one track off the ground. Operate the travel lever at full stroke and measure the maximum operating force required. When finished, lower the track and then jack-up the other track.
- ④ Repeat steps ② and ③ three times and calculate the average values.

(4) Evaluation

The measured operating force should be within the following specifications.

Unit : kgf

Model	Kind of lever	Standard	Maximum allowable	Remarks
R55-9	Boom lever	1.4 or below	1.9	
	Arm lever	1.4 or below	1.9	
	Bucket lever	1.4 or below	1.9	
	Swing lever	1.4 or below	1.9	
	Travel lever	2.0 or below	2.5	

12) CONTROL LEVER STROKE

- (1) Measure each lever stroke at the lever top using a ruler.
- When the lever has play, take a half of this value and add it to the measured stroke.

(2) Preparation

Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(3) Measurement

- ① Stop the engine.
- ② Measure each lever stroke at the lever top from neutral to the stroke end using a ruler.
- ③ Repeat step ② three times and calculate the average values.

(4) Evaluation

The measured drift should be within the following specifications.

Unit : mm

Model	Kind of lever	Standard	Maximum allowable	Remarks
R55-9	Boom lever	87±10	109	
	Arm lever	87±10	109	
	Bucket lever	87±10	109	
	Swing lever	87±10	109	
	Travel lever	86±10	105	

13) PILOT PRIMARY PRESSURE

(1) Preparation

- 1 Stop the engine.
- ⁽²⁾ Push the pressure release button to bleed air.
- ^③ Loosen and remove plug on the pilot pump delivery port (4G) and connect pressure gauge.
- ④ Start the engine and check for oil leakage from the port.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(2) Measurement

① Measure the primary pilot pressure in the M mode.

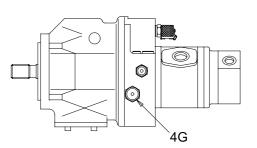
(3) Evaluation

The average measured pressure should meet the following specifications:

Unit : kgf / cm²

R55NN7MA14

Model	Standard	Remarks
R55-9	30±5	



14) FOR TRAVEL SPEED SELECTING PRESSURE:

(1) Preparation

- 1 Stop the engine.
- ⁽²⁾ Push the pressure release button to bleed air.
- ^③ To measure the speed selecting pressure: Install a connector and pressure gauge
- ④ assembly to turning joint P port as shown. Start the engine and check for on leakage from the adapter.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(2) Measurement

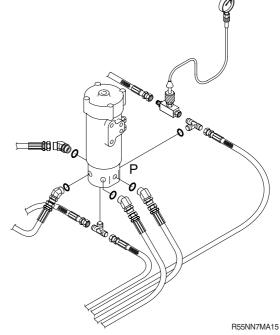
- Select the following switch positions. Travel mode switch : 1 speed 2 speed
- ② Measure the travel speed selecting pressure in the Hi or Lo mode.
- ③ Lower the bucket to the ground to raise the track off the ground. Operate the travel lever at full stroke and measure the fast speed pressure.
- ④ Repeat steps ② and ③ three times and calculate the average values.

(3) Evaluation

The average measured pressure should be within the following specifications.

Unit: kgf/cm²

Model	Travel speed mode	Standard	Maximum allowable	Remarks
R55-9	1 Speed	0	-	
	2 Speed	30±5	-	



15) SWING PARKING BRAKE RELEASING PRESSURE

(1) Preparation

- Stop the engine.
- ⁽²⁾ Push the pressure release button to bleed air.
- ③ Install a connector and pressure gauge assembly to swing motor SH port, as shown.
- ④ Start the engine and check for oil leakage from the adapter.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(2) Measurement

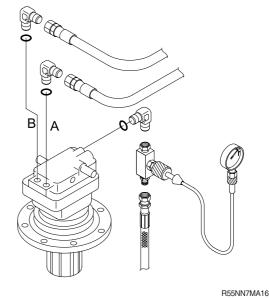
- Operate the swing function or arm roll in function and measure the swing brake control pressure with the brake disengaged. Release the control lever to return to neutral and measure the control pressure when the brake is applied.
- ② Repeat three times and calculate the average values.

(3) Evaluation

The average measured pressure should be within the following specifications.

Unit : kgf / cm²

Model	Description	Standard	Remarks
	Brake disengaged	30±5	
R55-9	Brake applied	0	



16) MAIN PUMP DELIVERY PRESSURE

(1) Preparation

- 1 Stop the engine.
- 2 Push the pressure release button to bleed air.
- ③ To measure the main pump pressure. Install a connector and pressure gauge assembly main pump gauge port (1G, 2G) as shown.
- ④ Start the engine and check for oil leakage from the port.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(2) Measurement

① Measure the main pump delivery pressure at high idle.

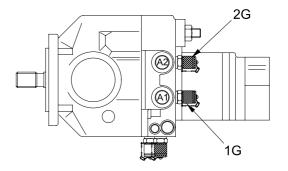
(3) Evaluation

The average measured pressure should meet the following specifications.

Unit : kgf / cm²

R55NN7MA17

Model	Engine speed	Standard	Allowable limits	Remarks
R55-9	High idle	20±5	-	



6-19

17) SYSTEM PRESSURE REGULATOR RELIEF SETTING

(1) Preparation

- Stop the engine.
- ⁽²⁾ Push the pressure release button to bleed air.
- ③ To measure the system relief pressure. Install a connector and pressure gauge assembly main pump gauge port, as shown.
- ④ Start the engine and check for oil leakage from the port.
- (5) Keep the hydraulic oil temperature at $50\pm5^{\circ}$ C.

(2) Measurement

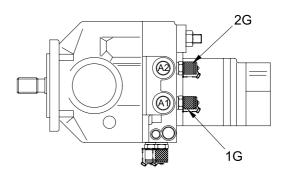
- Slowly operate each control lever of boom, arm and bucket functions at full stroke over relief and measure the pressure.
- ② In the swing function, place bucket against an immovable object and measure the relief pressure.
- ③ In the travel function, lock undercarriage with an immovable object and measure the relief pressure.

(3) Evaluation

The average measured pressure should be within the following specifications.

Unit : kgf / cm²

Model	Function to be tested	Standard
R55-9	Boom, Arm, Bucket	220±10
	Travel	220±10
	Swing	200±10



R55NN7MA17

GROUP 2 MAJOR COMPONENT

1. MAIN PUMP

Before inspection, wash the parts well and dry them completely.

Inspect the principal parts with care and replace them with new parts when any abnormal wear exceeding the allowable limit or damage considered harmful is found.

Replace the seal also when any remarkable deformation and damage are found.

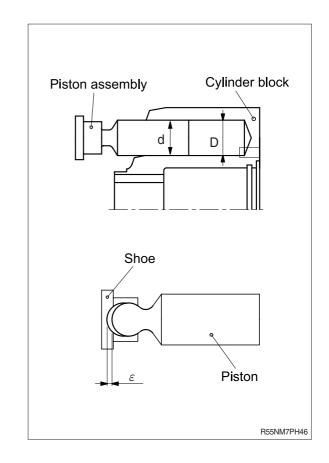
1) PISTON ASSEMBLY AND CYLINDER BLOCK

- Check the appearance visually. No damage, scouring, abnormal wear (particularly, in the slide portion) should be found.
- (2) Check the clearance between the piston outside dia and cylinder block inside dia. D-d \leq 0.050 mm

2) PISTON SHOE AND PISTON

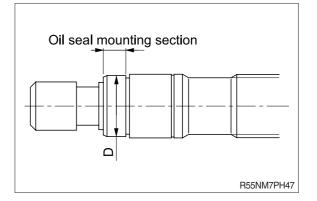
(1) Check the axial play of the piston and piston shoe.

 $arepsilon~\leq$ 0.2 mm



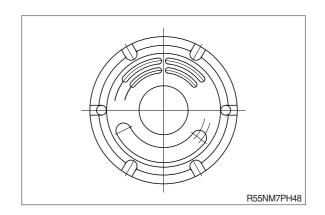
3) SHAFT

(1) Check the wear amount of the oil seal mounting section. Wear mount ≤ 0.025 mm



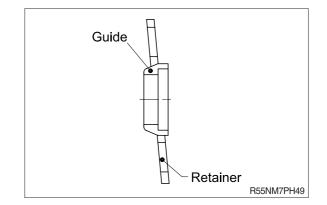
4) CONTROL PLATE

 Check the slide surface for any damage. When the damage is large, replace the plate with new one.



5) GUIDE AND RETAINER

- Check for scouring or stepped wear.
 If this can not be corrected, replace the guide and retainer with new full-set.
- (2) Fine scouring or damage can be corrected with lapping.Carry out thorough washing after lapping.



2. MAIN CONTROL VALVE

Part name	Inspection item	Criteria & measure
Block	Existence of scratch, rusting or corrosion.	• In case of damage in following section, replace part.
		 Sliding sections of casing fore and spool, especially land sections applied with holded pressure. Seal pocket section where spool is inserted. Seal section of port where O-ring contacts. Seal section of each relief valve for main, travel, and port. Other damages that may damage normal functions.
Spool	Existence of scratch, gnawing, rusting or corrosion.	Replacement when its outside sliding section has scratch (especially on seals-contacting section).
	· O-ring seal sections at both ends.	Replacement when its sliding section has scratch.
	Insert spool in casing hole, rotate and reciprocate it.	Correction or replacement when O-ring is damaged or when spool does not move smoothly.
Poppet	Damage of poppet or spring	Correction or replacement when sealing is incomplete.
	Insert poppet into casing and function it.	Normal when it can function lightly without being caught.
Around spring	Rusting, corrosion, deformation or breaking of spring, spring seat, plug or cover.	Replacement for significant damage.
Around seal	• External oil leakage.	Correction or replacement.
for spool	Rusting, corrosion or deformation of seal plate.	Correction or replacement.
Main relief valve &	External rusting or damage.	· Replacement.
port relief valve	· Contacting face of valve seat.	· Replacement when damaged.
	· Contacting face of poppet.	· Replacement when damaged.
	Abnormal spring.	· Replacement.
	\cdot O-rings, back up rings and seals.	· 100% replacement in general.

3. SWING DEVICE

1) WEARING PARTS

,		1	1
Inspection item	Standard dimension	Recommended replacement value	Counter measures
Clearance between piston and cylinder block bore	0.020	0.045	Replace piston or cylinder block
Play between piston and shoe caulking section (δ)	0	0.3	Replace assembly of piston and shoe
Thickness of shoe (t)	4	3.8	Replace assembly of piston and shoe
Combined height of set plate and guide (H)	17.4	17	Replace set of set plate and guide
Thickness of friction plate	3.6	3.2	Replace
			<u> </u>

2) SLIDING PARTS

Part name	Standard roughness	Remark
Shoe	0.8S	
Shoe plate	0.8S	
Cylinder block	6.3S	
Valve plate	0.8S	

5. TRAVEL DEVICE (TYPE 1)

Disassembling and inspection of the motor must be done in strict accordance with the servicing standards described here. During servicing, handle each part very carefully not to damage them, especially for their movable or sliding sections.

1) SEALS

Once the seals (o-rings, oil seals, and floating seals) have been disassembled, they must be replaced with new ones even if no damage is observed.

2) TABLE OF MAINTENANCE STANDARD

- (1) Replace all parts having a seriously damaged appearance.
- (2) Replace the part if any one of the states (symptoms) listed in the table below is observed.

ltem No.	Part name	Situation	Standard dimension	Maximum allowable value (criteria)
2 8 17	Spindle kit ·Spindle assembly ·Spindle ·Coupling gear ·Pin	 Seriously damaged in appearance. Galling or other forms of excessive wear are observed. 	-	-
3 6 9 14 25 34	Carrier assembly Carrier Cluster gear Shaft Thrust collar Needle bearing Dowel pin	 The tooth surface of the cluster gear (6) is nonuniformly worn out and damaged. The cluster gear (6) does not move smoothly. 	-	-
4	Ring gear A	•The tooth surface is nonuniformly worn out and damaged.	-	-
5	Ring gear B	•The tooth surface is nonuniformly worn out and damaged.	-	-
7	Sun gear	 The tooth surface is nonuniformly worn out and damaged. The spline section is worn. 	-	-
8	Coupling gear	•Excessive wear or pitching is observed on the tooth surface.	-	-
19	Coupling	•The spline section is worn.	-	-
20	Thrust bearing	·Worn out.	Axial clearance between coupling gear (8) and cover (13) : 0.3 mm±0.1 mm	-

ltem No.	Part name	Situation	Standard dimension	Maximum allowable value (criteria)
22	Distance piece	\cdot The sliding surface is damaged.		
		The sliding surface is excessively worn out.	-	-
24	Ball bearing	Dents are present.		
		 Flaking develops. 	-	-
		Nonuniform wear is present.		
101	Rear flange kit Rear flange	The movable section contacting the spool (123) is damaged.	Linear clearance : 10 to 20 μ	Linear clearance : 25 µ
		The clearance against the spool (123) is too large.		
		• The surface contacting the valve (127) is damaged.		
		The depth to the surface contacting the valve (127) is too large.		
123	Spool	\cdot The outer surface is damaged.		
		The outer surface is nonuniformly worn out.		
102	Shaft	• The surface contacting the oil seal (132) is worn out.	-	-
		\cdot The spline section is worn out.		
103	Swash plate	\cdot Seizure is observed.	-	-
104	Cylinder block	\cdot The spline section is worn out.		
		The bore inner surface is worn out too much.	-	-
		The sliding surface that contacts the timing plate (109) is damaged or nonuniformly worn out.		
105 106	Piston assembly Piston shoe	An axial clearance is present between the piston (105) and the shoe (106).	Clearance : 0.05mm	Clearance : 0.15mm
		\cdot The shoe is excessively worn out.		
		\cdot The shoe is nonuniformly worn out.		
107	Retainer plate	The peripheral edge is nonuniformly worn out.	-	-

Item No.	Part name	Situation	Standard dimension	Maximum allowable value (criteria)
108	Thrust ball	The spherical sliding section that contacts the retainer plate (107) is nonuniformly worn out.		
109	Timing plate	 The sliding surface has the traces of seizure or nonuniformly wear. 	-	-
115	Friction plate	Both edges are nonuniformly worn out.	Braking torque 40.6 kgf \cdot m or more	Braking torque 40.6 kgf \cdot m or less
116	Mating plate	The required torque cannot be achieved.		
		The traces of seizure are present.		
118	Valve seat	\cdot The seat surface is damaged.	-	-
119	Valve	\cdot The outer surface is damaged.		
		\cdot The seat surface is damaged.	-	-
136	Body kit Body	The sliding section that contacts the spool (137) is damaged.	Linear clearance : 7 to 15 μ	Linear clearance : 20 μ
		The clearance against the spool (137) is too large.		
137		\cdot The outer surface is damaged.		
	Spool	The outer surface is nonuniformly worn out.		
149	Roller bearing	\cdot Dents are present.		
150	Ball bearing	 Flaking develops. 	-	-
		Nonuniform wear is observed.		
163	Valve	• The outer surface is damaged.	-	-
		\cdot The seat surface is damaged.		
164	Stopper	\cdot The seat surface is damaged.		
142	Valve	\cdot The outer surface is damaged.		
		\cdot The seat surface is damaged.		
172	Valve seat	\cdot The seat surface is damaged.	-	-

TRAVEL DEVICE (TYPE 2, MACHINE SERIAL NO.: #3959-)

Disassembling and inspection of the motor must be done in strict accordance with the servicing standards described here. During servicing, handle each part very carefully not to damage them, especially for their movable or sliding sections.

1) PARTS INSPECTION TIPS AND REPLACEMENT STANDARDS

(1) Sun gear, drive gear, planetary gear, housing.

Pitting and breaking appear on the tooth surface.

% When the size of the groove or cavity in one pitting is Φ 1mm or more or the area ratio is 5% or more for the entire area.

(2) Oil seal

Replace when the surface of the lip is damaged or worn. When disassembling the oil seal from the motor for inspection.

(3) Planetary gear F of needle bearing part

As the planetary gear F is assembled, check the boss and circumference direction clearance of the motor casing. If it is 0.5 mm or more, replace it.

(4) Do not disassemble in housing and check with the following tips.

- ① Check the raceway surface, rollers or balls in the visible range, and make sure there are no pittings or cracks.
- 2 Check for local corrosion and wear on the ball.
- ③ Please check again with the following tips.
 - a) Check the gear oil for excessive wear powder.
 - b) Make sure that there is excessive wear powder between the ball and cage.
 - c) When turning lightly by hand, check that it rotates smoothly.

After performing the above inspection, replace any problem.

Do not use angular bearing separated from housing again.

(5) Side plate

If the drive gear and sliding surfaces are markedly damaged, they must be replaced.

(6) Fitting on rotating surfaces of needle bearing and inner racefor planetary gear R, should be replaced when broken.

5. TURNING JOINT

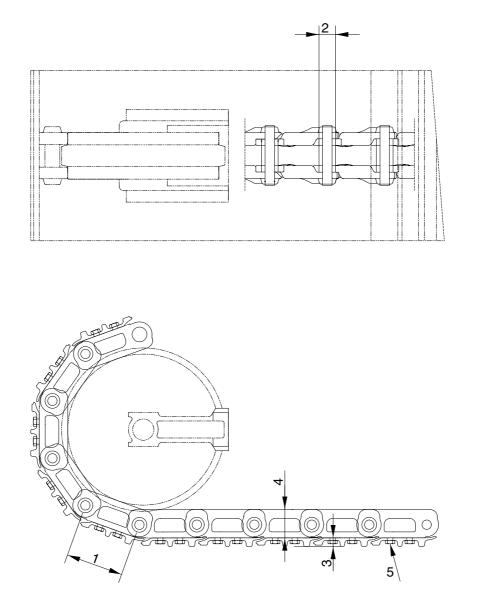
	Part name	Maintenance standards	Remedy
Body, Stem	Sliding surface with sealing sections.	Plating worn or peeled due to seizure or contamination.	Replace
	Sliding surface between body and stem other than	• Worn abnormality or damaged more than 0.1 mm (0.0039 in) in depth due to seizure contamination.	Replace
	sealing section.	Damaged more than 0.1 mm (0.0039 in) in depth.	Smooth with oilstone.
	Sliding surface with thrust plate.	\cdot Worn more than 0.5 mm (0.02 in) or abnormality.	Replace
	linder plate.	\cdot Worn less than 0.5 mm (0.02 in).	Smooth
		Damage due to seizure or contamination remediable within wear limit (0.5 mm) (0.02 in).	Smooth
Cover	Sliding surface with	\cdot Worn more than 0.5 mm (0.02 in) or abnormality.	Replace
	thrust plate.	• Worn less than 0.5 mm (0.02 in).	Smooth
		Damage due to seizure or contamination remediable within wear limit (0.5 mm) (0.02 in).	Replace
Seal set -		Extruded excessively from seal groove square ring.	Replace
		 Slipper ring 1.5 mm (0.059 in) narrower than seal groove, or narrower than back ring. 1.5 mm (max.) (0.059 in) 	Replace
	-	• Worn more than 0.5 mm (0.02 in) ~ 1.5 mm (MAX.) (0.059 in)	Replace

6. CYLINDER

Part name	Inspecting section	Inspection item	Remedy
Piston rod	Neck of rod pin	Presence of crack	· Replace
	• Weld on rod hub	Presence of crack	· Replace
	Stepped part to which piston is attached.	Presence of crack	· Replace
	· Threads	 Presence of crack 	 Recondition or replace
	Plated surface	 Plating is not worn off to base metal. 	Replace or replate
		Rust is not present on	 Replace or replate
		plating.	\cdot Recondition, replate or
		Scratches are not present.	replace
	· Rod	• Wear of O.D.	 Recondition, replate or replace
	\cdot Bushing at mounting part	• Wear of I.D.	· Replace
Cylinder tube	 Weld on bottom 	Presence of crack	· Replace
	\cdot Weld on head	 Presence of crack 	· Replace
	 Weld on hub 	 Presence of crack 	· Replace
	Tube interior	Presence of faults	\cdot Replace if oil leak is seen
	\cdot Bushing at mounting part	• Wear on inner surface	· Replace
Gland	• Bushing	Flaw on inner surface	Replace if flaw is deeper than coating

1. TRACK SHOE

1) STEEL SHOE SPEC

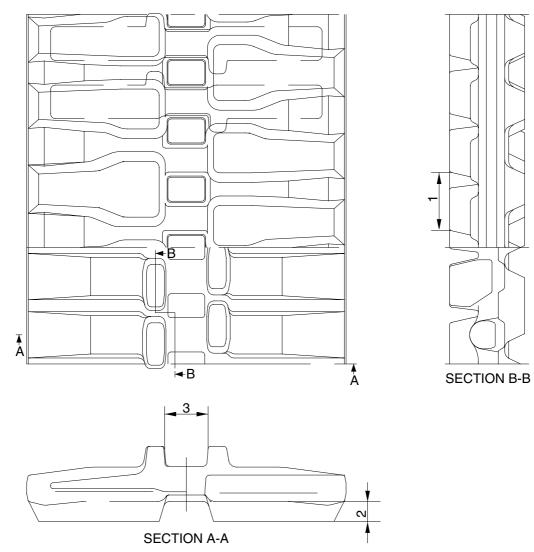


R5576MC16

U	nit	÷	mm
0	1.11.		

No	Check item	Crit	Criteria				
No		Standard size	Repair limit	Remedy			
1	Link pitch	135	138.6	Replace bushing			
2	Outside diameter of bushing	35	31.4	and pin and link assembly			
3	Height of grouser	14	11	Lug welding,			
4	Height of link	67	61.5	rebuild or replace			
5	Tightening torque	Initial tightening torque :	Retighten				

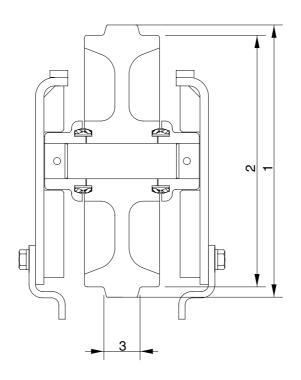
2) RUBBER SHOE SPEC



R5576MC17

No	Check item		Domody			
No	Check lieff	Standard size	Tolerance	Repair limit	Remedy	
1	Link pitch	73	±1.0	76		
2	Height of grouser	25	-	5	Replace	
5	Width of link	55	-	70	-	

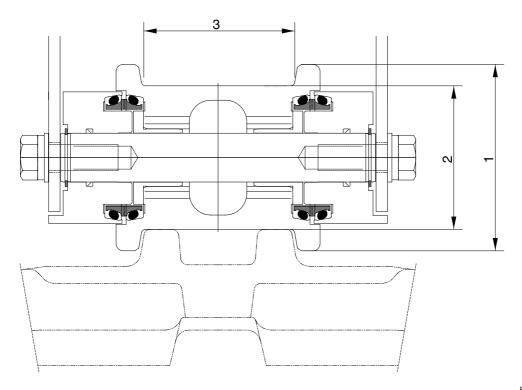
2. IDLER



R5576MC18

No	No Check item		Crit	Domody	
					Standard size Repair limit
4	1 Outside dispertor of flores		384	-	
	Outside diameter of flange	Rubber	398	-	Rebuild
2	Outside diameter of thread		355	345	or replace
5	Width of flange		51	-	

3. TRACK/CARRIER ROLLER

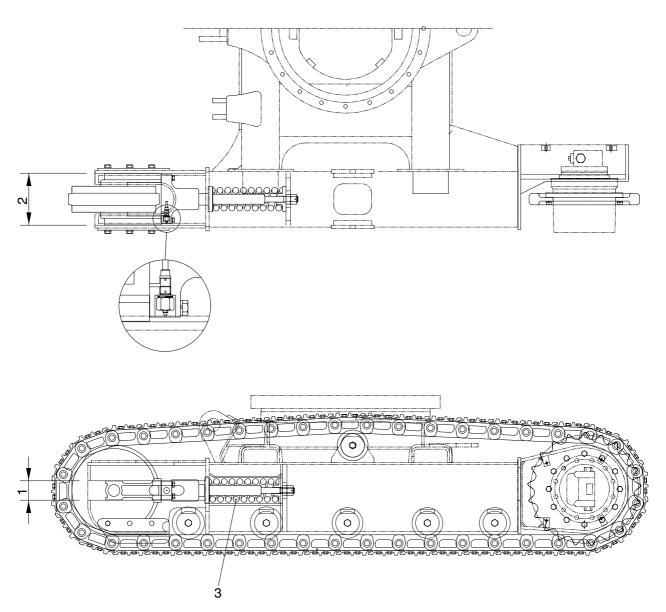


R5576MC15

No	No Check item		Crit	Domodu	
			Checkilem		Standard size Repair limit
4	1 Outside diameter of flange		130	-	
	Outside diameter of flange	Rubber	135	-	Rebuild
2	Outside diameter of thread		105	95	or replace
5	Width of flange		108	114	•

4. TENSION CYLINDER

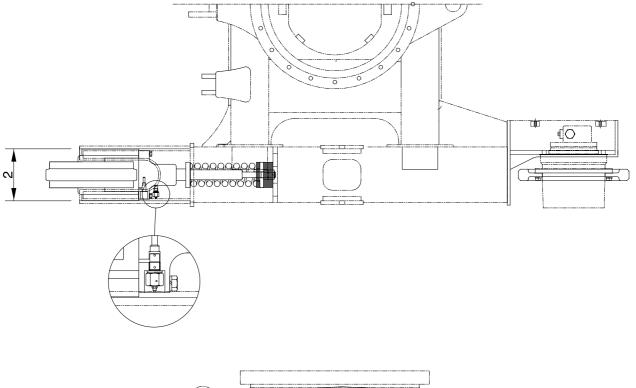
1) STEEL SHOE SPEC

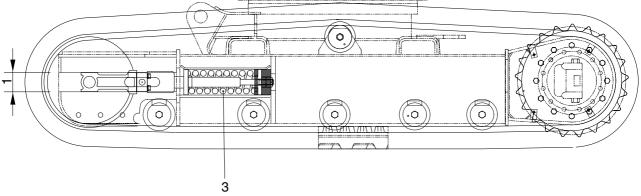


R5576MC19

No	Check item				Bomody		
	Check lien			Standard siz	ze Rep	air limit	Remedy
4	1 Outside diameter of flange		ame	82		86	Rebuild
			pport	80		78	Rebuild or replace
			ame	220		222	Rebuild
2	Outside diameter of thread	Idler guide		218		214	Rebuild or replace
		Standar		size	Repa	ir limit	
3	Recoil spring	Free length	Installe lengt	ed Installed load	Free length	Installed load	Replace
		ø 100×330	292	3,900 kg	-	3,120 kg	

2) RUBBER SHOE SPEC

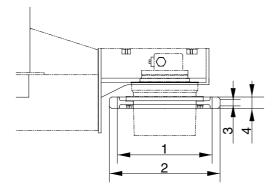


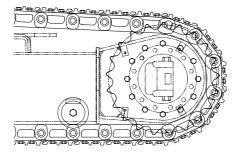


R5576MC20

No	Check item			Criteria			Demody	
	NO CHECKIEM			Standard si	ze Rej	pair limit	Remedy	
4	1 Vertical width of idler guide		Track frame		82		Debuild	
			pport	80		76	Rebuild	
2	Herizentel width of idler quide	Track frame		220		222	Rebuild or replace	
	Horizontal width of idler guide	Idler guide		218	218		Rebuild	
		St	andard	l size	Repa	air limit	Rebuild or replace	
3	Recoil spring	Free length	Installe lengt	ed Installed h load	Free length	Installed load		
		330	280	5,140 kg	-	4,110 kg	Replace	

5. SPROCKET

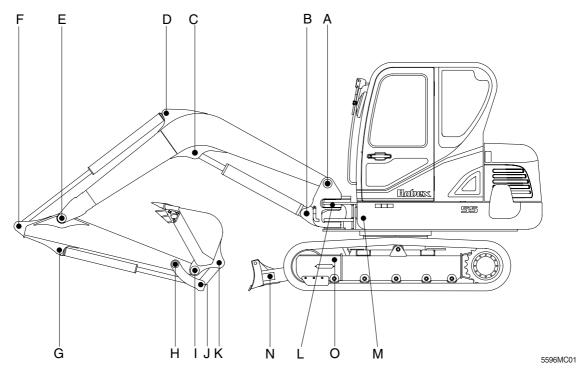




R5576MC21

No	Check item	Crit	Criteria			
		Standard size	Repair limit	Remedy		
1	Wear out of sprocket tooth lower side diameter	418.6	412			
2	Wear out of sprocket tooth upper side diameter	476	-	Repair or		
3	Wear out of sprocket tooth upper side width			Replace		
4	Wear out of sprocket tooth lower side width	42.5	36.5			

6. WORK EQUIPMENT



U	nit	÷	mm

			Р	in	Bus	hing	Remedy
Mark	Measuring point (pin and bushing)	Normal value	Recomm. service limit	Limit of use	Recomm. service limit	Limit of use	Remark
A	Boom Rear	50	49	48.5	50.5	51	Replace
В	Boom Cylinder Head	60	59	58.5	60.5	61	"
С	Boom Cylinder Rod	60	59	58.5	60.5	61	"
D	Arm Cylinder Head	50	49	48.5	50.5	51	"
E	Boom Front	50	49	48.5	50.5	51	"
F	Arm Cylinder Rod	50	49	48.5	50.5	51	"
G	Bucket Cylinder Head	45	44	43.5	45.5	46	"
Н	Arm Link	45	44	43.5	45.5	46	"
I	Bucket and Arm Link	45	44	43.5	45.5	46	"
J	Bucket Cylinder Rod	45	44	43.5	45.5	46	"
К	Bucket Link	45	44	43.5	45.5	46	"
L	Boom swing post	110	109	108.5	110.5	111	"
М	Boom swing cylinder	50	49	48.5	50.5	51	"
N	Blade cylinder	55	54	53.5	55.5	56	"
0	Blade and frame link	35	34	33.5	35.5	36	"

SECTION 7 DISASSEMBLY AND ASSEMBLY

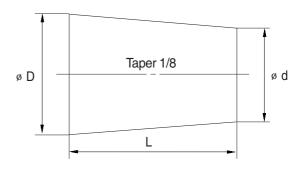
Group	1	Precaution	7-1
Group	2	Tightening Torque	7-4
Group	3	Pump Device	7-7
Group	4	Main Control Valve	7-38
Group	5	Swing Device	7-51
Group	6	Travel Device	7-72
Group	7	RCV Lever ·····	7-100
Group	8	Turning Joint	7-114
Group	9	Boom, Arm and Bucket Cylinder	7-119
Group	10	Undercarriage	7-138
Group	11	Work Equipment	7-150

GROUP 1 PRECAUTIONS

1. REMOVAL WORK

- 1) Lower the work equipment completely to the ground. If the coolant contains antifreeze, dispose of it correctly.
- 2) After disconnecting hoses or tubes, cover them or fit blind plugs to prevent dirt or dust from entering.
- 3) When draining oil, prepare a container of adequate size to catch the oil.
- 4) Confirm the match marks showing the installation position, and make match marks in the necessary places before removal to prevent any mistake when assembling.
- 5) To prevent any excessive force from being applied to the wiring, always hold the connectors when disconnecting the connectors.
- 6) Fit wires and hoses with tags to show their installation position to prevent any mistake when installing.
- 7) Check the number and thickness of the shims, and keep in a safe place.
- 8) When raising components, be sure to use lifting equipment of ample strength.
- 9) When using forcing screws to remove any components, tighten the forcing screws alternately.
- 10) Before removing any unit, clean the surrounding area and fit a cover to prevent any dust or dirt from entering after removal.
- 11) When removing hydraulic equipment, first release the remaining pressure inside the hydraulic tank and the hydraulic piping.
- 12) If the part is not under hydraulic pressure, the following corks can be used.

Nominal	Dimensions					
number	D	d	L			
06	6	5	8			
08	8	6.5	11			
10	10	8.5	12			
12	12	10	15			
14	14	11.5	18			
16	16	13.5	20			
18	18	15	22			
20	20	17	25			
22	22	18.5	28			
24	24	20	30			
27	27	22.5	34			



2. INSTALL WORK

- 1) Tighten all bolts and nuts(Sleeve nuts) to the specified torque.
- 2) Install the hoses without twisting or interference.
- 3) Replace all gaskets, O-rings, cotter pins, and lock plates with new parts.
- 4) Bend the cotter pin or lock plate securely.
- 5) When coating with adhesive, clean the part and remove all oil and grease, then coat the threaded portion with 2-3 drops of adhesive.
- 6) When coating with gasket sealant, clean the surface and remove all oil and grease, check that there is no dirt or damage, then coat uniformly with gasket sealant.
- 7) Clean all parts, and correct any damage, dents, burrs, or rust.
- 8) Coat rotating parts and sliding parts with engine oil.
- 9) When press fitting parts, coat the surface with antifriction compound(LM-P).
- 10) After installing snap rings, check that the snap ring is fitted securely in the ring groove(Check that the snap ring moves in the direction of rotation).
- 11) When connecting wiring connectors, clean the connector to remove all oil, dirt, or water, then connect securely.
- 12) When using eyebolts, check that there is no deformation or deterioration, and screw them in fully.
- 13) When tightening split flanges, tighten uniformly in turn to prevent excessive tightening on one side.
- 14) When operating the hydraulic cylinders for the first time after repairing and reassembling the hydraulic cylinders, pumps, or other hydraulic equipment or piping, always bleed the air from the hydraulic cylinders as follows:
- (1) Start the engine and run at low idling.
- (2) Operate the control lever and actuate the hydraulic cylinder 4-5 times, stopping 100mm before the end of the stroke.
- (3) Next, operate the piston rod to the end of its stroke to relieve the circuit. (The air bleed valve is actuated to bleed the air.)
- (4) After completing this operation, raise the engine speed to the normal operating condition.
- * If the hydraulic cylinder has been replaced, carry out this procedure before assembling the rod to the work equipment.
- * Carry out the same operation on machines that have been in storage for a long time after completion of repairs.

3. COMPLETING WORK

- 1) If the coolant has been drained, tighten the drain valve, and add water to the specified level. Run the engine to circulate the water through the system. Then check the water level again.
- 2) If the hydraulic equipment has been removed and installed again, add engine oil to the specified level. Run the engine to circulate the oil through the system. Then check the oil level again.
- 3) If the piping or hydraulic equipment, such as hydraulic cylinders, pumps, or motors, have been removed for repair, always bleed the air from the system after reassembling the parts.
- 4) Add the specified amount of grease(Molybdenum disulphied grease) to the work equipment related parts.

GROUP 2 TIGHTENING TORQUE

1. MAJOR COMPONENTS

No. Descriptions		Descriptions	Dolt oizo	Torque		
INO.			Bolt size	kgf∙m	lbf ∙ ft	
1		Engine mounting bolt(Engine-Bracket)	M10 × 1.5	6.9±1.0	50±7.2	
2	F ucciana	Engine mounting bolt(Bracket-Frame)	M16 × 2.0	25±2.5	181±18.1	
3	Engine	Radiator mounting bolt, nut	M10 × 1.5	6.9±1.4	50±10.0	
4		Coupling mounting bolt	M10 × 1.5	6.0±1.0	43.4±7.2	
5		Main pump mounting bolt	M12 × 1.75	12.3±3.0	92±22.0	
6		Main control valve mounting bolt	M 8 × 1.25	2.5±0.5	18±3.6	
7	Hydraulic system	Fuel tank mounting bolt	M16 × 2.0	29.7±4.5	215±33	
8	oyotom	Hydraulic oil tank mounting bolt	M16 × 2.0	29.7±4.5	215±33	
9		Turning joint mounting bolt, nut	M12 × 1.75	12.8±3.0	92±22.0	
10		Swing motor mounting bolt	M16 × 2.0	29.7±4.5	215±33.0	
11	Power	Swing bearing upper mounting bolt	M16 × 2.0	29.7±4.5	215±33.0	
12	train	Swing bearing lower mounting bolt	M16 × 2.0	29.7±4.5	215±33.0	
13	system	Travel motor mounting bolt	M14 × 2.0	20±2.0	145±14.0	
14		Sprocket mounting bolt	M14 × 2.0	19.6±2.9	142±21.0	
15		Carrier roller mounting bolt, nut	M16 × 2.0	29.6±3.2	214±23.1	
16		Track roller mounting bolt	M18 × 2.0	$41\!\pm\!5.0$	297±36.0	
17	Under carriage	Track tension cylinder mounting bolt	M12 × 1.75	12.8±3.0	92±22.0	
18	55	Track shoe mounting bolt, nut	1/2-20UNF	19.5±2.0	141±14.5	
19		Track guard mounting bolt	M16 × 2.0	29.6±3.2	214±23.0	
20		Counter weight mounting bolt	M20 × 2.5	57.8±6.4	418±46.3	
21	Others	Cab mounting bolt, nut	M12 × 1.75	12.8±3.0	92±22.0	
22		Operator's seat mounting bolt	M 8 × 1.25	1.17±0.1	8.5±0.7	

* For tightening torque of engine and hydraulic components, see engine maintenance guide and service manual.

2. TORQUE CHART

Use following table for unspecified torque.

1) BOLT AND NUT

(1) Coarse thread

Bolt size	8T		10T		
	kg∙m	lb ⋅ ft	kg∙m	lb ⋅ ft	
M 6×1.0	0.85 ~ 1.25	6.15 ~ 9.04	1.14 ~ 1.74	8.2 ~ 12.6	
M 8×1.25	2.0 ~ 3.0	14.5 ~ 21.7	2.7 ~ 4.1	19.5 ~ 29.7	
M10 × 1.5	4.0 ~ 6.0	28.9 ~ 43.4	5.5 ~ 8.3	39.8 ~ 60	
M12 × 1.75	7.4 ~ 11.2	53.5 ~ 81.0	9.8 ~ 15.8	70.9 ~ 114	
M14 × 2.0	12.2 ~ 16.6	88.2 ~ 120	16.7 ~ 22.5	121 ~ 163	
M16 × 2.0	18.6 ~ 25.2	135 ~ 182	25.2 ~ 34.2	182 ~ 247	
M18 × 2.5	25.8 ~ 35.0	187 ~ 253	35.1 ~ 47.5	254 ~ 344	
M20 × 2.5	36.2 ~ 49.0	262 ~ 354	49.2 ~ 66.6	356 ~ 482	
M22 × 2.5	48.3 ~ 63.3	349 ~ 458	65.8 ~ 98.0	476 ~ 709	
M24 × 3.0	62.5 ~ 84.5	452 ~ 611	85.0 ~ 115	615 ~ 832	
M30 × 3.0	124 ~ 168	898 ~ 1214	169 ~ 229	1223 ~ 1656	
M36 × 4.0	174 ~ 236	1261 ~ 1704	250 ~ 310	1808 ~ 2242	

(2) Fine thread

Bolt size	8T		10T		
DOIL SIZE	kg∙m	lb∙ft	kg∙m	lb ⋅ ft	
M 8×1.0	2.2 ~ 3.4	15.9 ~ 24.6	3.0 ~ 4.4	21.7 ~ 31.8	
M10 × 1.2	4.5 ~ 6.7	32.5 ~ 48.5	5.9 ~ 8.9	42.7 ~ 64.4	
M12 × 1.25	7.8 ~ 11.6	56.4 ~ 83.9	10.6 ~ 16.0	76.7 ~ 116	
M14 × 1.5	13.3 ~ 18.1	96.2 ~ 131	17.9 ~ 24.1	130 ~ 174	
M16 × 1.5	19.9 ~ 26.9	144 ~ 195	26.6 ~ 36.0	192 ~ 260	
M18 × 1.5	28.6 ~ 43.6	207 ~ 315	38.4 ~ 52.0	278 ~ 376	
M20 × 1.5	40.0 ~ 54.0	289 ~ 391	53.4 ~ 72.2	386 ~ 522	
M22 × 1.5	52.7 ~ 71.3	381 ~ 516	70.7 ~ 95.7	511 ~ 692	
M24 × 2.0	67.9 ~ 91.9	491 ~ 665	90.9 ~ 123	658 ~ 890	
M30 × 2.0	137 ~ 185	990 ~ 1339	182 ~ 248	1314 ~ 1796	
M36 × 3.0	192 ~ 260	1390 ~ 1880	262 ~ 354	1894 ~ 2562	

2) PIPE AND HOSE (FLARE type)

Thread size (PF)	Width across flat (mm)	kgf ∙ m	lbf ⋅ ft
1/4"	19	4	28.9
3/8"	22	5	36.2
1/2"	27	9.5	68.7
3/4"	36	18	130
1"	41	21	152
1-1/4"	50	35	253

3) PIPE AND HOSE (ORFS type)

Thread size (UNF)	Width across flat (mm)	kgf ∙ m	lbf ⋅ ft
9/16-18	19	4	28.9
11/16-16	22	5	36.2
13/16-16	27	9.5	68.7
1-3/16-12	36	18	130
1-7/16-12	41	21	152
1-11/16-12	50	35	253

4) FITTING

Thread size	Width across flat (mm)	kgf ∙ m	lbf ⋅ ft
1/4"	19	4	28.9
3/8"	22	5	36.2
1/2"	27	9.5	68.7
3/4"	36	18	130
1"	41	21	152
1-1/4"	50	35	253

GROUP 3 PUMP DEVICE

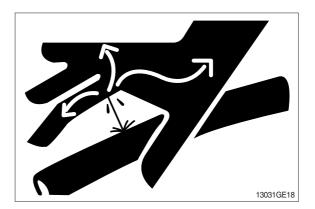
1. REMOVAL AND INSTALL

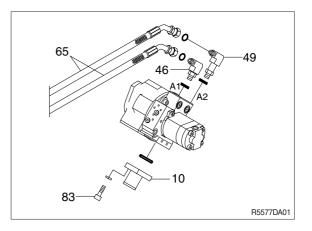
1) REMOVAL

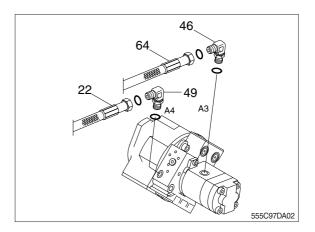
- Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrate the skin causing serious injury.
- (4) Loosen the drain plug under the hydraulic tank and drain the oil from the hydraulic tank.
 - Hydraulic tank quantity : 70 l

(18.5 U.S.gal)

- (5) Disconnect hydraulic hoses (22, 64, 65).
- (6) Remove socket bolts (83) and disconnect pump suction pipe (10).
- When pump suction pipe is disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (7) Sling the pump assembly and remove the pump mounting bolts.
 - Weight : 30 kg (70 lb)
- Pull out the pump assembly from housing. When removing the pump assembly, check that all the hoses have been disconnected.





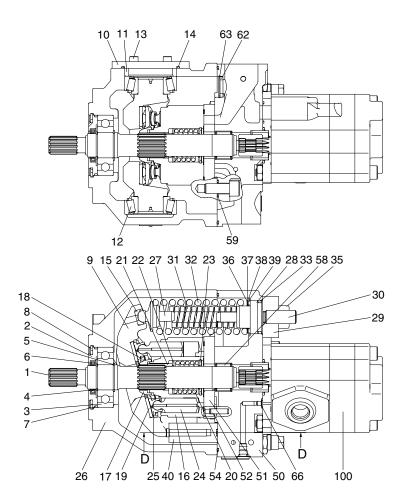


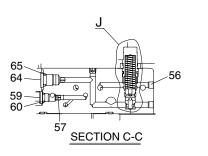
2) INSTALL

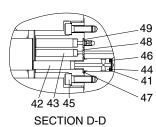
- (1) Carry out installation in the reverse order to removal.
- (2) Remove the suction strainer and clean it.
- (3) Replace return filter with new one.
- (4) Remove breather and clean it.
- (5) After adding oil to the hydraulic tank to the specified level.
- (6) Bleed the air from the hydraulic pump.
- ① Loosen the air vent plug.
- ② Start the engine, run at low idling, and check oil come out from plug.
- ③ Tighten plug.
- (7) Start the engine, run at low idling (3~5 minutes) to circulate the oil through the system.
- (8) Confirm the hydraulic oil level and check the hydraulic oil leak or not.

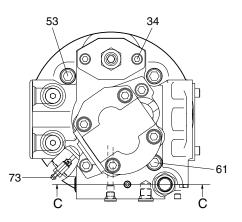
2. MAIN PUMP

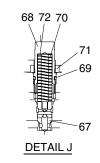
1) STRUCTURE











- 1 Drive shaft
- 2 Seal cover
- 3 Ball bearing
- 4 Snap ring
- 5 Snap ring
- 6 Oil seal
- 7 O-ring
- Snap ring 8
- 9 Swash plate
- 10 Plate
- 11 Bearing spacer
- 12 Roller bearing
- 13 Socket bolt

- 14 O-ring
- 15 Pivot
- 16 Cylinder block
- 17 Bushing
- 18 Push plate
- 19 Shoe plate
- 20 Spring
- 21 Parallel pin
- 22 Spring seat
- 23 Snap ring
- 24 Piston
- 25 Shoe
- 26 Pump casing
- 27 Spring seat(1) 28 Spring seat(2) 29 Spring cover 30 Adjusting screw 31 Spring 32 Spring 33 O-ring 34 Socket bolt 35 Hex nut
- 36 Shim 37 Shim
- 38 Shim

41 Control piston 42 Control push-rod(1) 43 Control push-rod(2) 44 Spring seat(1) 45 Socket bolt 46 Conical spring washer 47 O-ring 48 O-ring 49 O-ring 50 Valve block

40 Control cylinder

39 Shim

- 51 Valve plate 52 Parallel pin 53 Socket bolt 54 O-ring 55 O-ring 56 Plug 57 Orifice 58 Needle bearing 59 RP plug 60 O-ring
 - 61 Socket bolt 62 Filter

7-9

555C92SF06

63 Snap ring

O-ring

O-ring

Spring

73 Air breather

100 Gear pump assy

71 Hex nut

72 Shim

68 Adjusting screw

65 O-ring

67 Spool

66

69

70

- 64 RO plug

2) TOOLS AND TIGHTENING TORQUE

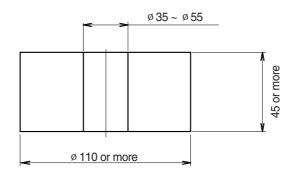
(1) Tools

The tools necessary to disassemble/reassemble the pump are shown in the follow list.

Name	Quantity	Size (nominal)	
Hexagonal bar spanner	One each	5, 6, 8, 10	
Spanner	1	17, 24	
Plastic hammer	1	Medium size	
Snap ring pilers	1	For hole (stop ring for 72)	
Snap ring pilers	1	For shaft (stop rings for 28 and 30)	
Standard screw-driver	2	Medium size	
Torque wrench	-	Wrench which can tighten at the specified torque	
Grease	Small	-	
Adhesives	Small	LOCTITE #270	

(2) Jigs

① Disassembling table

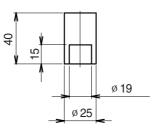


R55NM7HP01

This is plate to stand the pump facing downward.

A square block may be used instead if the shaft end does not contact.

② Bearing assembling jig



R55NM7HP02

(3) Tightening torque

Dort nome	Bolt size	Torque		Wrench size	
Part name		kgf ∙ m	lbf ⋅ ft	in	mm
Hexagon socket head bolt	M 6	1.2	8.7	0.20	5
	M 8	3.0	21.7	0.24	6
	M12	10.0	72.3	0.39	10
	M16	24.0	174	0.55	14
	M18	34.0	246	0.55	14
PT Plug	PT 1/16	0.9	6.5	0.16	4
PF Plug	PF 1/8	1.5	10.8	0.20	5
	PF 1/4	3.0	21.7	0.24	6

3. DISASSEMBLY PROCEDURE

1) DISASSEMBLING THE GEARED PUMP

- Remove the hexagonal socket headed bolts (M10 × 25, 2 pieces). Hexagonal bar spanner (Hex. side distance : 8)
- Be careful because the O-ring and filter are provided to the match surface of the geared pump.
- 2 Remove the coupling.



R55NM7HP03



R55NM7HP04

2) DISASSEMBLING THE MAIN PUMP

 Remove the cover.
 Remove the hexagonal socket headed bolts. (M12 × 30, 3pieces) and (M12× 55, 1piece).
 Hexagonal bar spanner (Hex. side distance : 10)



R55NM7HP05

② Remove the cover in a horizontal condition.

Connect motor to work table.

 Be careful because the control plate is provided to the backside.
 When the cover is difficult to remove, knock lightly with a plastic hammer.



R55NM7HP06

 $\ensuremath{\textcircled{}}$ This photo shows the state with the cover removed.



R55NM7HP07

4 Remove the O-ring from the cover.

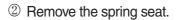
(1) The removal of the control spring ① Remove 2 springs (inner and outer).



R55NM7HP08



R55NM7HP09





R55NM7HP10

(2) The removal of rotary group

① Lay the pump on the side and take out the rotary group from the shaft.



R55NM7HP11

② Remove the plate.



(3) The removal of the shaft

① Remove the C-type stop ring. (snap ring pliers for hole)



R55NM7HP13

⁽²⁾ Use two standard screw-drivers to remove the oil seal case.



③ Remove the O-ring.



R55NM7HP15

④ Remove it while knocking the shaft rear and lightly with a plastic hammer.



R55NM7HP16

(4) The removal of the hanger

 Remove the hexagonal socket headed bolts (M6 \times 16, 4pieces) and plate. Hexagonal bar spanner (Hex. side distance : 5)







③ Remove the bearing.



R55NM7HP19

④ Remove the hanger.



- (5) The removal of the cover
- ① Remove the control plate.





R55NM7HP22

7-16

2 Remove the C-type stop ring.

③ Remove the filter.



R55NM7HP23

(6) The removal of the control piston

 Remove the hexagonal socket headed bolts. (M8 × 25, 2pieces) Hexagonal bar spanner (Hex. side distance : 6) The threaded portion of the bolt is coated with LOCTITE #270. This disassembly must therefore be made only when necessary.



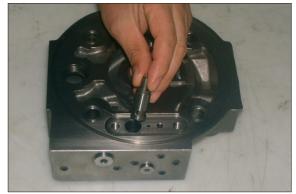
② Remove the cylinder and parallel pin.

③ Take out the piston.

* Be careful because 3 O-rings are provided to the cylinder.



R55NM7HP25



4 Take out three caned disk springs and spring seats.

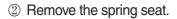


R55NM7HP27

(7) The removal of the control spring

 Remove the hexagonal socket headed bolts (M8 \times 30, 2pieces) and remove the cover.

Hexagonal bar spanner (Hex. side distance : 6).





R55NM7HP28



(8) The removal of the relief valve

- ① Remove the hexagonal nuts.
- * Since the pressure has been set, this assembly must be made only when necessary.

Spanner (Hex. side distance : 24).



R55NM7HP30

- ② Remove the adjusting screw.
- * Be careful because the shim is inserted.



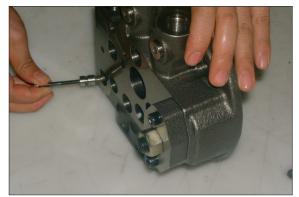
R55NM7HP31

③ Remove the spring.

④ Remove the spool.



R55NM7HP32



(9) Disassembly of the shaft

Remove the bearing.
 Remove the C-type stop ring.
 Snap ring pliers for shaft.



R55NM7HP34

② Remove it while knocking the rear end of shaft lightly with a plastic hammer.



R55NM7HP35

3) DISASSEMBLING THE GEARED PUMP

(1) Disassembling the P3 and P4 pump

① Removed hexagonal socket head bolt and nut.

Hexagonal socket wrench (8 mm). Hexagonal bar spanner (17 mm).



R55NM7HP209

(2) Disassembling the geared pump (P4)

① Remove the geared pump (P4) from the center frame.



R55NM7HP208

② Pulling out the drive gear and the idle gear.



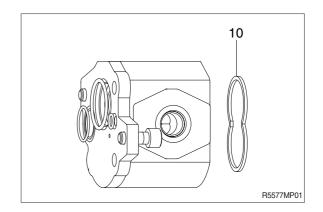
R55NM7HP207

③ Remove the O-ring from the center frame.



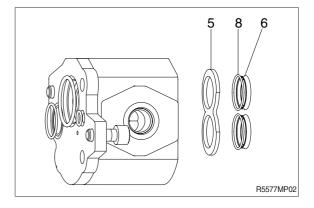
(3) Disassembling the geared pump (P3)

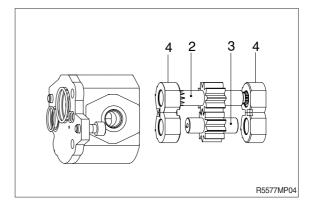
① Remove the square ring (10).



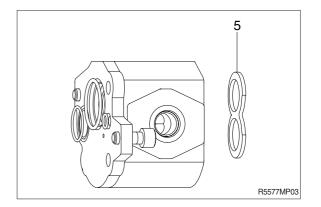
② Remove the plate (5) and the guide ring (pieces). With O-ring (6, 8).
 Remove the O-ring (8) from guide ring (6).

③ Remove the drive and idle gear (2, 3) and the side plate (4) assembly.





④ Remove the plate



4. ASSEMBLING PROCEDURE

1) ASSEMBLING THE MAIN PUMP

(1) Assembling the hanger.



R55NM7HP50

(2) Install the bearing.



R55NM7HP50A

(3) Install the distance piece. Confirm that pre-load is 0.1 \pm 0.2.



R55NM7HP51

(4) Fix the plate with the hexagonal socket headed bolts (M6 \times 16, 4pieces). Hexagonal bar spanner (Hex. side distance : 5) Tightening torque : 1.2 ~ 1.5 kgf \cdot m (8.7 ~ 10.8 lbf · ft)



(5) Assembling the shaft

- Fit the shaft into the bearing (with the bearing in the bottom) by using the press machine and jig. If the press is not available, use the jig in the similar manner and drive the shaft into the bearing by knocking with a plastic hammer.
- ② Install the C-type stop ring to fix the bearing.



R55NM7HP53



R55NM7HP54

③ Assembling the shaft.
 Assemble the shaft into the housing.
 Knock the spline end lightly with a plastic hammer and fix the bearing outer ring firmly into the housing hole.

R55NM7HP55

(6) Apply grease to the O-ring for assembling.



- (7) Install the case with oil seal vertically without tilting.
- * Apply grease to the oil seal lip beforehand.



R55NM7HP57

(8) Install the C-type stop ring to fix the shaft.



R55NM7HP58

(9) Assembling the rotary group.Install 10 (ten) pistons into the retainer.



R55NM7HP59

(10) Apply grease to 3 parallel pins and assemble them to the cylinder block.



(11) Apply grease to the spherical portion of the guide.



R55NM7HP61

(12) Insert the guide between the retainer and cylinder block and assemble the piston into the hole of cylinder block.



R55NM7HP62

(13) Assembling the rotary group.To prevent dislodgement, apply grease to the back side of the plate and assemble it to the hanger.



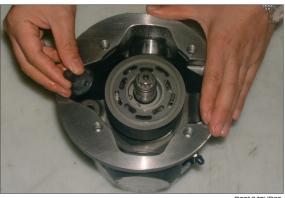
R55NM7HP63

- (14) Assemble the rotary group along the shaft spline.
- During assembly, apply grease to the slide surface of piston shoe and to the slide surface of the cylinder block relative to the control plate.



R55NM7HP64

(15) Assembling the control spring. Apply grease to the spherical portion of the spring seat before assembling.



R55NM7HP65

(16) Assemble 2 springs (inner and outer).

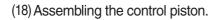


R55NM7HP66

(17) Assembling the cover. Assemble the spring seats and coned disk springs (3 pieces).



R55NM7HP67





(19) Apply grease to the O-rings

(5.28 × 1.78, 1piece), (7.65 × 1.78, 1piece) and (15.6×1.78, 1piece) and assemble them to the cylinder.



R55NM7HP69

(20) Apply grease to 3 parallel pins and assemble 3 pins into the cylinder.



R55NM7HP70

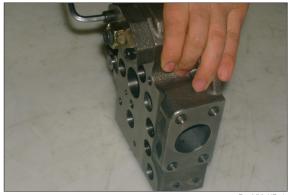
- (21) Fix the cylinder with the hexagonal socket headed bolts (M8×25, 2pieces).
- * Apply LOCTITE #270 to the threaded portion of bolt. Hexagonal bar spanner (Hex. side distance : 6) Tightening torque : 2.9 ~ 3.5 kgf · m (21 ~ 25.3 lbf · ft)
- (22) Assembling the control spring. Install the spring seat.



R55NM7HP71



(23) Fix the cover with the hexagonal socket headed bolts (M8×30, 2pieces) Hexagonal bar spanner (Hex. side distance : 6) Tightening torque : 2.9 ~ 3.5 kgf \cdot m (21 ~ 25.3 lbf · ft)



R55NM7HP73

(24) Apply grease to the back side of the control plate and assemble it to the cover while matching knock holes.



R55NM7HP74

(25) Install the O-ring. Assemble the spring seats and coned disk springs (3pieces).

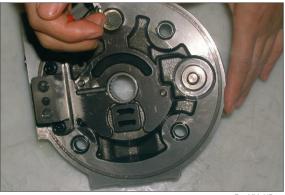


R55NM7HP75





(27) Fix the filter with the C-type stop ring.



R55NM7HP77



R55NM7HP78



R55NM7HP79



R55NM7HP80

(28) Assembling the relief valve. Assemble the spool.

(29) Assemble the spring.

(30) Insert the shim into the adjusting screw.

(31) Assemble the adjusting screw.



R55NM7HP81

(32) Tighten the hexagonal nuts.
After assembling, set the pressure and tighten the nuts.
1 kgf · m (7.2 lbf · ft)
Spanner (Hex. side distance : 24)



R55NM7HP82

(33) Install the cover in a parallel direction to the housing mounting surface.



R55NM7HP83

(34) Fix the cover with the hexagonal socket headed bolts (M12 \times 30, 3pieces) and (M12 \times 55, 1piece) Hexagonal bar spanner (Hex. side distance :10) Tightening torque : 10 ~ 12.5 kgf \cdot m (72.3 ~ 90.4 lbf \cdot ft)



(35) Install the O-ring into the cover.



R55NM7HP85

(36) Install the coupling to the shaft end of the main pump.



R55NM7HP86

(37) Connect the main and geared pump.



R55NM7HP87

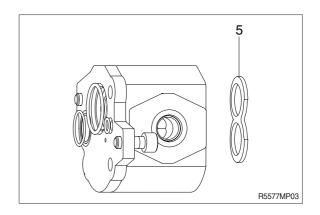
(38) Fix the geared pump with the hexagonal socket headed bolts (M10 \times 25, 2pieces). Hexagonal bar spanner (Hex. side distance : 8) Tightening torque : 5.6 ~ 7.0 kgf \cdot m (40.5 ~ 50.6 lbf · ft)



4) REASSEMBLING THE GEARED PUMP

(1) Reassembling the geared pump (P3)

① Insert the plate (5) to the pump housing.



- 2 Insert the square ring into the side plate.
- * Be careful to suction and discharge side.



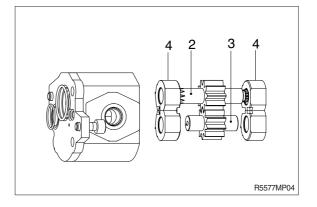
R55NM7HP210

③ Assemble the side plate to the drive and idle gear.



R55NM7HP211

④ Assemble the gear assembly into the gear casing.

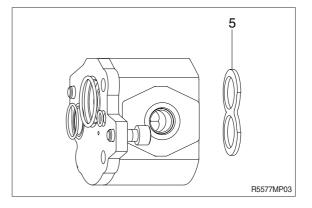


(5) Assemble the O-ring to the guide ring and assemble them to the plate.

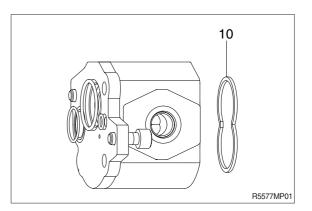


R55NM7HP213

⑥ Assemble the guide ring assembly (6, 8) and plate (5) to the gear casing.



⑦ Assemble the square ring (10) to the gear casing.



(2) Reassembling the geared pump (P4)

① Insert the drive gear into the gear casing.



R55NM7HP219

② Insert the idle gear to into the gear casing.



R55NM7HP220

③ Insert the pins (2-pieces) to the center frame.

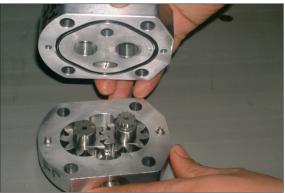


R55NM7HP221

4 Assemble the O-ring to the center frame.



⑤ Assemble the center frame subassemble to the gear casing subassembly.



R55NM7HP223

(3) Reassembling the P3 and P4 pumps

① Insert the pins (2-pieces) into the center frame.



R55NM7HP224

② Insert coupling to the P3 geared pump.



R55NM7HP225

③ Assemble the P3 and P4 geared pumps.



- ④ Assemble the hexagonal socket bolts and nuts.
- · Size : M10 \times 65L, 4pieces
- Allen wrench : 8 mm
- Spanner : 17 mm
- \cdot Tightening torque : 580 kgf \cdot cm
 - (56.9 N · m)
- ⑤ Assemble the O-ring to the pump housing.



R55NM7HP227



R55NM7HP228

GROUP 4 MAIN CONTROL VALVE

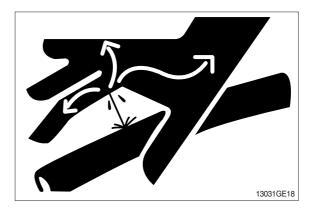
1. REMOVAL AND INSTALL OF MOTOR

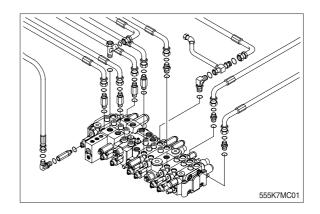
1) REMOVAL

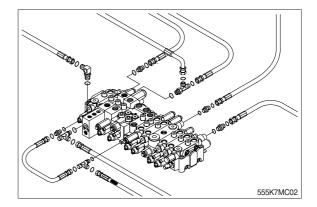
- Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrate the skin causing serious injury.
- When pipes and hoses are disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (4) Disconnect hydraulic hose.
- (5) Disconnect pilot line hoses.
- (6) Remove links.
- (7) Sling the control valve assembly and remove the control valve mounting bolt.
 Weight : 40 kg (90 lb)
- (8) Remove the control valve assembly. When removing the control valve assembly, check that all the piping have been disconnected.

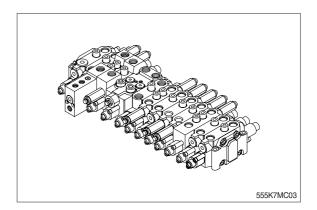
2) INSTALL

- (1) Carry out installation in the reverse order to removal.
- (2) Bleed the air from below items.
- ① Cylinder (boom, arm, bucket)
- ② Swing motor
- ③ Travel motor
- $\ast~$ See each item removal and install.
- (3) Confirm the hydraulic oil level and recheck the hydraulic oil leak or not.

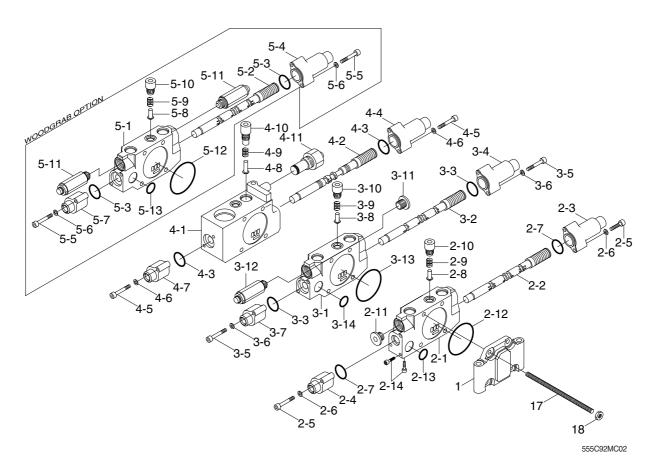








2. STRUCTURE (1/4)

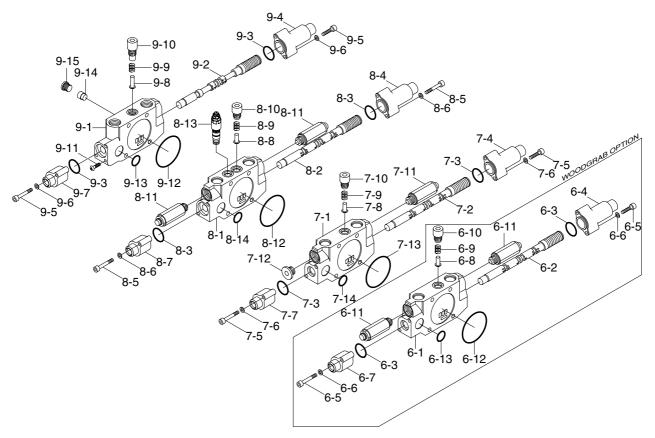


- 1 Cover
- 2 Swing block
- 2-1 Block
- 2-2 Swing spool assy
- 2-3 Pilot cap (A)
- 2-4 Pilot cap (B1)
- 2-5 Wrench bolt
- 2-6 Plain washer
- 2-7 O-ring
- 2-8 Check poppet
- 2-9 Check spring
- 2-10 Plug
- 2-11 Plug
- 2-12 O-ring
- 2-13 O-ring
- 2-14 Plug
- 3 Dozer block
- 3-1 Block
- 3-2 Dozer spool assy
- 3-3 O-ring

- 3-4 Pilot cap (A)
- 3-5 Wrench bolt
- 3-6 Plain washer
- 3-7 Cap
- 3-8 Check poppet
- 3-9 Check spring
- 3-10 Plug
- 3-11 Plug
- 3-12 Check valve
- 3-13 O-ring
- 3-14 O-ring
 - 4 Inlet block
- 4-1 Block
- 4-2 Inlet spool assy
- 4-3 O-ring
- 4-4 Pilot cap (A)
- 4-5 Wrench bolt
- 4-6 Plain washer
- 4-7 Pilot cap (B1)
- 4-8 Check poppet

- 4-9 Check spring
- 4-10 Plug
- 4-11 Main relief valve
- 5 Swing block
- 5-1 Block
- 5-2 Swing spool assy
- 5-3 O-ring
- 5-4 Pilot cap (A)
- 5-5 Wrench bolt
- 5-6 Plain washer
- 5-7 Pilot cap (B1)
- 5-8 Check poppet
- 5-9 Check spring
- 5-10 Plug
- 5-11 Overload relief valve
- 5-12 O-ring
- 5-13 O-ring
- 17 Tie bolt
- 18 Nut

STRUCTURE (2/4)



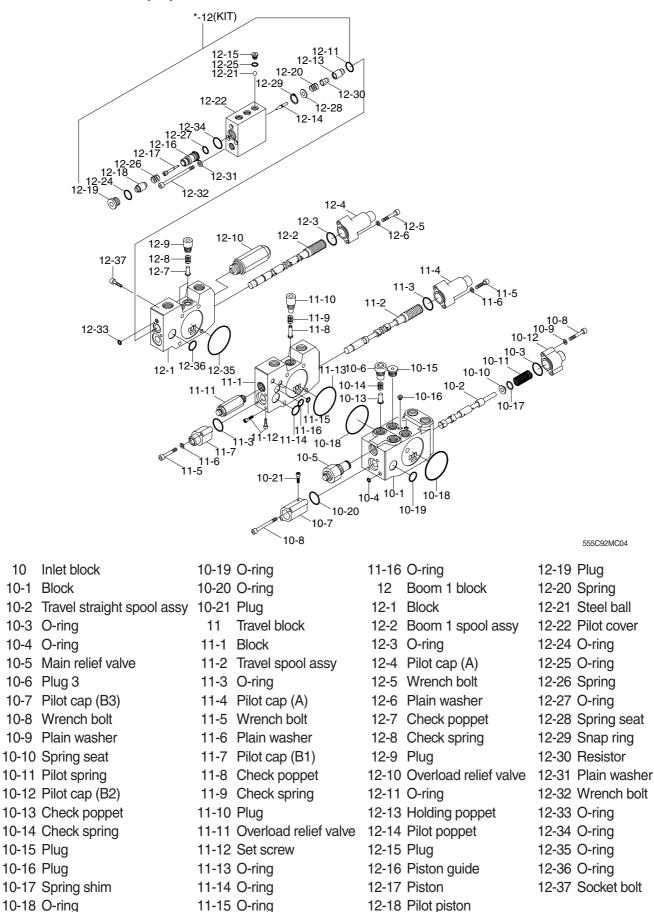
555C92MC03

- 6 Woodgrab block
- 6-1 Block
- 6-2 Woodgrab spool assy
- 6-3 O-ring
- 6-4 Pilot cap (A)
- 6-5 Wrench bolt
- 6-6 Plain washer
- 6-7 Pilot cap (B1)
- 6-8 Check poppet
- 6-9 Check spring
- 6-10 Plug
- 6-11 Overload relief valve
- 6-12 O-ring
- 6-13 O-ring
- 7 Boom 2 block
- 7-1 Block
- 7-2 Boom 2 spool assy
- 7-3 O-ring
- 7-4 Pilot cap (A1)
- 7-5 Wrench bolt

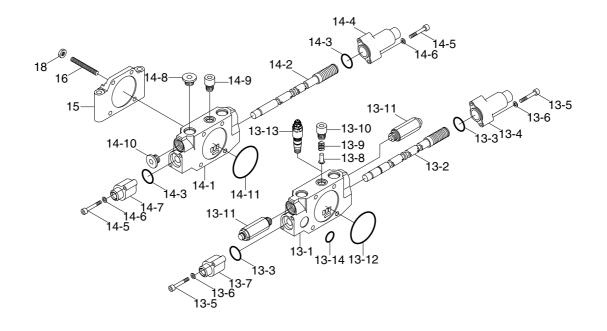
- 7-6 Plain washer
- 7-7 Pilot cap (B1)
- 7-8 Check poppet
- 7-9 Check spring
- 7-10 Plug
- 7-11 Overload relief valve
- 7-12 Plug
- 7-13 O-ring
- 7-14 O-ring
- 8 Arm 1 block
- 8-1 Block
- 8-2 Arm 1 spool assy
- 8-3 O-ring
- 8-4 Pilot cap (A)
- 8-5 Wrench bolt
- 8-6 Plain washer
- 8-7 Pilot cap (B1)
- 8-8 Check poppet
- 8-9 Check spring
- 8-10 Plug

- 8-11 Overload relief valve
- 8-12 O-ring
- 8-13 Check valve
- 8-14 O-ring
 - 9 Travel block
- 9-1 Block
- 9-2 Travel spool assy
- 9-3 O-ring
- 9-4 Pilot cap (A)
- 9-5 Wrench bolt
- 9-6 Plain washer
- 9-7 Pilot cap (B1)
- 9-8 Check poppet
- 9-9 Check spring
- 9-10 Plug
- 9-11 Plug
- 9-12 O-ring
- 9-13 O-ring
- 9-14 Poppet
- 9-15 Spring seat

STRUCTURE (3/4)



7-41



13 Bucket block
13-1 Block
13-2 Bucket spool assy
13-3 O-ring
13-4 Pilot cap (A)
13-5 Wrench bolt
13-6 Plain washer
13-7 Pilot cap (B1)
13-8 Check poppet
13-9 Check spring

13-10 Plug
13-11 Relief valve
13-12 O-ring
13-13 Check valve
13-14 O-ring
14-1 Arm 2 block
14-2 Arm 2 assy
14-3 O-ring
14-4 Pilot cap (A)

14-5 Wrench bolt14-6 Plain washer14-7 Pilot cap (B1)14-8 Plug14-9 Plug14-10 Plug

555C92MC05

- 14-11 O-ring
- 15 Cover
- 16 Tie bolt
- 18 Nut

3. DISASSEMBLY AND ASSEMBLY

1) GENERAL PRECAUTIONS

- (1) All hydraulic components are manufactured to a high precision. Consequently, before disassembling and assembling them, it is essential to select an especially clean place.
- (2) In handling a control valve, pay full attention to prevent dust, sand, etc. from entering into it.
- (3) When a control value is to be remove from the machine, apply caps and masking seals to all ports. Before disassembling the value, recheck that these caps and masking seals are fitted completely, and then clean the outside of the assembly. Use a proper bench for working. Spread paper or a rubber mat on the bench, and disassemble the value on it.
- (4) Support the body section carefully when carrying or transferring the control valve. Do not lift by the exposed spool, end cover section etc.
- (5) After disassembling and assembling of the component it is desired to carry out various tests (for the relief characteristics, leakage, flow resistance, etc.), but hydraulic test equipment is necessary for these tests. Therefore, even when its disassembling can be carried out technically, do not disassemble such components that cannot be tested, adjusted, and so on. Additionally one should always prepare clean cleaning oil, hydraulic oil, grease, etc. beforehand.

2) TOOLS

Before disassembling the control valve, prepare the following tools beforehand.

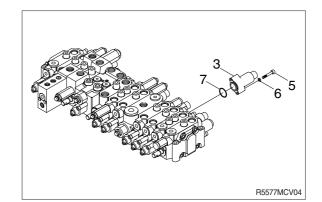
Name of tool	Quantity	Size (mm)
Vice mounted on bench (soft jaws)	1 unit	
Hexagon wrench	Each 1 piece	5, 6, 10, 12 and 14
Socket wrench	Each 1 piece	5 and 6
Spanner	Each 1 piece	13, 21 and 30
Rod	1 piece	Less than 10×250

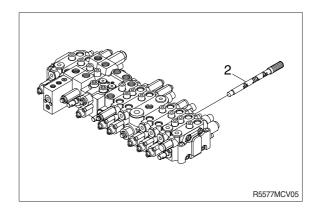
3) DISASSEMBLY

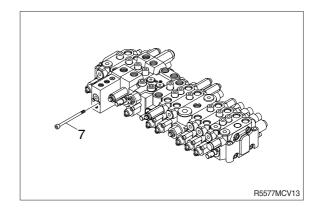
- (1) Disassembly of spools (pilot type)
- Loosen hexagon socket head bolts (5) with washer (6). (Hexagon wrench : 5 mm)
- ② Remove the pilot cover (3).
- * Pay attention not to lose the O-ring (7) under the pilot cover.
- ③ Remove the spool assembly (2) from the body by hand slightly.
- When extracting each spool from its body, pay attention not to damage the body.
- When extracting each spool assembly, it must be extracted from spring side only.
- When any abnormal parts are found, replace it with completely new spool assembly.
- When disassembled, tag the components for identification so that they can be reassembled correctly.

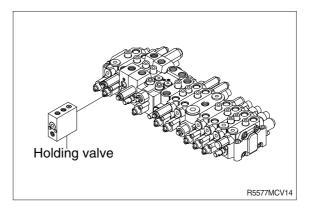
(2) Disassembly of holding valve (boom 1)

- Loosen hexagon socket head bolts (7). (Hexagon wrench : 5 mm)
- ② Remove the holding valve.
- * Pay attention not to lose the O-ring and the poppet under the pilot cover.
- * Pay attention not to damage the "piston A" under pilot cover.
- When any abnormal parts are found, replace it with completely new holding valve assembly.
- When disassembled, tag the components for identification so that they can be reassembled correctly.

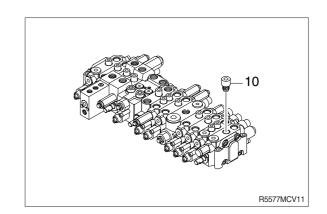


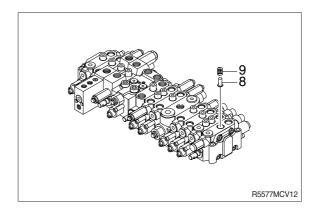






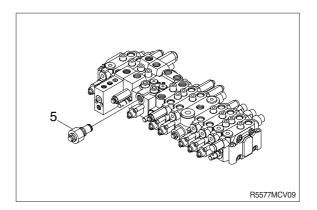
- (3) Disassembly of the load check valve and the negative relief valve
- 1 The load check valve
 - a. Fix the body to suitable work bench.
 - * Pay attention not to damage the body.
 - b. Loosen the plug (10) (Hexagon wrench : 10 mm).
 - c. Remove the spring (9) and the load check valve (8) with pincers or magnet.

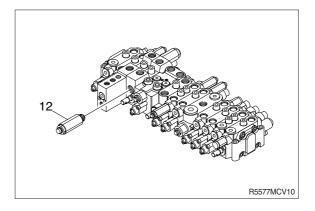




(4) Disassembly of the main and overload relief valve

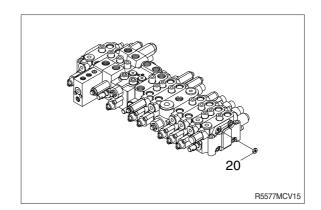
- T is the body to suitable work bench.
- ② Remove the main relief valve (5). (Spanner : 30 mm)
- ③ Remove the overload relief valve (12).(Spanner : 22 mm)
- When disassembled, tag the relief valve for identification so that they can be reassembled correctly.
- * Pay attention not to damage seat face.
- When any abnormal parts are found, replace it with completely new relief valve assembly.

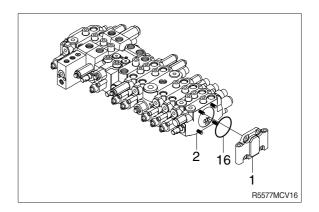




(5) Disassembly of the block assembly

- Tix the body to suitable work bench.
- ② Remove the nut (20).(Spanner : 13 mm)
- * The work block is assembled by two sets of tie-bolts.
- ③ Remove the end cover (1) and the work blocks.
- * Do not removed the tie bolt.
- * Pay attention not to lose the O-ring (16).





(6) Inspection after disassembly

Clean all disassembled parts with clean mineral oil fully, and dry them with compressed air. Then, place them on clean papers or cloths for inspection.

1 Control valve

- a. Check whole surfaces of all parts for burrs, scratches, notches and other defects.
- b. Confirm that seal groove faces of body and block are smooth and free of dust, dent, rust etc.
- c. Correct dents and damages and check seat faces within the body, if any, by lapping.
- * Pay careful attention not to leave any lapping agent within the body.
- d. Confirm that all sliding and fitting parts can be moved manually and that all grooves and path's are free foreign matter.
- e. If any spring is broken or deformed, replace it with new one.
- f. When a relief valve does not function properly, repair it, following it's the prescribed disassembly and assembly procedures.
- g. Replace all seals and O-rings with new ones.

2 Relief valve

- a. Confirm that all seat faces at ends of all poppets and seats are free of defects and show uniform and consistent contact faces.
- b. Confirm manually that main poppet and seat can slide lightly and smoothly.
- c. Confirm that outside face of main poppet and inside face of seat are free from scratches and so on.
- d. Confirm that springs are free from breakage, deformation, and wear.
- e. Confirm that orifices of main poppet and seat section are not clogged with foreign matter.
- f. Replace all O-rings with new ones.
- g. When any light damage is found in above inspections, correct it by lapping.
- h. When any abnormal part is found, replace it with a completely new relief valve assembly.

4) ASSEMBLY

(1) General precaution

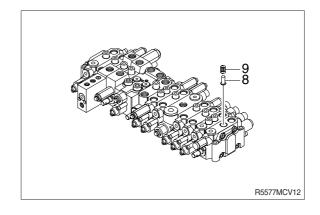
① In this assembly section, explanation only is shown.

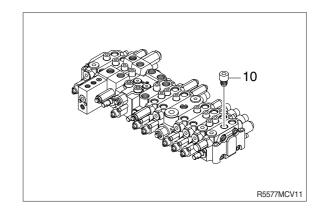
For further understanding, please refer to the figures shown in the previous structure & disassembly section.

- ② Pay close attention to keeping all seals free from handling damage and inspect carefully for damage before using them.
- ③ Apply clean grease or hydraulic oil to the seal so as to ensure it is fully lubricated before assembly.
- ④ Do not stretch seals so much as to deform them permanently.
- ⑤ In fitting O-rings, pay close attention not to roll them into their final position in addition, a twisted O-ring cannot easily untwist itself naturally and could thereby cause inadequate sealing and thereby both internal and external oil leakage.
- ⑥ Tighten fitting bolts for all sections with a torque wrench adjusted to the respective tightening torque.
- ⑦ Do not reuse removed O-rings and seals.

(2) Load check valve

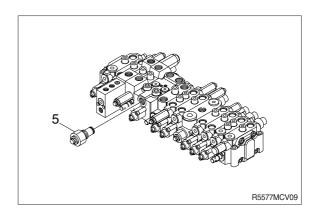
- Assemble the load check valve (8) and spring (9).
- 2 Put O-rings on to plug (10).
- ③ Tighten plug to the specified torque.
 - · Hexagon wrench : 8 mm
 - Tightening torque : 3.7 kgf · m (26.7 lbf · ft)

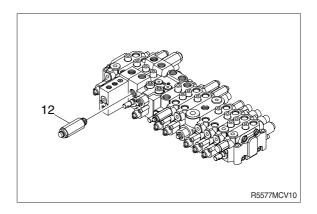




(3) Main relief, port relief valves

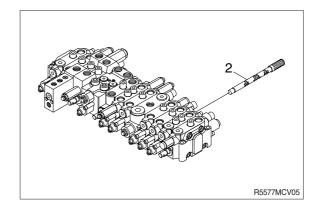
- 1 Install the main relief value (5).
 - Spanner : 30 mm
 - · Tightening torque : 6 kgf · m (43.4 lbf · ft)
- 2 Install the over load relief valve (12).
 - Spanner : 22 mm
 - \cdot Tightening torque : 4 kgf \cdot m (28.9 lbf \cdot ft)





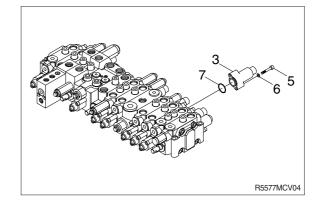
(4) Main spools

- Carefully insert the previously assembled spool assemblies into their respective bores within of body.
- * Fit spool assemblies into body carefully and slowly. Do not under any circumstances push them forcibly in.



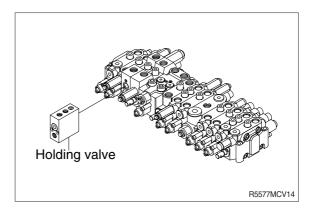
(5) Covers of pilot type

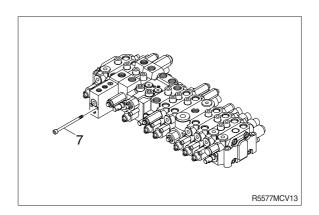
- Fit spool covers (3) tighten the hexagonal socket head bolts (5) to the specified torque.
 - \cdot Hexagon wrench : 5 mm
 - \cdot Tightening torque : 1~1.1 kgf \cdot m (7.2~7.9 lbf \cdot ft)
- * Confirm that O-rings (7) have been fitted.



(6) Holding valve

- Fit the holding valve to the body and tighten hexagon socket head bolt (7) to specified torque.
 - Hexagon wrench : 5 mm
 - Tightening torque : 1.1 kgf m(7.9 lbf ft)





GROUP 5 SWING DEVICE

1. REMOVAL AND INSTALL OF MOTOR

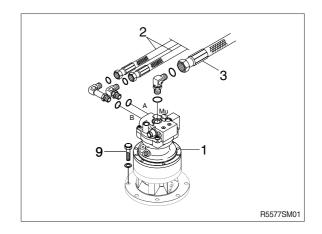
1) REMOVAL

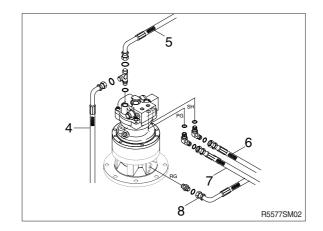
- Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- ▲ Escaping fluid under pressure can penetrate the skin causing serious injury.
- When pipes and hoses are disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (4) Disconnect hose assembly (2, 3).
- (5) Disconnect pilot line hoses (4, 5, 6, 7, 8).
- (6) Sling the swing motor assembly (1) and remove the swing motor mounting bolts (9).
- Motor device weight : 23 kg (51 lb)
- (7) Remove the swing motor assembly.
- When removing the swing motor assembly, check that all the piping have been disconnected.

2) INSTALL

- Carry out installation in the reverse order to removal.
- (2) Bleed the air from the swing motor.
- ① Remove the air vent plug.
- ② Pour in hydraulic oil until it overflows from the port.
- ③ Tighten plug lightly.
- ④ Start the engine, run at low idling and check oil come out from plug.
- 5 Tighten plug fully.
- (3) Confirm the hydraulic oil level and check the hydraulic oil leak or not.

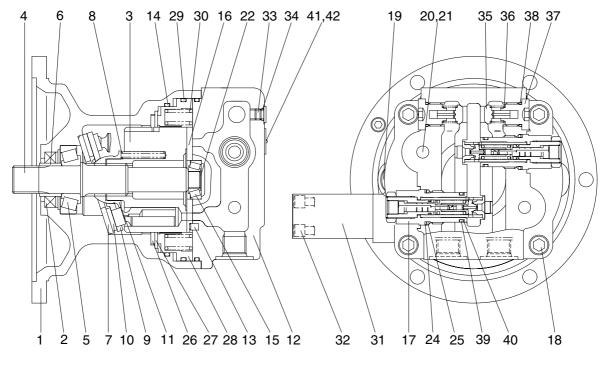






2. DISASSEMBLY AND ASSEMBLY OF SWING MOTOR

1) STRUCTURE



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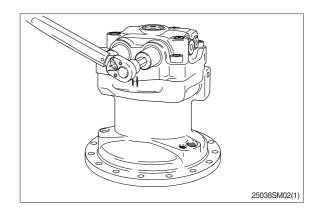
- 1 Body
- 2 Oil seal
- 3 Cylinder block
- 4 Shaft
- 5 Taper bearing
- 6 Bushing
- 7 Shoe plate
- 8 Spring
- 9 Set plate
- 10 Piston shoe assy
- 11 Ball guide
- 12 Rear cover
- 13 Pin
- 14 O-ring

- 15 Taper bearing
- 16 Valve plate
- 17 Relief valve assy
- 18 Socket bolt
- 19 Plug
- 20 Plug
- 21 O-ring
- 22 Shim
- 23 Plug
- 24 Back up ring
- 25 O-ring
- 26 Friction plate
- 27 Plate
- 28 Parking piston

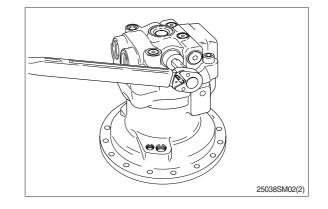
- 29 O-ring
- 30 Spring
- 31 Time delay valve
- 32 Socket bolt
- 33 Plug
- 34 O-ring
- 35 Valve
- 36 Spring
- 37 Plug
- 38 O-ring
- 39 O-ring
- 40 Back up ring
- 41 Name plate
- 42 Rivet

2) DISASSEMBLY

- (1) Removal of relief valve assembly
 Remove cap of relief valve assembly (17)
 with 14 mm hexagonal wrench.
- Assemble removed relief valve assembly (17) to original state when reassembling.

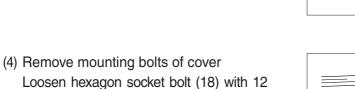


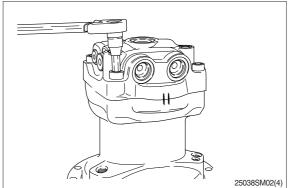
(2) Removal of make up valve and bypass valve assembly
Loosen plug (37) with 14 mm hexagonal wrench, and remove check valve (35) and spring (36).



(3) Marking at swing motor Before disassembling motor, make a matching mark between cover (12) and housing (1) for easy reassembling.

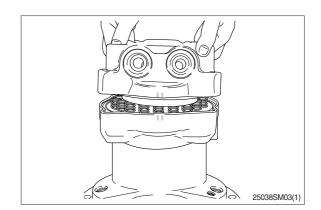
mm hexagonal wrench.



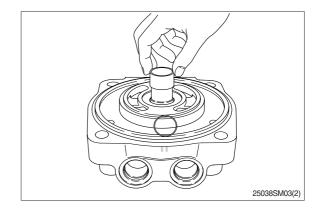


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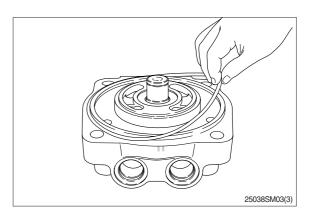
(5) Removal of cover assemblyPlace shaft of motor assembly to downward and take cover (12) out.



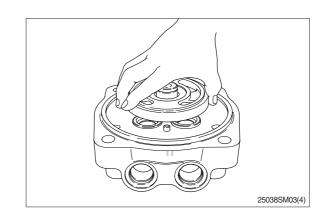
(6) Remove shim (22) remove inner race of needle bearing (15) by bearing puller.



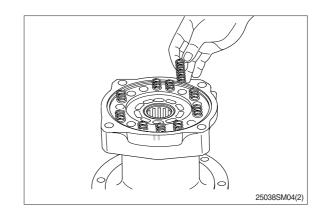
(7) Remove O-ring (29) from cover.



(8) Remove balance plate
Valve plate (16) is adhered on end surface of cylinder (3) by oil viscosity. Take off balance plate (16) with hands.
Assembling method of balance plate (16) depends on cover (12).
(Band groove and round groove of high · low pressure transmission area)
Before removing, check and record location of balance plate (16) to prevent misassembling.

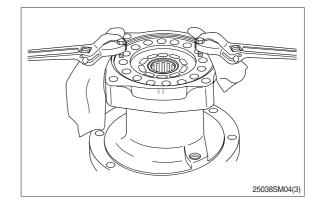


(9) Removal of spring (30, brake area)
 Remove spring (30) from piston (28).
 Check and record original position of each spring (30) for correct assembling.

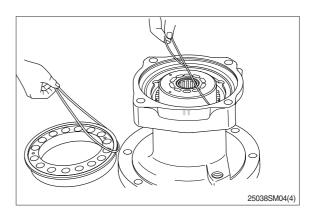


(10) Removal of brake piston

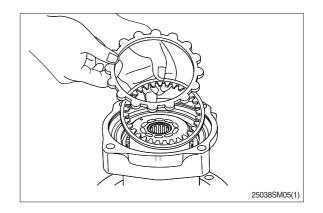
When removing piston (28) from housing (1), there is a sliding resistance against tightening of O-rings (14,29). Use tap hole on piston (28) as shown in the picture.



(11) Remove O-rings (14, 29) from piston (28) and housing (1).



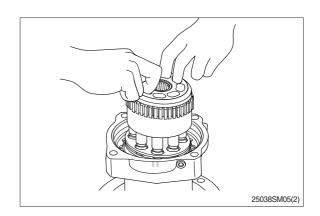
(12) Remove friction plate (26) and lining plate (27) from housing (1).

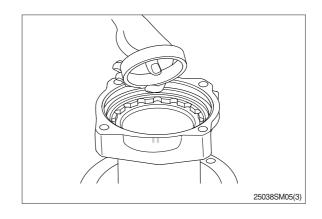


(13) Removal of cylinder assembly

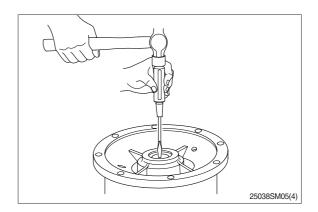
Holding end of cylinder assembly (3) with hand, draw out cylinder assembly from housing.

- * Oil seal (2) and outer race of taper roller bearing (15) are left inside of housing.
- * End surface of cylinder (3) is sliding face . So, protect the surface with a scrap of cloth against damage.
- Make a matching mark on piston hole of cylinder (3) and piston assembly (10) to fit piston into the same hole when reassembling.
- (14) Separate outer race of taper roller bearing(5) from housing.





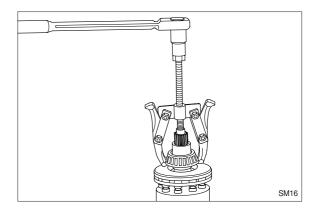
- (15) Removal of oil sealRemove oil seal (2) from housing (1) with driver and hammer.
- * Do not reuse oil seal after removal.



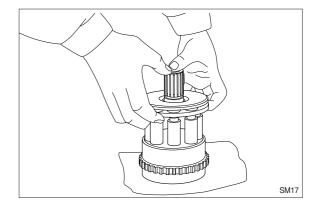
(16) Disassembly of cylinder assembly

 Removal of inner race of taper roller bearing (5).

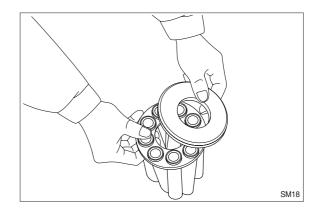
Lift out cylinder block (3) with 2 inner race of roller bearing (5) by applying gear puller at the end of spline in the cylinder.



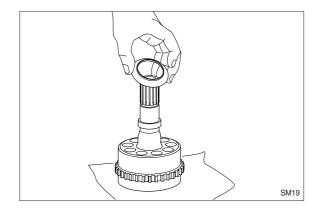
② Separate shoe plate (7), piston assembly (10), set plate (9) from cylinder block (3).



- ③ Get shoe plate (7) slide on sliding face of piston assembly (10) and remove it.
- * Be cautious not to damage on sliding face of cam plate.



④ Remove ball guide (11) from cylinder block (3).



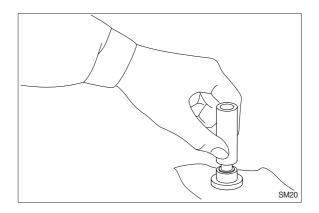
This completes disassembly.

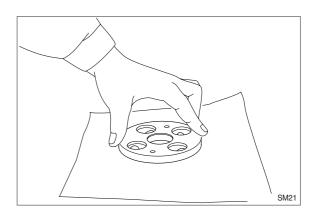
3) ASSEMBLY

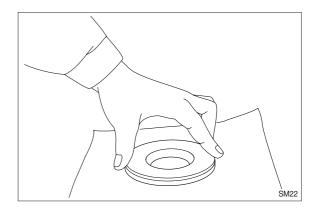
(1) Preparation

Before reassembling, perform below procedure.

- Check each part for damage caused by using or disassembling. If damaged, eliminate damage by grinding with proper sandpaper, wash them with cleaning oil and dry with compressed air.
- 2 Replace seal with new one.
- ③ Grind sliding face of piston assembly (10), balance plate (16) and shoe plate (7) with sandpaper #2000.







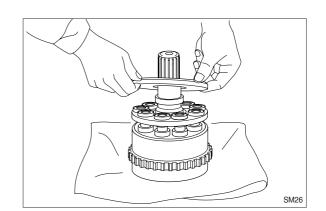
- ④ When assembling, lubricate with specified clean hydraulic oil.
- ⑤ When assembling piston assembly (10) to piston hole of cylinder block (3), check matching mark between them.

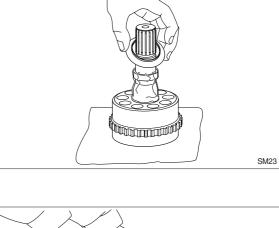
(2) Cylinder assembly

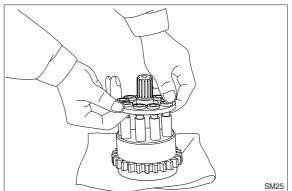
 Lubricate grease on round area (Contacting area withball guide (11)) of cylinder block (3) and assemble spring (4).



- ③ Assemble piston assembly (10) and set plate (9) to cylinder block (3). When assem-
 - Assemble piston assembly (10) and set plate (9) to cylinder block (3). When assembling, check matching mark between them. Before assembling, lubricate specified hydraulic oil in piston hole of cylinder block (3).
- ④ Lubricate specified hydraulic oil on shoe sliding face of piston assembly (10) and assemble shoe plate (7).

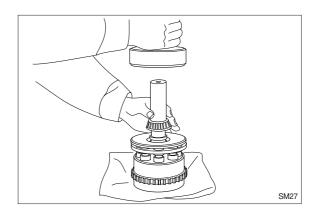




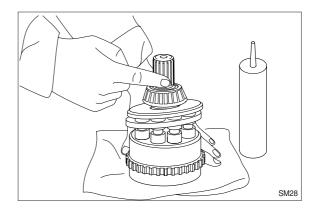


SM24

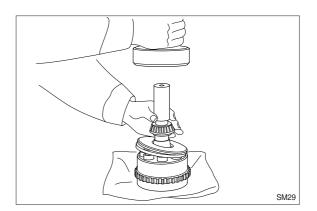
⑤ Assemble inner race of taper roller bearing (5) to cylinder block (3).



⑥ Apply loctite to bearing mounting area of inner race of cylinder block (3) lightly.



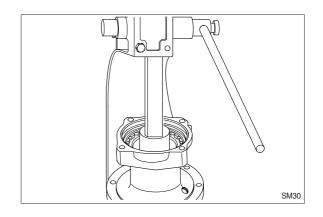
⑦ Assemble bushing (6) to cylinder block (3).



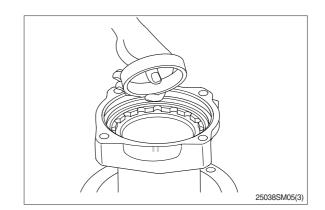
(3) Oil seal

Apply three bond of white color on outer surface of oil seal (2) and assemble and insert it.

* Before assembling, lubricate lip of oil seal with grease.



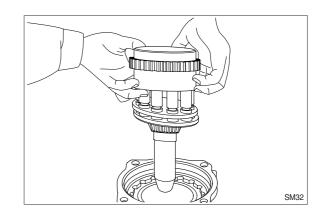
(4) Assemble outer race of taper roller bearing (5) to motor housing (1).

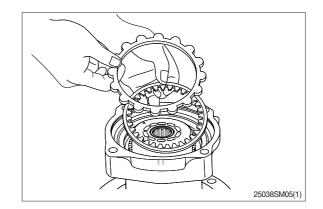


(5) Cylinder assembly

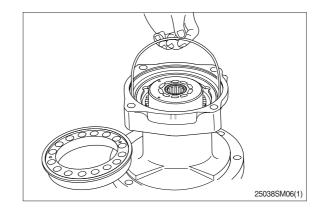
Hold end of cylinder assembly(3) with hands and assemble cylinder assembly to housing(1). Be careful to prevent damage of seal by spline of shaft.

- When assemble cylinder assembly, spline shaft of cylinder is protruded from end of housing, therefore put pads with length 30~50mm under bottom of housing.
- (6) Assemble friction plate (26) and lining plate (27).
- * Lubricate specified hydraulic oil on each side.





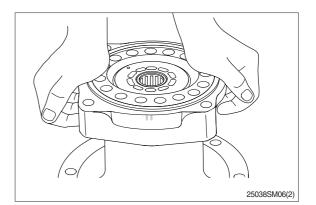
- (7) Insert O-rings (14,29) into housing (1) and piston (28).
- * Lubricate O-ring with grease.



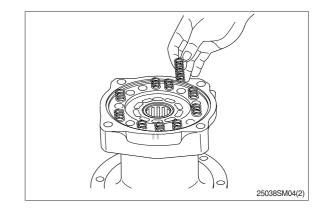
(8) Brake piston

Lubricate specified hydraulic oil on outer sliding face of piston (28) and assemble brake piston to housing (1).

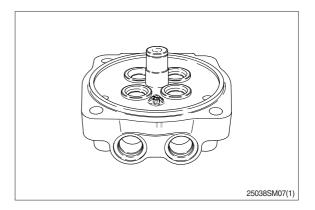
It is too tight to assemble piston (10) because O-rings (14,29) are fitted, therefore it is recommended to push piston (28) horizontally by hands at once.



- (9) Spring (30, brake unit) Assemble spring (30) to piston (28) of brake unit.
- * Insert spring (30) into original position.



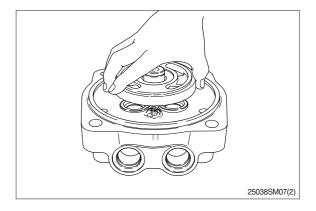
(10) Lubricate locating pin for antirotation of valve plate (16) of cover (12) with grease sufficiently and install locating pin to housing.



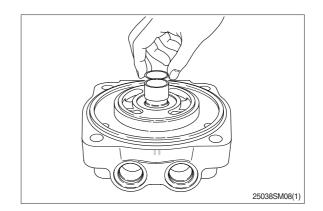
(11) Balance plate

Assemble valve plate (16) to cover (12).

* Be cautious of assembling direction.

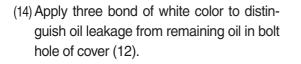


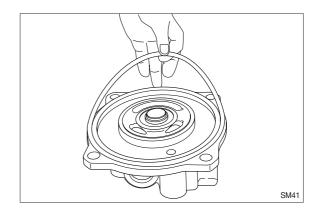
(12) Assemble inner race of needle bearing (15) and shim (22) to cover (12).

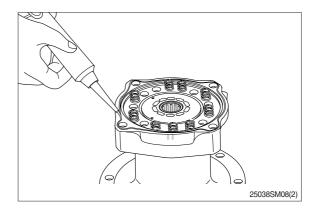


(13) Assemble O-ring (29) to cover (12).

 $\ast~$ Lubricate O-ring with grease.



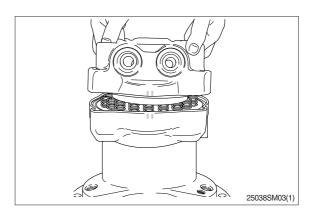




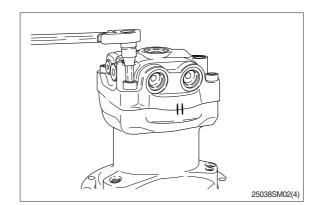
(15) Cover

Assemble cover (12) and valve plate (16) to housing (1) lightly, holding them up with hands.

- When assembling, be careful not to detach valve plate (16) and bushing (6) from cover (12).
- Fit matching marks on housing (1) and cover (12) made before disassembling.



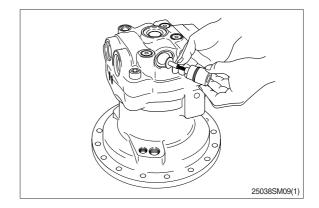
- (16) Tighten cover (12) and housing (1) with 12 mm hexagonal socket bolt (18).
 - Tightening torque : $16 \text{ kgf} \cdot \text{m} (116 \text{ lbf} \cdot \text{ft})$



(17) Make up valve

Assemble check(35) and spring(36) to cover(12) and tighten plug(37) with 14 mm hexagonal socket bolt.

• Tightening torque : $14 \text{ kgf} \cdot \text{m}$ (101 lbf $\cdot \text{ ft}$)

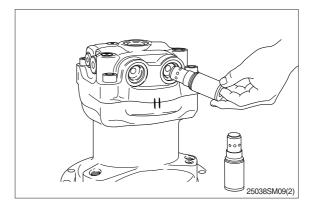


(18) Relief assembly

Assemble relief valve assembly(17) to cover(12) with 14mm hexagonal socket bolt.

 \cdot Tightening torque : 8 kgf \cdot m (58 lbf \cdot ft)

* Be cautious of assembling method.



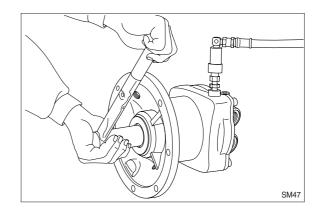
(19) Check of assembly

Load pilot pressure of 20 kgf/cm² to brake release port after opening inlet and outlet port.

Check if output shaft is rotated smoothly around torque of 0.5~1 kgf \cdot m.

If not rotated, disassemble and check.

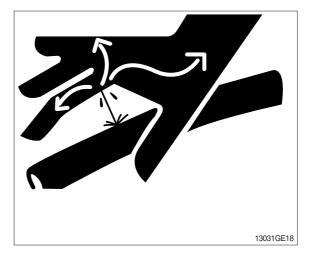
This completes assembly.



3. REMOVAL AND INSTALL OF REDUCTION GEAR

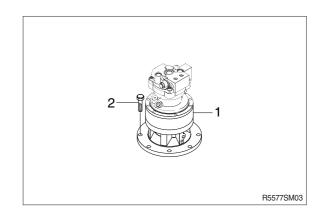
1) REMOVAL

- (1) Remove the swing motor assembly.For details, see removal of swing motor assembly.
- (2) Sling reduction gear assembly (1) and remove mounting bolts (2).
- (3) Remove the reduction gear assembly.
 Reduction gear device weight : 45 kg (99 lb)



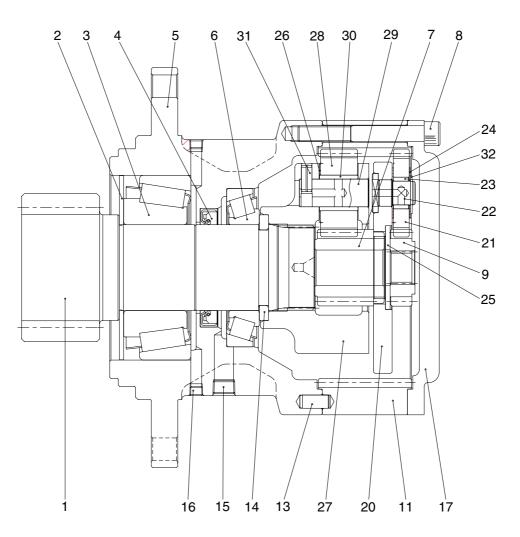
2) INSTALL

- (1) Carry out installation in the reverse order to removal.
 - Tightening torque : 10.5 kgf · m
 (76 lbf · ft)



4. DISASSEMBLY AND ASSEMBLY OF REDUCTION GEAR

1) STRUCTURE



55W72SM02

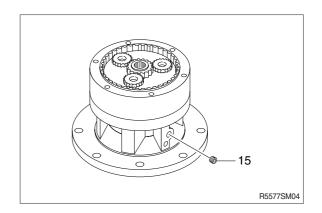
- 1 Shaft
- 2 Bearing cover
- 3 Taper roller bearing
- 4 Case
- 5 Oil seal
- 6 Taper roller bearing
- 7 Sun gear 2
- 8 Socket bolt
- 9 Sun gear 1
- 10 Carrier assy 1
- 11 Ring gear

- 12 Carrier assy 2
- 13 Dowel pin
- 14 Collar
- 15 Plug
- 16 Plug
- 17 Cover
- 18 Pipe
- 19 Level gauge
- 20 Carrier assy 1
- 21 Planet gear 1
- 22 Pin 1

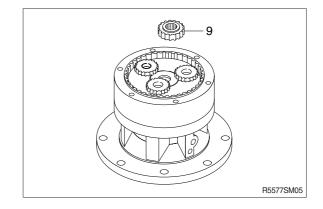
- 23 Bushing 1
- 24 Thrust washer 1
- 25 Thrust washer 3
- 26 Thrust washer 2
- 27 Carrier assy 2
- 28 Planet gear 2
- 29 Pin 2
- 30 Bushing 2
- 31 Spring pin
- 32 Snap ring
- 33 Thrust washer 4

2) DISASSEMBLY

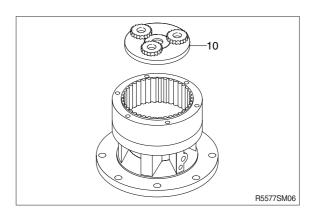
(1) Remove the plug (15) and drain out gear oil.



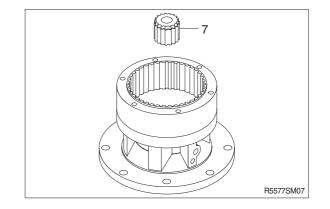
(2) Remove the No.1 sun gear (9).



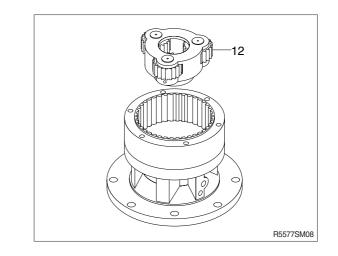
(3) Remove the No.1 carrier sub-assembly(10) using the jig.



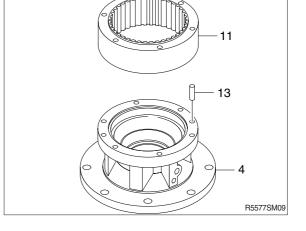
- (4) Remove the No.2 sun gear (7).
- * Pay attention to ensure the gear is not damaged during disassembling.



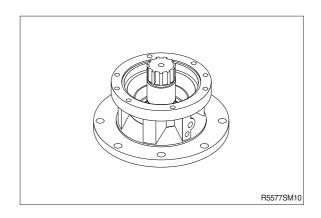
(5) Remove the No.2 carrier sub assembly (12).



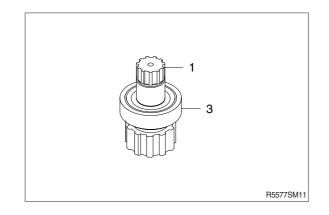
(6) Remove the ring gear by the removal groove between the ring gear (11) and casing (4) by using jig.Full out the knock pin (13).Do not need to remove the knock pin (13) if it is not worn or damaged.



(7) Put it on the working table with the drive shaft up.

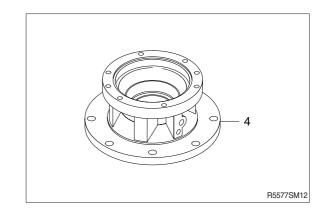


(8) Disassemble the drive shaft (1) with bearing (3) by using jig.

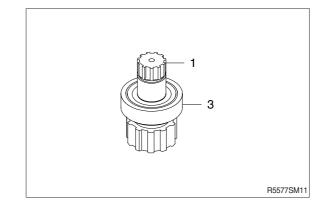


3) ASSEMBLING SWING REDUCTION GEAR

(1) Place the case (4) on the reversing machine having the flange side of the case up.



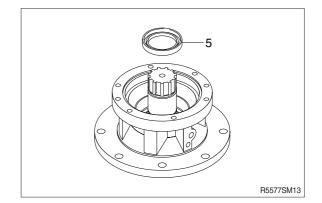
- (2) Install shaft assembly (1) into case (4).
- Be sure to clean the case before install, using washing machine with the temperature of 80°C
- * Do not install shaft assembly by force.

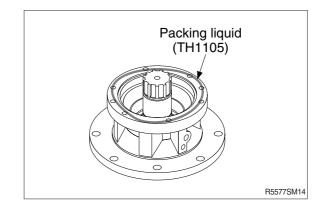


(3) Reverse case and press to insert oil seal(5) by using pressing jig after spreading grease oil around the outside ring of the seal and bearing.

Coat grease oil slightly on the lip surface to prevent any scratch when installing.

- * Be sure to check by eye that the oil seal is seated completely after being installed.
- (4) Clean the assembling surface of case and spread packing liquid (TH1105) as shown in figure.





- (5) Place ring gear (11) on the case by matching it with knock pin (13) hole.
- (6) Insert 2 knock pins (13) by using jig.
- * Be sure to check the hole location of oil gage before inserting.

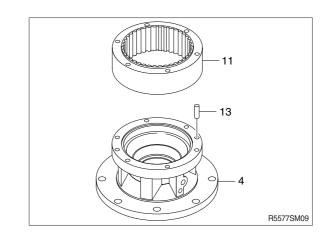
(7) Screw drain plug into drain plug (15) after winding sealing tape.

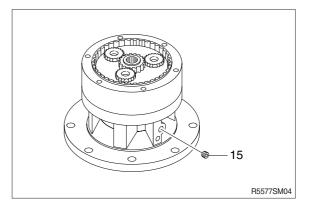
- (8) Mount No.2 carrier assembly (12) in the case sub assembly and install bolts into 2 TAP holes (M6) as shown in figure.
- * Turn the carrier slowly by hand to adjust the matching holes when assembling.

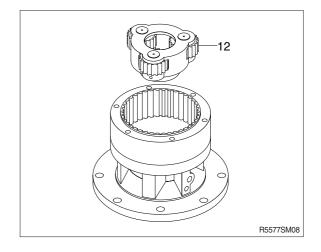
* Be sure to check the direction of sun gear

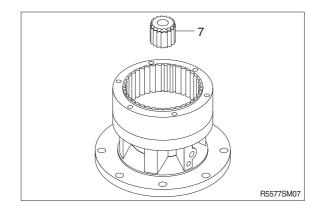
(9) Install No.2 sun gear (7).

(7) when assembling.

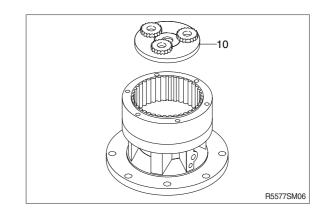




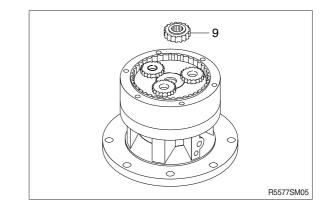




- (10) Mount No.1 carrier assembly (10) in the case sub assembly and install bolts into 2 TAP holes (M6) as shown in figure.
- * Turn the carrier slowly by hand to adjust the matching holes when assembling.



(11) Assemble No.1 sun gear (9).



GROUP 6 TRAVEL DEVICE (TYPE 1)

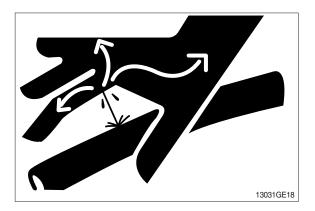
1. REMOVAL AND INSTALL

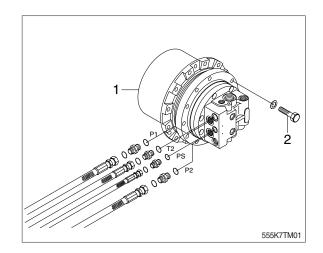
1) REMOVAL

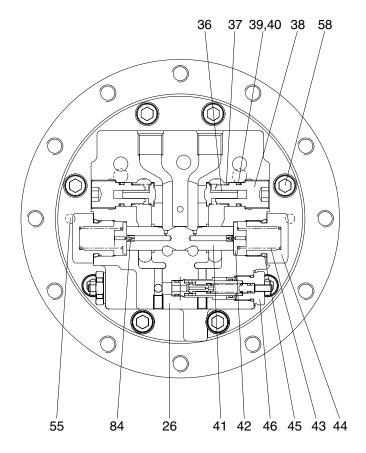
- (1) Swing the work equipment 90° and lower it completely to the ground.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrate the skin causing serious injury.
- When pipes and hoses are disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (4) Remove the track shoe assembly.For details, see removal of track shoe assembly.
- (5) Remove the cover.
- (6) Remove the hose.
- * Fit blind plugs to the disconnected hoses.
- (7) Remove the bolts and the sprocket.
- (8) Sling travel device assembly(1).
- (9) Remove the mounting bolts(2), then remove the travel device assembly.
 Weight : 80 kg (180 lb)

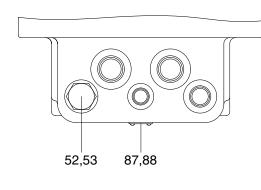
2) INSTALL

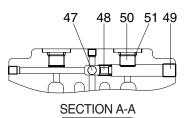
- (1) Carry out installation in the reverse order to removal.
- (2) Bleed the air from the travel motor.
- ① Remove the air vent plug.
- ② Pour in hydraulic oil until it overflows from the port.
- ③ Tighten plug lightly.
- ④ Start the engine, run at low idling, and check oil come out from plug.
- 5 Tighten plug fully.
- (3) Confirm the hydraulic oil level and check the hydraulic oil leak or not.

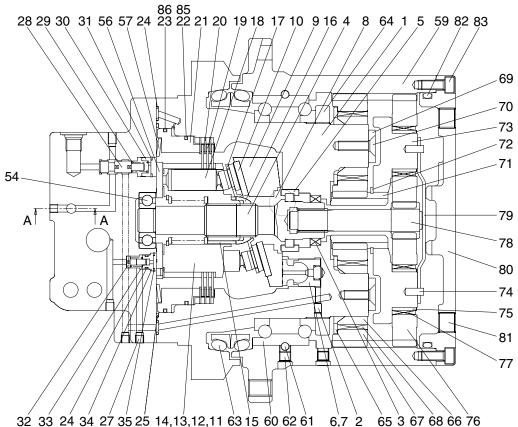












- Shaft casing 1 2 Expand Oil seal 3 Shaft 4
- 5 Bearing
- 6 Swash piston
- Spring 7
- 8 Swash steel ball
- 9 Swash plate
- 10 Shoe plate
- 11 Cylinder block
- 12 Spring seat
- 13 Spring
- 14 Snap ring 15 Pin
- 16 Ball guide 17 Set plate 18 Piston 19 Friction plate 20 Parking plate 21 Parking piston 22 O-ring O-ring 23 24 O-ring 25 O-ring 26 Valve casing 27 Plug Spool 28 29 Spring 30 Stopper

31	Snap ring
32	Check
33	Spring
34	Seat
35	Snap ring
36	Check
37	Spring
38	Plug
39	O-ring
40	Back up ring
41	Main spool
42	Spring seat
43	Spring
44	Plug
45	O-ring

46	Relief valve assembly
47	Steel ball
48	Check seat
49	Plug
50	Plug
51	O-ring
52	Plug
53	O-ring
54	Ball bearing
55	Pin
56	Valve plate
57	Spring
58	Wrench bolt
59	Ring gear
60	Angular bearing

61	Steel ball
62	Plug
63	Floating seal
64	Nut
65	Washer
66	Collar
67	Planetary gear (A)
68	Needle bearing
69	Plate
70	Flat head bolt
71	Sun gear
72	Snap ring
73	Carrier

- 74 Spring pin
- 75 Collar

R5572TM10

- 76 Planetary gear (B)
- 77 Needle bearing
- 78 Drive gear
- 79 Thrust plate
- 80 Ring gear cover
- 81 Plug
- 82 O-ring83 Wrench bolt
- 84 Orifice
- 85 Back up ring
- 86 Back up ring
- 87 Name plate
- 88 Rivet

2. DISASSEMBLY

1) GENERAL PRECAUTIONS

- (1) Before disassembling the travel motors, check the items to be inspected and, for remedy against trouble, closely examine the nature of the trouble, so that the motor can be disassembled effectively.
- (2) To disassemble the motor, use the disassembling procedures described as followings and select a clean place.
- (3) Place a rubber or vinyl sheet or other such protective materials on your working bench to protect the surface of the motor to be serviced.
- (4) During disassembly, give a match mark to the mating surfaces of each part.
- (5) Arrange removed parts in order so that they will not become damaged or missing during disassembly.
- (6) Once seals have been disassembled, they should be replaced even if damage is not observed. Have replacement seals ready on hand before starting your disassembling job.

2) TOOLS AND TIGHTENING TORQUE

(1) Tools

Name of tools	Size	Name of applied parts		
	2.5	Orifice (84)		
Hexagonal L-wrench	4	Plug (27)		
	6	Plug (49), wrench bolt (70, 83)		
	8	Plug (81)		
	-	Plug (38, 52, 50)		
Socket wrench / spanner	27	Plug (44), Relief valve assembly (46)		
Snap-ring plier (for holes, axis)		Snap ring (14, 31, 35, 72)		
Solder hammer		Bearing (5), Pin (55, 74), Oil seal (3)		
Torque wrench		Size : 500, 3000		
Jig for assembling oil seal		Oil seal (3)		
Induction heating apparatus for bearing		Bearing (5)		

(2) Tightening torque

No.	Name	Size	Torque
	Name		kgf ⋅ m
27	Plug	NPT 1/16	0.7~1.1
38	Plug	M24	5
46	Orifice	M27	17~19
49	Plug	PT 1/4	5
58	Wrench bolt	M12×35L	10
64	Nut	-	40
81	Plug	PT 3/8	8.5
70, 83	Wrench bolt	M8×20L	10
84	Orifice	M5	0.7

3. DISASSEMBLY

1) GENERAL PRECAUTIONS

- Select a clean place for disassembling.
 Spread a rubber plate on a working table in order to prohibit the damage of parts.
- (2) Clean a reduction gear and a motor part, washing out dirt and unnecessary substances.
- (3) Without any damage of O-ring, oil seal, the adhered surface of other seals, a gear, a pin, the adhered surface of other bearings, and the surface of moisturized copper, treat each parts.
- (4) Numbers written in the parenthesis (), next to the name of a part represent the item numbers of a previous page.
- (5) The side of a pipe in a motor can be written as a rear side ; the side of out-put as a front side.
- (6) In case of bonding bolts, combine a standard torque by torque wrench after spraying loctite #262 on the tap parts.

2) DISASSEMBLING

(1) Motor unit

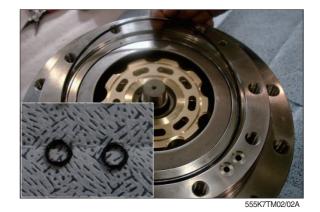
① Put the motor assembly on the assemble table.

Using L-Wrench, disassemble 8 wrench bolt (58) and so respectively disassemble shaft casing assembly and rear cover assembly.



7078TM01/01A

② Disassemble O-ring (24) and O-ring (25) in that order from shaft casing (1).



③ Dissemble plate spring (57) from shaft casing (1).

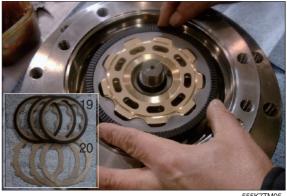


555K7TM03

- ④ Using compression air, disassemble parking piston (21) from shaft casing (1) and dissemble O-ring (23), O-ring (22) and back up ring (85) in that order.

7078TM04/04A

5 Disassemble respectively 3 set of friction plate (19), parking plate (20) from shaft casing (1).



555K7TM05

6 Disassemble cylinder block assembly (11) from shaft casing (1).



555K7TM06

(2) Cylinder block

 Disassemble set plate (17), piston assembly (18) from cylinder block assembly (11).

② Disassemble cylinder block (11), ball guide (16) and pin (15) in that order.

③ Put the cylinder block (11) on the air assembling jig and dissemble snap ring (14) by using a plier.
Dissemble spring seat (12), spring (13) and spring seat (12) in that order.

④ Disassemble shoe plate (10) from shaft casing (1).





555K7TM08/08A



555K7TM09/09A



555K7TM10

(5) Disassemble steel ball (8) and swash plate (6) from shaft casing (1).



555K7TM11/11A/11B

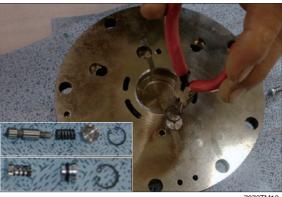
(3) Rear cover

① Disassemble valve plate (56) from rear cover (26).



555K7TM12/12A

② Using plier jig, disassemble snap ring (35), seat (34), O-ring (24), spring (33), check (32) from rear cover (26) and then disassemble snap ring (31), stopper (30), spring (29) and spool (28) same procedure.



7078TM13

③ Using torque wrench, disassemble relief valve assembly (46) from rear cover (26) (left, right is symmetry).



 ④ Using torque wrench, disassemble plug (44) and O-ring (45), spring (43), spring seat (42) and main spool (41) in that order.



7078TM15/15A

5 Disassembly make up valve

Using L-wrench, disassemble plug (38) and dissemble O-ring (36), back up ring (40) and spring (37) and then check (36) and spring (37) in that order.



555K7TM15/15A

(4) Reduction gear

 Using L-wrench, disassemble wrench bolt (83) and then ring gear cover (80), O-ring (82) from ring gear (59).



7078TM17/17A

② Disassemble thrust plate (79) from ring gear (59).



7078TM18/18A

③ Disassemble planetary gear (76), drive gear (78) in that order from ring gear (59).



7078TM19/19A

④ Disassemble 3 needle bearing (77) from ring gear (59).



7078TM20/20A

7-81

(5) Disassemble in order collar (75), carrier(73) from ring gear (59).



7078TM21/21A

 ⑥ Disassemble sun gear (71) from ring gear (59) and then disassemble snap ring (72) with a plier jig.

 Using a L-wrench, disassemble plate head bolt (70)-4EA from ring gear (59) and then disassemble plate (69).



7078TM22/22A



⑧ Disassemble planetary gear (67)-4EA from ring gear (59).



7078TM24/24A

(9) Disassemble needle bearing (68)-4EA from ring gear (59).

10 Disassemble collar (66)-4EA from ring

gear (59).



7078TM25/25A



7078TM26/26A

 Disassemble washer (65)-4EA from ring gear (59).

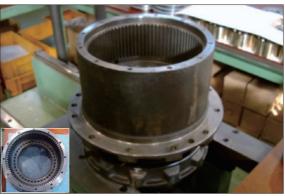


② Using jig, disassemble nut (64) when inner pressed state with a L-wrench bolt from ring gear (59).



78078TM29

③ Put the reduction gear on the assembling jig and then disassemble ring gear (59).



555K7TM17

4. ASSEMBLY

1) GENERAL SUGGESTIONS

- (1) After washing each parts cleanly, dry it with compressed air. Provided that you do not wash friction plate with treated oil.
- (2) In bonding each part, fasten bond torque.
- (3) When using a hammer, do not forget to use a plastic hammer.

2) ASSEMBLING

(1) Sub of turning axis and valve casing

① Using a jig, insert the steel ball (61) to the shaft casing (1) and then assemble plug (62).

O Using a jig, assemble oil seal (3) to the shaft casing (1) and then insert with solid hammer.



7078TM51



7078TM52

③ Assemble bearing (5) to the shaft casing (1) and then assemble steel ball (8) with grease and swash piston (6).



555K7TM19/19A/19B/19C

④ Assemble swash plate (9) to the shaft casing (1).



555K7TM20

(5) Assemble shoe plate (10) to the shaft casing (1).



555K7TM21

⑥ Assemble shaft (4) to the shaft casing (1).



555K7TM22/22A

(2) Cylinder block sub assembly

 Put cylinder block (11) on the air jig, assemble spring seat (12), spring (13) in that order and then assemble the snap ring (14) with a plier.



555K7TM09A

② Assemble pin (15), ball guide (16) in that order to the cylinder block (11).

③ Assemble piston (18) to the set plate (17,

9 set).



555K7TM08/08A



555K7TM23

④ Assemble sub-assembled piston (17, 18)

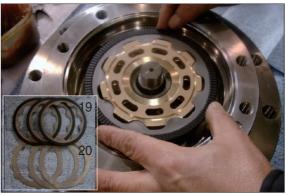
to the cylinder block (9).

⑤ Assemble sub-assembled cylinder block (11) to the shaft casing (1).



555K7TM06

 6 Assemble friction plate (19), parking plate (20) (respectively 3 EA) to the shaft casing (1).



555K7TM05

- ⑦ Assemble back up ring (86), O-ring (23, 22), back up ring (85) in that order to the parking piston (21).

7078TM04/04A

(8) Using a jig, insert the parking piston to the shaft casing (1) and assemble.



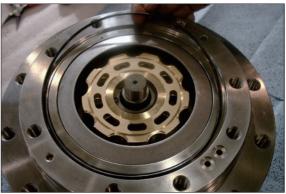
555K7TM24

(9) Assemble spring (57) to the shaft casing (1).



555KTM03

① Assemble O-ring (25) to the shaft casing (1).



555K7TM02

 Assemble pin (55), O-ring (24) in that order to the shaft casing (1).



555K7TM25

(3) Rear cover assembly

① Using a L-wrench, assemble plug (27)-9EA to the rear cover (26).



7078TM66

② Contact steel ball (47) to the rear cover (26) by using jig and assemble plug (49) with a L-wrench.



3 Assemble the make up check valve

Assemble check (36), spring (37) to rear cover (26) and assemble plug (38) with back up ring (40) and O-ring (39) to rear cover (26) by using a L-wrench.



7078TM16/16A

④ Fit orifice (84) to main spool (41) symmetry and assemble it to rear cover (26) and then assemble spring seat (42), spring (43), O-ring (45) and plug (44) in that order by using a torque wrench.



7078TM15/15A

(5) Assemble relief valve assembly (46) (with left-right symmetry) to the rear cover (26) and then tighten with a torquewrench.



6 Using plier, Assemble spool (28), spring (29), stopper (30) and snap ring (31) in that order to the Ø16 hole on the underneath of the rear cover (26) and assemble check (32), spring (33), O-ring (24), seat (34) and snap ring (35) in that order to the Ø15 hole of the rear cover (26).



7 Fit O-ring (51) to plug (49) and O-ring (53) to plug (52) and then assemble them to rear cover (26) by a torque wrench.



555K7TM26/26A

⑧ Assemble 2 plug (50) to rear cover (26) by a torque wrench.



555K7TM27

③ Assemble ball bearing (54) with grease to rear cover (26) and insert 2 pin (55) by using hammer.



555K7TM28

① Assemble valve plate (56) with grease to rear cover (26).



555K7TM12/12A

Assemble rear cover (26) to shaft casing (1).



555K7TM29

② Combine rear cover assembly and shaft casing assembly with 8 bolt (58).



555K7TM30

(13) Motor pressure test

 Check the oil leak for one minute by appearance test at air pressure 5 kgf/cm² (43 psi).



555K7TM31

14 Leakage test

 Clean the unit by #1 color checker and spray #3 checker.
 Check leakage from oil seal and body.



555K7TM32

(4) Travel reduction gear

 Before assemble nut (64) to the motor. Remove burr and alien substances ready for assembling.



② Insert ring gear (59) to the spray washing machine and heat up 69~70 °C for one minute.

③ Assemble angular bearing (60) to the

ring gear (59).



7078TM78

7078TM79/79A

④ Insert 10 steel ball (61) to the ring gear
(59) with a jig and assemble 2 plug (62)
with a L-wrench.



7078TM80/80A

(5) Assemble floating seal (63) to ring gear(59) and motor part with a jig.



7078TM81/81A/82

⁽⁶⁾ Upset the ring gear (59) and assemble with motor.



7078TM83

- ⑦ Combine nut (64) to the ring gear (59) and pressing use a jig and then assemble with a torque-wrench.
 - Tightening torque : 40 kgf \cdot m (290 lbf \cdot ft)



7078TM28/28B/28C

⑧ Using a L-wrench, assemble plug-4EA to the ring gear (59) and then cocking by a jig.



7078TM84/84A/85

(9) Assemble washer (65)-4EA to the ring gear (59).

10 Assemble collar (66)-4EA to the ring

gear (59).

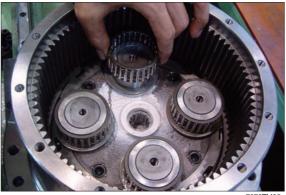


7078TM27



7078TM26

 Assemble needle bearing (68)-4EA to the ring gear (59).



7078TM25

② Assemble planetary gear (67)-4EA to the ring gear (59).



7078TM24

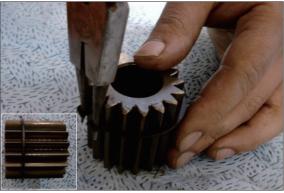
13 Assemble plate (69)-1EA to the ring gear (59) and then tighten flat head bolt (70)-4EA with a L-wrench. (after paste loctite and then tighten the flat head bolt).

(4) Assemble snap ring (72) to the sun gear

(71) with a plier jig.



7078TM23





(15) Assemble sun gear with snap ring assembly to the ring gear (59).



7078TM22

(6) Assemble in that order collar (75), spring pin (74) to the carrier (73).



7078TM21

⑦ Assemble carrier sub assembly to the ring gear (59).



7078TM87

(B) Assemble needle bearing (77)-3EA to the ring gear (59).

⁽¹⁾ Assemble in order planetary gear (76), drive gear (78) to the ring gear (59).



7078TM20



7078TM19

② Assemble thrust plate (79) to the ring gear (59).



7078TM18

② Assemble in order ring gear cover (80) with O-ring (82) and then assemble wrench bolt (83) with a torque-wrench.



7078TM17/17A

② Roll the teflon tape to the ring gear (59) and then combine with a L-wrench (after test of drain part water pressure and capacity and then assemble plug PT3/8).



7078TM88

(5) Test

1 Motor pressure test

- Check the oil leak for one minute by appearance test at air pressure 5 kgf/cm² (71 psi).



7078TM89

2 Performance test

- Pour the gear oil (85W-140) by beaker at the reduction gear.



7078TM90

③ Test bench mounting

- Partially performance test by mounting the motor test bench.



TRAVEL DEVICE (TYPE 2, MACHINE SERIAL NO.: #3959-)

1. REMOVAL AND INSTALL

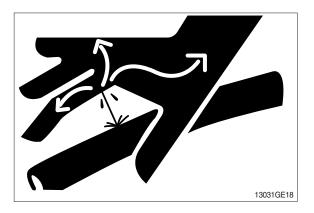
1) REMOVAL

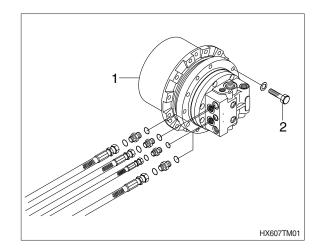
- (1) Swing the work equipment 90° and lower it completely to the ground.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrate the skin causing serious injury.
- When pipes and hoses are disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (4) Remove the track shoe assembly.For details, see removal of track shoe assembly.
- (5) Remove the cover.
- (6) Remove the hose.
- % Fit blind plugs to the disconnected hoses.
- (7) Remove the bolts and the sprocket.
- (8) Sling travel device assembly(1).
- (9) Remove the mounting bolts(2), then remove the travel device assembly.
 - · Weight : 80 kg (180 lb)
 - · Tightening torque : 20 ± 2.0 kgf·m

 $(145\pm14.5 \, \text{lbf} \cdot \text{ft})$

2) INSTALL

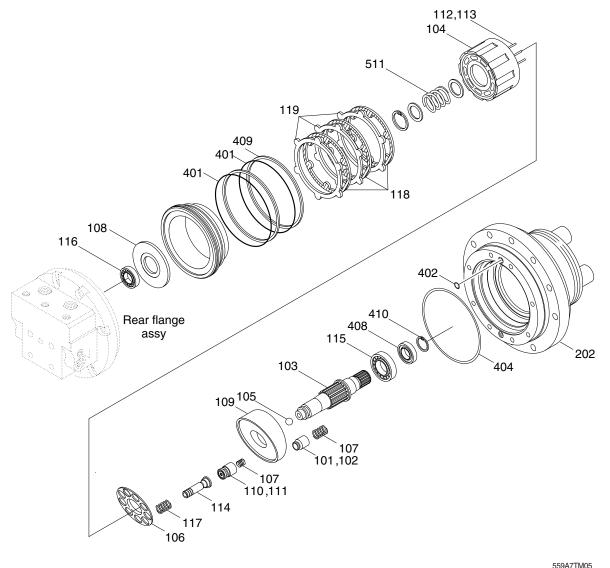
- (1) Carry out installation in the reverse order to removal.
- (2) Bleed the air from the travel motor.
- ① Remove the air vent plug.
- ② Pour in hydraulic oil until it overflows from the port.
- ③ Tighten plug lightly.
- ④ Start the engine, run at low idling, and check oil come out from plug.
- 5 Tighten plug fully.
- (3) Confirm the hydraulic oil level and check the hydraulic oil leak or not.





2. DISASSEMBLY AND ASSEMBLY OF MOTOR UNIT

1) PARTS LIST (1/2)

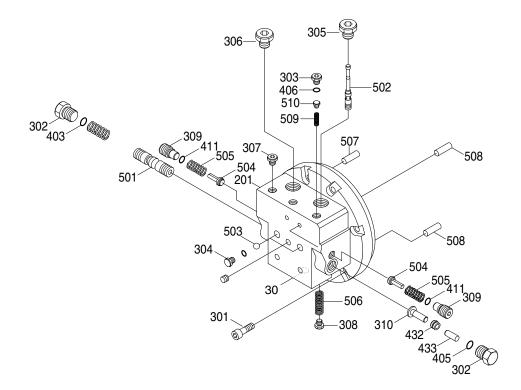


101 Piston

- 102 Shoe
- 103 Drive shaft
- 104 Cylinder block
- 105 Spherical bushing
- 106 Set plate
- 107 Cylinder spring
- 108 Valve plate
- 109 Swash plate

- 110 Swash piston
- 111 Swash shoe
- 112 Pivot
- 113 Pivot pin
- 114 Brake piston
- 115 Roller bearing
- 116 Ball bearing
- 117 Brake spring
- 118 Friction plate

- 119 Separator plate
- 202 Reducer casing
- 401 O-ring
- 402 O-ring
- 404 O-ring
- 408 Oil seal
- 409 Back up ring
- 410 Snap ring
- 511 Swash piston spring



- Relief valve assy 30 201 Valve casing 301 Socket bolt 302 Plug 303 Drain plug 304 NPTF plug 305 Dust plug 306 Dust plug 307 Dust plug
- 308 2 speed plug
- Set plug 309 310 Restrictor 403 O-ring
- 405 O-ring
- 406 O-ring
- 411 O-ring
- 432 Seat
- Seat casing 433
- 501 Main spool
- 502 2 speed spool

- 503 Steel ball
- 504 Plunger
- 505 Main spool spring
- 506 2 speed spool spring
- 507 Spring pin
- 508 Pin
- 509 Spring cap
- 510 Cap

2) TOOLS AND TIGHTENING TORQUE

(1) Tightening torque

This table shows the typical screw sizes and tightening torques used in the motor

Item	Part name	Size	Tightening torque	
			kgf ⋅ m	lbf ⋅ ft
30	Relief valve assy	G 1/2	11.2	81.0
301	Socket bolt	M14	16.3	118
302	ROH plug	G 1/4	3.6	26.0
303	Drain plug	G 3/8	7.5	54.2
304	NPTF plug	NPTF 1/16	1.1	8.0
308	2 speed plug	G 1/4	3.6	26.0
309	Set plug	G 3/4	17.3	125
310	Restrictor	NPTF 1/16	1.1	8.0
626	Pipe plug	RC 1/8	1.2	8.7
632	ROH plug	G 1/8	1.5	10.8

(2) Tools

1 Hexagon and socket wrench

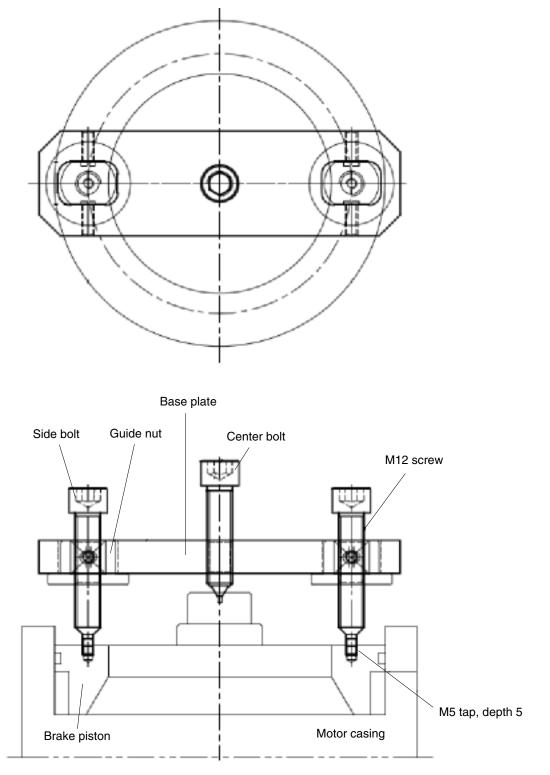
Tools	Item	Part name	B size	Screw size
	304, 310	NPTF plug, Restrictor	4	R 1/16
Hexagon	626, 632	Pipe plug, ROH plug	5	R 1/8
wrench	302, 308	ROH plug, 2 speed plug	6	G 1/4
	301	Socket bolt	12	M14
	303	Drain plug	22	G 3/8
Socket	30	Relief valve assy	27	G 1/2
wrench	309	Set plug	30	G 3/4
	30	Relief valve assy	8	M5

0 Others

Tools	Specification	
Driver	Screw driver (small, medium)	
Hammer	Rubber or plastic hammer, iron hammer	
	Round bar : about Ø45 mm x 150 mm	
Bearing press jig	Round bar : about Ø60 mm x 150 mm	
Torque wrench	Torque adjustment range	
	- For 4~20 Nm	
	- For 20~100 Nm	
	- For 40~200 Nm	
Slide hammer bearing puller	-	
Brake piston disassembly jig	-	
Brake piston press jig	-	
Snap ring plier	Inner diameter	

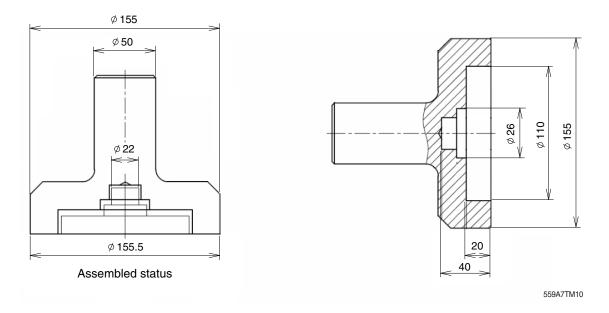
(3) Special tools

① Brake piston disassembly jig



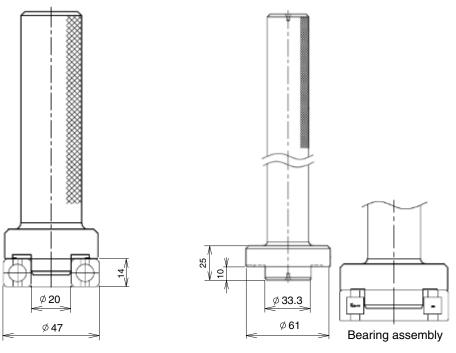
② Brake piston press jig

The below dimensions are the reference dimensions.



③ Bearing press jig

The below dimensions are the reference dimensions.



Bearing pressing jig for valve casing

Roller bearing pressing jig for casing

3) DISASSEMBLY

When disassembling the motor, disassemble in the order shown below. The number in brackets after part name means item number of section drawing.

- (1) Wrap a wire rope around the outer periphery of the motor, lift it with a crane, and wash it with white kerosene. After washing, dry with compressed air.
- * The motor can be disassembled into an mounted state on the excavator. In this case, disassemble not to be got foreign materials: dust, mud, etc.
- (2) Remove the oil in the casing (202) from the drain plug.
- In the case of automatic 1-speed specification, 2 speed spool (502) may drop out during operation. Block pilot port with dust plug (306).
- 559ATM12
- (3) Disassembly is easily fixed to the workstation.

Place the shaft end of the drive shaft (103) facing down.

Mark the joint mark at the junction point of casing (202) and valve casing (201).

* Choose a clean place.

Spread a rubber plate or cloth on the workbench to prevent friction and damage of the parts.

Disassembly of valve casing kit

(4) Loosen the relief valve assy (30) and remove it from the valve casing (201).



(5) Disassemble the spring cap (510) \rightarrow cap (509).



559A7TM14

(6) Loosen the set plug (309), remove the plunger (504) and the main spool spring (505).

Then take out the main spool (501).

Main spool is disassembled in the horizontal direction with the hole. Be careful not to scratch the sliding surface of the main spool.

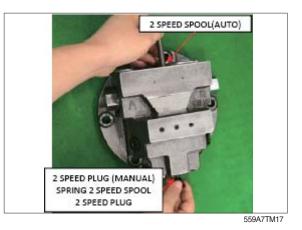


559A7TM15

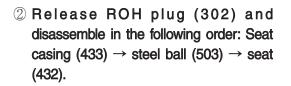


559A7TM16

(7) Loosen the 2 speed plug (308), take out the 2 speed plug spring (506) and the 2 speed spool (502).



- (8) The following operations should be carried out if necessary.
- ① Loosen the ROH plug (302) and remove the restrictor (310).
- * If there is no problem with the 1st / 2nd speed switching, no special disassembly is required.



- * If there is no problem with the 1st / 2nd speed switching, no special disassembly is required. Please be careful about the loss of the steel ball. Please be careful not to damage the inner diameter of the seat casing and seat.
- (9) Loosen socket bolt (301) and remove valve casing (201) from casing (202).
- * (Due to the force of the brake spring E (117), when the socket bolt (301) is unscrewed, the valve casing (201) is raised from the casing (202). Further, remove the valve plate (108) from the valve casing (201).

Carefully work so that the valve plate does not fall off the valve casing.

* In some cases, the valve plate is attached to the cylinder block. Be careful not to scratch the sliding surface and mating surface when you disassemble the mating surface with a

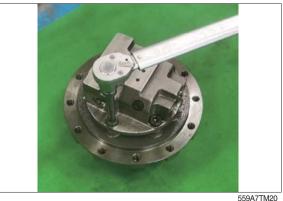
screwdriver or the like.



559A7TM18



559A7TM19

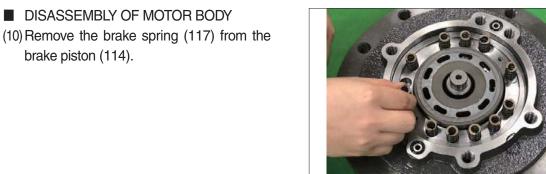




59A7TM21



559A7TM22



559A7TM25

■ DISASSEMBLY OF MOTOR BODY

brake piston (114).

- (11) Using the jig, remove the brake piston (114) from the casing (202). No.16
- % If you need to disassemble without jig, Fill the brake flow path hole with compressed air.

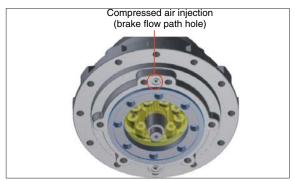
If you blow compressed air suddenly brake piston can jump out of casing. There is a risk of damage or injury to the part;

Please follow the directions below.

- ① Cover the casing with a clean cloth.
- 2 Press the cloth lightly with your hand to prevent the brake piston from jumping out.
- ③ Fill the brake flow path hole with compressed air.
- * Both ends of the jig are hooked to the groove of the brake piston. The center of the jig is hooked to the center of the drive shaft and makes the jig and brake piston parallel.



559A7TM26



(12) Put the motor horizontally.

Disassemble cylinder block (104) from drive shaft (103).

Also, disassemble piston assy (10), set plate (106), spherical bush (105), cylinder spring (107).



559A7TM31

Mark each cylinder block bore, piston assy, and set plate bore in the assembled position so that the assembled position does not change.

Be careful not to scratch the sliding surface of cylinder block, piston, shoe, etc.



559A7TM32



559A7TM33



(13) Disassemble friction plate (118) and separator plate (119) in casing (202).



559A7TM35

(14) Disassemble the drive shaft (103) and swash plate (109).



559A7TM37

(15) Disassemble swash piston assy (20), swash piston spring (511), pivot (112), pivot pin (113).



- (16) Do not disassemble any further unless there is a specific problem. At this state, check bearing according to the following inspection instructions.
 - Check the raceway surface, rollers or balls in the visible range, and make sure there are no pittings or cracks.
 - ② Check for local corrosion and wear on the ball or roller.
 - ③ Make sure that there is excessive wear powder between the ball or roller and cage.
 - ④ When turning lightly by hand, check that it rotates smoothly.

If there is no problem after checking in this step, the following disassembly is not necessary.



559A7TM41

(17) The following operations should be carried out if necessary.

From the casing (202), the outer ring of the cylindrical roller bearing (115) is tapped lightly from the housing part side of the oil seal (408) via the steel bar and is pulled out.

* Do not reuse the removed roller bearing.

(18) Disassemble the snap ring (410) using a snap ring plier (inner diameter) in casing (202).

- (19) From the casing (202), the gently tap out the housing side of the oil sea (408) is tapped lightly from the rear of the casing (202) via the steel bar and is pulled out.
- * Do not reuse the removed oil seal.
- (20) Remove the cylindrical ball bearing (116) from the valve casing (201) using the slide hammer bearing puller.
- * Do not reuse the removed ball bearing.
- * The disassembly operation is finished. Please check that there is no problem in each part.

4) ASSEMBLY

- (1) The assembly way is the reverse of the disassembly way, but be careful of the following items.
- ① Be sure to repair damaged parts during disassembly. Please prepare replacement parts in advance.
- 2 Wash each part thoroughly with wash liquid and dry with compressed air.
- ③ Be sure to coating clean hydraulic oil to sliding parts, bearings, etc. and assemble them.
- ④ In principle, should replace seal parts such as O ring and oil seal.
- ⁵ Use the torque wrench to tighten the mounting bolts and plugs of each part, and tighten with the torque shown in page 7-99-4.

ASSEMBLY OF VALVE CASING KIT

- (2) This operation is necessary only when the seat assy is removed. Assemble seat (432) \rightarrow steel ball (503) \rightarrow seat casing (433) \rightarrow ROH plug (302) in this order.
- * Please pay attention to the assembly sequence. Refer to section drawing.

(3) This operation is necessary only when the

Apply loctite on the restrictor (310) and assemble to casing (21). And tighten ROH plug (302) with specified torque.

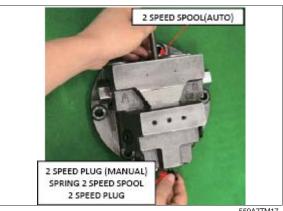
restrictor is removed.



559A7TM19

559A7TM18

(4) Assemble the 2 speed spool (502), the 2 speed spool spring (506), the 2 speed plug (308).



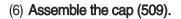
- (5) Assemble main spool (501), Plunger (504) \rightarrow main spool spring (505) \rightarrow O-ring (411) \rightarrow Assemble set plug (309) in order.
- Make sure the main spool moves smoothly.

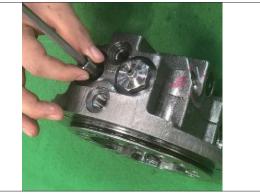


559A7TM16



559A7TM15





- (7) Assemble the spring cap (510) to the relief valve assy (30). Attach the relief valve to the valve casing (201).
- It is advisable to apply grease thinly on the mating surface of spring cap to prevent falling off.



- ASSEMBLY OF MOTOR BODY
- (8) Place the casing (202) on the work surface with the valve casing (201) assembly surface facing up.
- (9) Insert the oil seal (408) into the casing (202) using a jig.
- Pay attention to the direction of the oil seal. (refer to cross-section drawing) Apply grease thinly to the lip portion of the oil seal.

Hit it uniformly and be careful not to scratch the outer circumference.

- (10) Assemble the snap ring (410) using the snap pliers (internal diameter) on the casing (202).
- * The snap ring "R" faces the oil seal.

(11) The outer ring of the cylindrical roller bearing (115) is tapped lightly on the casing (202) via the bearing press jig and incorporated.



(12) Assemble pivot pin (113), pivot (112) to casing (202).



- (13) Assemble swash piston spring (511) and swash piston assy (20) to casing (202).
- It is advisable to apply grease thinly on the mating surface of swash piston spring to prevent falling off.

When assembled normally, the pushed swash piston assy goes deeper than the casing stage.

Make sure the swash piston assy moves smoothly.

- (14) Place casing (202) horizontally and insert swash plate (109).
- Make sure the swash plate moves smoothly.



559A7TM38



559A7TM37

- (15) The drive shaft (103) is attached to the casing (202).
- * Carefully insert so that the lip of the oil seal will not be scratched.

Assemble by applying oil to the oil seal assembly of drive shaft.

When assembled normally, the pushed swash piston assy goes deeper than the casing stage.

Make sure the swash piston assy moves smoothly.



- (16) Set the cylinder spring (107) and the spherical bush (105) into the cylinder block (107). and insert the piston assy.(10) to the bore of set plate (106).
- Assemble the Larger outer diameter face of set plate and the sliding movement face of shoe in the same direction. (Refer to section drawing)



559A7TM34



559A7TM33

(17) The piston assy (101) set on the set plate(106) is assembled in the cylinder block(104).

And the cylinder block sub assembled is inserted in accordance with the spline of the drive shaft (103) to casing (202).

- Before assembly, apply oil to the surface of cylinder bore or piston.
- It is easy to insert into drive shaft by matching spline of cylinder block and the spherical bush.
- After assembly, try rotating the cylinder block lightly in the forward and reverse directions by hand.



(18) Place casing (202) with the valve casing (201) assembly surface of casing (202) facing up. Separator plate (119) and friction plate

(118) are alternately assembled to casing (202).

- ※ Put the separator plate in arc groove of casing.
- * Please refer to the assembly drawing for the number of assembly of the separator plate and friction plate.



559A7TM30



559A7TM29

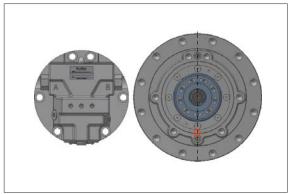
- (19) Install the O-ring (118, 401) and the back up ring (409) on the brake piston (114).
- * Back up ring is installed to the valve casing direction.
- * If the grease is lightly applied to the O-ring, it will not be cut when the brake piston is inserted.



(20) The brake piston (114) is tapped lightly via the brake piston press jig and pressed into casing (202).



* Pay attention to the assembly direction of the brake piston. The orifice of the brake piston is located downward on the same vertical line as the flow hole in casing.



559A7TM42

- (21) Attach the brake spring (117) to the brake piston (114).
- (22) Attach the O-ring (402) to the casing (202).



559A7TM25

(23) This term is necessary only when the cylindrical ball bearing (116) is removed. The outer ring of the cylindrical ball bearing (116) is tapped lightly on the valve casing (201) via the bearing press JIG and incorporated.



- (24) The valve plate (108) is installed in the valve casing (202) and the O-ring (401) is mounted.
- Apply grease thinly to the joint surface of the valve plate. (prevention of dropout)



559A7TM23



559A7TM22

- (25) Attach the valve casing (201) to the casing (202) and fasten it with a socket bolt (301).
- Be careful not to remove the valve plate.
 Be careful not to tilt the brake spring.
 Tighten the socket bolt evenly until specified torque.

559A7TM21

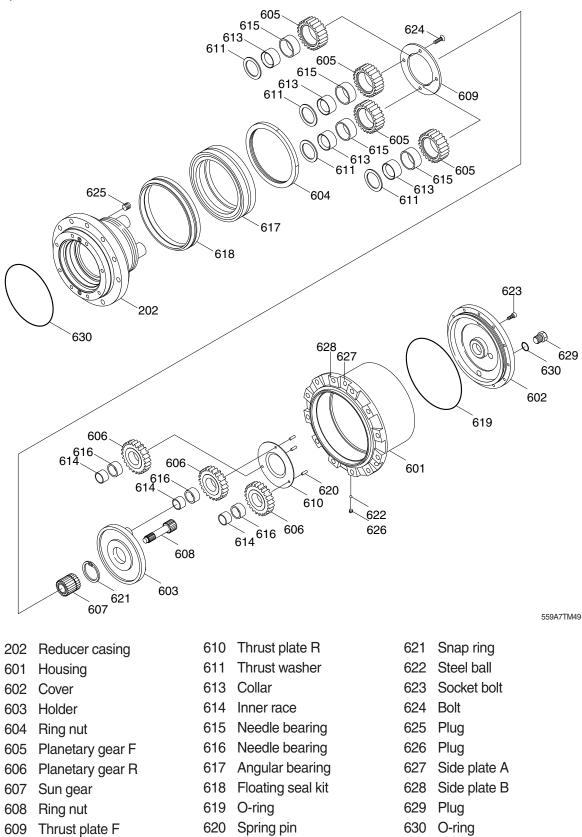


559A7TM20

* Assembly is completed with the above.

3. DISASSEMBLY AND ASSEMBLY OF REDUCTION GEAR

1) PARTS LIST



2) GENERAL PRECAUTIONS

This reduction gear is designed to reduce the number of parts and balance the life of the parts. Therefore, all parts can be supplied separately, but when replacing, it is often necessary to replace them both structurally and functionally.

						Part	s to l	oe re	place	d at t	the sa	ame	time			
		Part number	617	618	611	613	615	605	612	609	624	603	620	614	616	606
	Name of part		Angular bearing	Floating seal	Thrust washer	Collar	Needle bearing	Planetary gear F	Thrust washer	Thrust plate F	Ext. flush bolt	Holder	Spring pin	Inner race	Needle bearing	Planetary gear R
	617	Angular bearing		\bigcirc												
	618	Floating seal	\triangle	—												
	611	Thrust washer			—	\triangle	\triangle	\triangle	\bigtriangleup	\bigcirc	\bigcirc					
	613	Collar			\triangle		0	0	\triangle	0	\bigcirc					
	615	Needle bearing			\bigtriangleup	\bigcirc	—	0	\bigtriangleup	\bigcirc	\bigcirc					
	605	Planetary gear F			\triangle	\triangle	\triangle		\triangle	\bigcirc	\bigcirc					
Replace-	612	Thrust washer			\triangle	\triangle	\triangle		—	\bigcirc	\bigcirc					
ment parts	609	Thrust plate F			\triangle	\triangle	\triangle		\triangle		\bigcirc					
parto	624	Ext. flush bolt			\triangle	\triangle	\triangle		\triangle	\bigcirc						
	603	Holder														
	620	Spring pin											No disassembly			
	614	Inner race											Please replace the entire			
	616	Needle bearing											No.1 holder assy.			-
	606	Planetary gear R														

 \bigcirc Indicates parts that must be replaced at the same time.

▲ Indicates parts that is desirable to be replaced at the same time.

* Be sure to replace the bearing inner and outer rings at the same time.

2) TOOLS AND TIGHTENING TORQUE

(1) Tightening torque

This table shows the typical screw sizes and tightening torques used in the reduction gear.

ltem	Part name	Size	Tightening torque			
	Faithanie	Size	kgf ⋅ m	lbf ⋅ ft		
604	Ring nut	M165	18	130		
623	Socket bolt	M6	1.2	8.7		
624	Ext flush bolt	M8	3	21.7		
625	Pipe plug	RC 3/8	10	72.3		
626	Pipe plug	RC 1/8	1.2	8.7		
629	RO plug	G 1/2	8.4	60.8		
632	ROH plug	G 1/8	1.5	10.8		

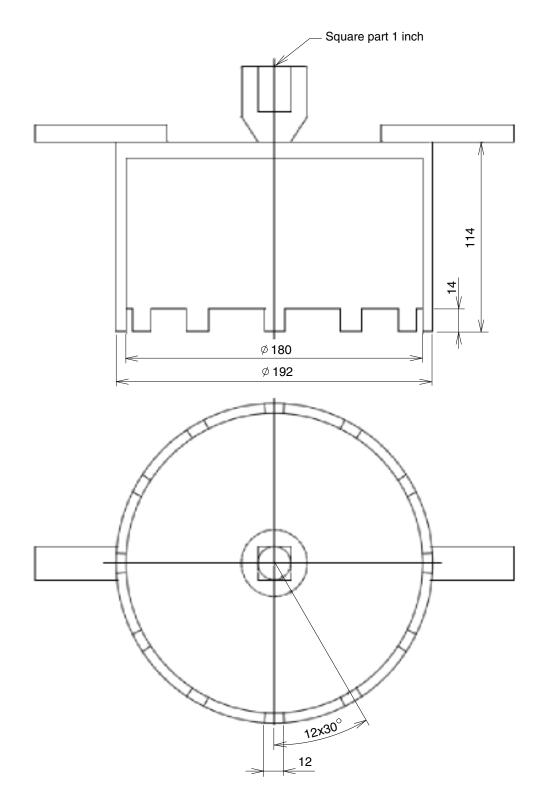
(2) Tools

1 Hexagon wrench and exclusive jig

Tools	Item	Part name	B size	Screw size
	626	Pipe plug	5	R 1/8
	625	Pipe plug	8	R 3/8
Hexagon wrench	629	RO plug	10	G 1/2
	623	Socket bolt	5	M6
	624	Ext flush bolt	6	M8
Exclusive jig	604	Nut ring	-	M165

② Others

Tools	Specification			
Driver	Screw driver (small, medium)			
Hammer	Rubber or plastic hammer, iron hammer			
Torque wrench	Torque adjustment range			
	- For 4~20 Nm			
	- For 20~100 Nm			
	- For 40~200 Nm			
Snap ring plier	Outer diameter			
Nut ring disassembly and assembly jig	-			



4) ASSEMBLY

- (1) Disassembly and assembly tips
- ① When disassembling, be careful not to damage the parts.
- 2 Wash each part with washing oil and dry it with compressed air.
- ③ The numbers in parentheses after the part name represent the symbols of the cross-sectional drawing.
- (2) Wrap a wire rope around the outside of the traveling device to lift it with a crane. Then wash with white kerosene. After washing, dry with compressed air.



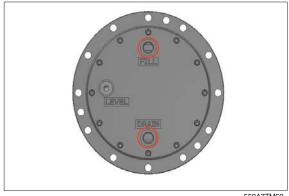
559A7TM51

(3) Make sure that the fill plug (629) and drain plug (629) shown in the dimensional installation drawing are perpendicular to the horizontal plane.

Unplug both ports and remove the gear oil.

Place it on a suitable base.

- * Receive the gear oil in a clean container and inspect the presence and presence of wear powder.
- (4) Loosen the socket bolt (623) and disassemble the cover (602).







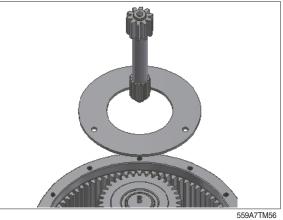
* Be careful not to damage the O-ring (619) of the cover during disassembly.



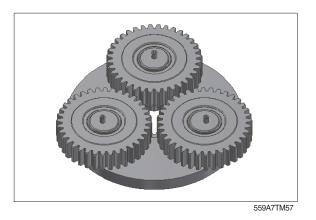
559A7TM54

(5) Disassemble thrust plate R (610), drive gear (608).





- (6) Disassemble the No.1 holder assembly with the planetary gear R (606) attached.
- * No. 1 holder assy components are as follows.
 - Holder (603)
 - Spring pin (620)
 - Planetary gear R (606)
 - Needle bearing (616)
 - Inner race (614)



(7) Disassembly of No.1 holder assy

Do not disassemble the No.1 holder assy further.

In this state, check the parts according to the inspection instructions shown in section 6.

As mentioned above, it is recommended to exchange No.1 holder assy as a set as much as possible.

Please follow the instructions below when you are forced to exchange parts.

- ① Disassemble in the order of planetary gear R (606) \rightarrow Needle bearing (616) \rightarrow Inner race (614).
- ② Unplug the spring pin.
- Mark each planetary gear, needle bearing, and inner race in the assembled position so that each combination and assembly position does not change.
- * When disassembling the spring pin, do not reuse it.
- (8) Disassemble the sun gear (607). Then, the snap ring (621) is separated from the sun gear (607) using a snap ring pliers.



559A7TM58



559A7TM59





559A7TM61

(9) Disassemble the No.2 holder assy.

(10) Disassembly of No.2 holder assy

Do not disassemble any more No.2 holder assy unless otherwise specified.

In this state, check the parts according to the inspection instructions shown in section 6.

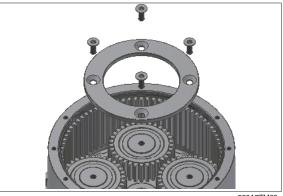
As mentioned above, it is recommended to exchange No.2 holder assy as a set as much as possible.

Please follow the instructions below when you are forced to exchange parts.

- ① Apply enough heat to ext flush bolt(624)
- ② Disassemble thrust plate F (609).
- ③ Disassemble in the order of thrust plate F
 (609) → Planetary gear F (605) →
 Needle bearing (615) → Collar (613) →
 Thrust washer (611)

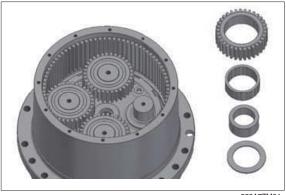


559A7TM62



559A7TM63

Mark each planetary gear, needle bearing, and inner race in the assembled position so that each combination and assembly position does not change.



559A7TM64

- (11) Do not disassemble any further unless there is a specific problem.In this condition, check the parts according to the inspection instructions shown in Section 1-2.
- If there is no problem after checking in this step, the following disassembly is not necessary.

- (12) Disassemble pipe plug (625).
- * When disassembling the pipe plug (625), Do not reuse.



559A7TM65

(13) Disassemble the nut ring (604).

* Please disassemble the nut ring using the

dedicated jig referring to the attachment.



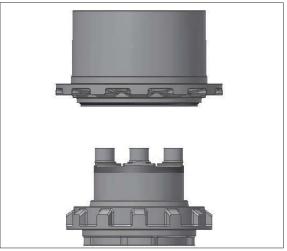
559A7TM66

0 .

(14) Disassemble casing (202) from housing (601).



559A7TM68



559A7TM69

- (15) After disassembling the pipe plug (626), remove the steel ball (622).
- The number of steel ball is 105.
 When disassembling, be sure to check the number of balls.



559A7TM70

(16) Disassemble the floating seal kit (618).



(17) Disassemble angular bearing (617).



559A7TM72

* Use a press for disassembly.



* The disassembly process is finished.

5) ASSEMBLY

(1) After placing angular bearing (617) on housing (601), press the angular bearing (617) using a press.



559A7TM72

* Assemble the protrusion of the inner ring face down.



559A7TM73

- (2) Insert 105ea steel ball (622) into housing(601) and tighten the pipe plug (626).
- * Pipe plug is assembled by wrapping Teflon tape.

After assembling the pipe plug, check if the cloud condition of the angular bearing is smooth.

(3) Assemble the floating seal kit (618) using dedicated jig for casing (202) and housing (601).



* Before assembling, check the metal surface of the floating seal for cracks, dents, and O-ring damage.

Do not apply oil to the floating seal rubber part.

After assembling the floating seal, check if there are any deviations.



559A7TM75

- (4) Using a press, assemble the housing sub on the casing (202).
- Floating seal are located on the same circumference.
 Rotate so that the floating seal is in place.



559A7TM68

- (5) Use the nut ring disassembly jig to assemble the nut ring (604).
- * After tightening, check the gap between casing and housing (0.5 ~1.5 mm) with a gauge.

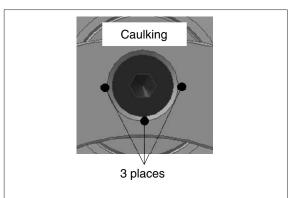


559A7TM66

(6) Tighten pipe plug (625).



* Caulking is performed to prevent loosening around the assembly.



559A7TM76

(7) Assemble the No. 2 holder assy
 Assemble in the order of thrust washer
 (611) → Collar (613) → Needle bearing
 (615) → Planetary gear F (605)

- * The thrust washer R part is assembled in the bearing direction and the chamfered part of the collar is assembled in the casing direction.
- <image>

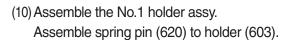
559A7TM77

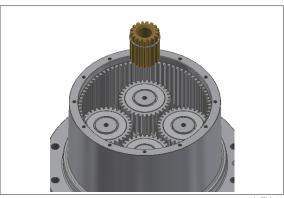
- (8) Assemble the thrust plate F (609), ext flush bolt (624).
- * Assemble ext flush bolt by applying loctite in the axial direction.



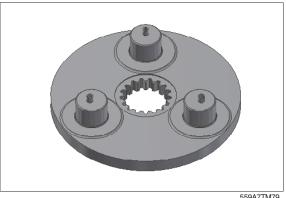
- (9) Fasten snap ring (621) to sun gear (607) using snap ring pliers. And assemble in the center of planetary gear F.
- * Assemble R part of snap ring toward cover.

Sun gear is assembled with the long end facing toward casing.





559A7TM78



559A7TM79

(11) Assemble the holder sub to the sun gear (607).

Then, assemble inner race (614) \rightarrow Needle bearing (616) \rightarrow planetary gear R.



559A7TM80

- * When assembling planetary gear R, assemble the convex part in the direction of thrust plate R.
- * Check the rotation status.



(12) Assemble drive gear (608) and thrust plate R (610).



559A7TM55

- (13) Assemble the O-ring (619), side plate A (627) and side plate B (628) on the cover (602).
- * After assembling the side plate B, remove any debris from the side.



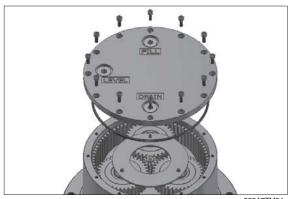
559A7TM82

(14) Assemble cover sub to housing.



559A7TM53

- (15) Assemble the socket bolt (623).
- * Assemble by applying loctite in the direction of the socket bolt axis.



559A7TM54

* The assembly process is finished.

GROUP 7 RCV LEVER

1. REMOVAL AND INSTALL

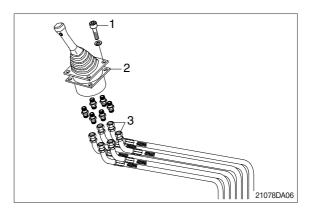
1) REMOVAL

- (1) Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- ▲ Escaping fluid under pressure can penetrate the skin causing serious injury.
- (4) Loosen the socket bolt (1).
- (5) Remove the cover of the console box.
- (6) Disconnect pilot line hoses (3).
- (7) Remove the pilot valve assembly (2).
- When removing the pilot valve assembly, check that all the hoses have been disconnected.

2) INSTALL

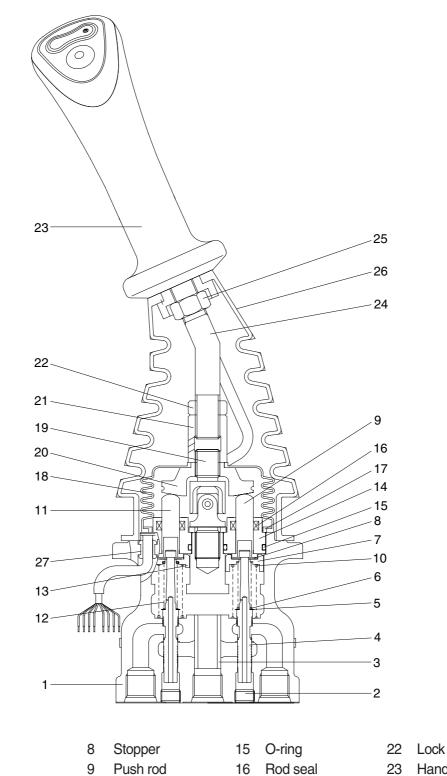
- (1) Carry out installation in the reverse order to removal.
- (2) Confirm the hydraulic oil level and check the hydraulic oil leak or not.





2. DISASSEMBLY AND ASSEMBLY

1) STRUCTURE



Plug 2

1

Bushing 3

Case

- 4 Spool
- 5 Shim
- 6 Spring
- Spring seat 7
- 10 Spring
- 11 Push rod
- 12 Spring
- Spring seat 13
 - 14 Plug

- Plate 17
- 18 Boot
- Joint assembly 19
- Swash plate 20
- 21 Adjusting nut

555C92RL02

- Lock nut
- Handle assembly
- Handle bar 24
- 25 Nut
- 26 Boot
- 27 Bushing

7-101

2) TOOLS AND TIGHTENING TORQUE

(1) Tools

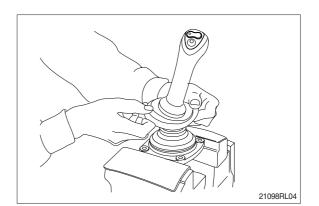
Tool name	Remark				
Allen wrench	6 <u>B</u>				
Spapper	22				
Spanner	27				
(+) Driver	Length 150				
(-) Driver	Width 4~5				
Torque wrench	Capable of tightening with the specified torques				

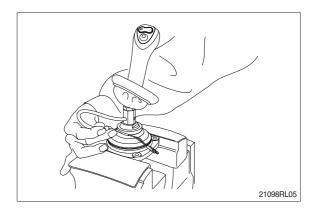
(2) Tightening torque

Part name	Item	Size	Torque			
Fait name	nem	Size	kgf ∙ m	lbf ⋅ ft		
Plug	2	PT 1/8	3.0	21.7		
Joint	18	M14	3.5	25.3		
Swash plate	19	M14	5.0 ± 0.35	36.2±2.5		
Adjusting nut	20	M14	5.0±0.35	36.2±2.5		
Lock nut	21	M14	5.0±0.35	36.2±2.5		
Screw	29	М З	0.05	0.36		

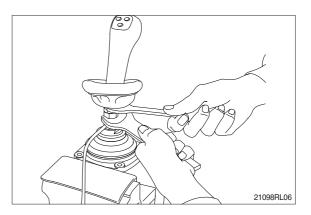
3) DISASSEMBLY

- (1) Clean pilot valve with kerosene.
- * Put blind plugs into all ports
- (2) Fix pilot valve in a vise with copper (or lead) sheets.
- (3) Remove end of boot (26) from case (1) and take it out upwards.
- * For valve with switch, remove cord also through hole of casing.

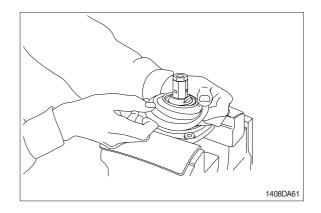




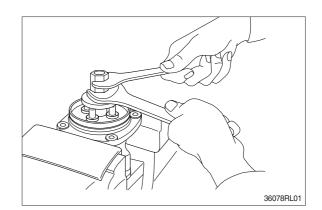
(4) Loosen lock nut (22) and adjusting nut(21) with spanners on them respectively, and take out handle section as one body.

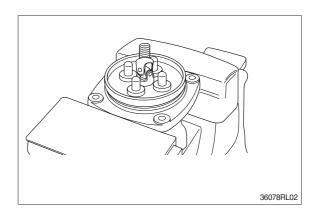


(5) Remove the boot (18).

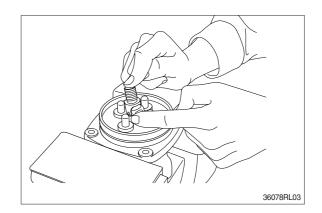


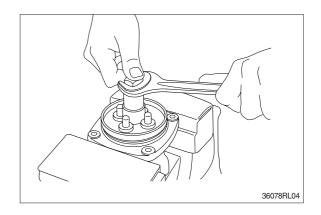
(6) Loosen adjusting nut (21) and plate (20) with spanners on them respectively, and remove them.



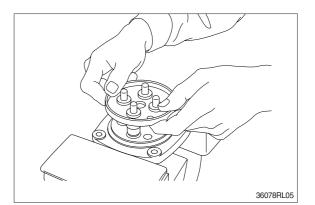


- (7) Turn joint anticlockwise to loosen it, utilizing jig (special tool).
- When return spring (10) is strong in force, plate (17), plug (14) and push rod (11) will come up on loosening joint.
 Pay attention to this.

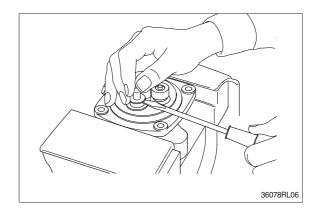


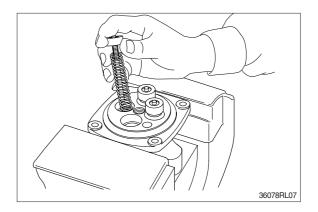


(8) Remove plate (17).

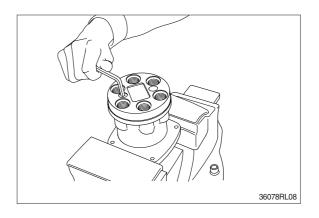


- (9) When return spring (10) is weak in force, plug (14) stays in casing because of sliding resistance of O-ring.
- * Take it out with minus screwdriver. Take it out, utilizing external periphery groove of plug and paying attention not to damage it by partial loading.
- During taking out, plug may jump up due to return spring (10) force.
 Pay attention to this.
- (10) Remove reducing valve subassembly and return spring (10) out of casing.
- Record relative position of reducing valve subassembly and return springs.





(11) Loosen hexagon socket head plug (2) with hexagon socket screw key.



- (12) For disassembling reducing valve section, stand it vertically with spool (4) bottom placed on flat workbench. Push down spring seat (7) and remove two pieces of semicircular stopper (8) with tip of small minus screwdriver.
- * Pay attention not to damage spool surface.
- * Record original position of spring seat (7).
- * Do not push down spring seat more than 6 mm.
- 36078RL09
- (13) Separate spool (4), spring seat (7), spring * Until being assembled, they should be
- (14) Take push rod (14) out of plug (11).

(6) and shim (5) individually.

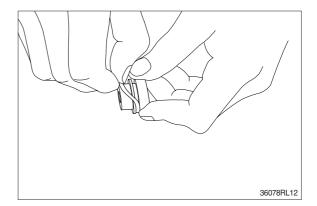
handled as one subassembly group.

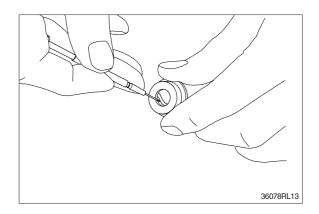
36078RL11

36078RL10

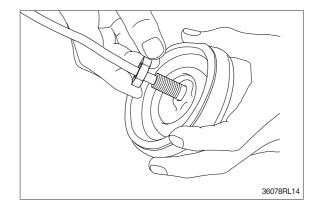
(15) Remove O-ring (15) and seal (16) from plug (14).

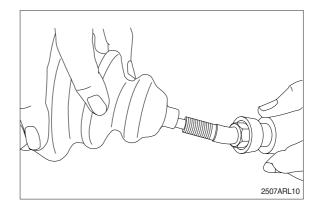
Use small minus screwdriver or so on to remove this seal.





(16) Remove lock nut (22) and then boot (26).





(17) Cleaning of parts

- Put all parts in rough cleaning vessel filled with kerosene and clean them (rough cleaning).
- If dirty part is cleaned with kerosene just after putting it in vessel, it may be damaged. Leave it in kerosene for a while to loosen dust and dirty oil.
- If this kerosene is polluted, parts will be damaged and functions of reassembled valve will be degraded.

Therefore, control cleanliness of kerosene fully.

- ② Put parts in final cleaning vessel filled with kerosene, turning it slowly to clean them even to their insides (finish cleaning).
- Do not dry parts with compressed air, since they will be damaged and/or rusted by dust and moisture in air.

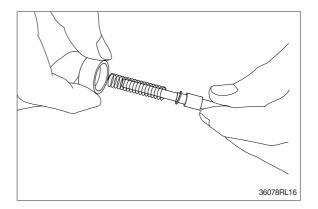
(18) Rust prevention of parts.

Apply rust-preventives to all parts.

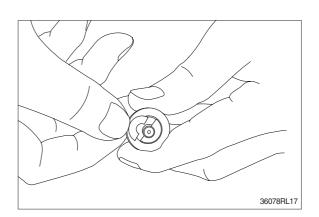
If left as they after being cleaned, they will be rusted and will not display their functions fully after being reassembled.

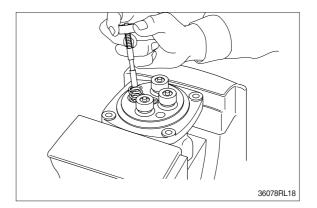
4) ASSEMBLY

- (1) Tighten hexagon socket head plug (2) to the specified torque.
- * Tighten two bolts alternately and slowly.
- 36078RL15
- (2) Put shim (5), springs (6) and spring seat(7) onto spool (4) in this order.

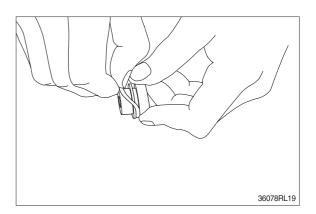


- (3) Stand spool vertically with its bottom placed on flat workbench, and with spring seat pushed down, put two pieces of semicircular stopper (8) on spring seat without piling them on.
- Assemble stopper (8) so that its sharp edge side will be caught by head of spool. Do not push down spring seat more than 6 mm.
- (4) Assemble spring (10) into casing (1).Assemble reducing valve subassembly into casing.
- * Assemble them to their original positions.

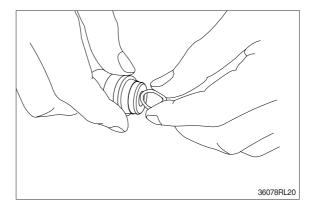




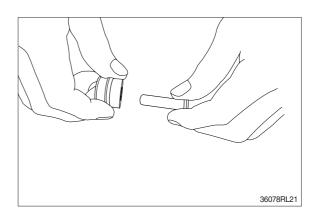
(5) Assemble O-ring (15) onto plug (14).



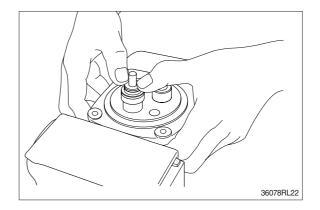
- (6) Assemble seal (16) to plug (14).
- * Assemble seal in such lip direction as shown below.



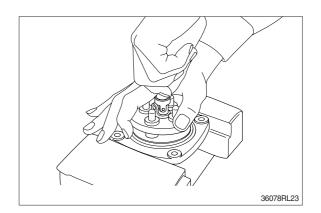
- (7) Assemble push rod (11) to plug (14).
- $\, \ast \,$ Apply working oil on push-rod surface.



- (8) Assemble plug subassembly to casing.
- When return spring is weak in force, subassembly stops due to resistance of O-ring.

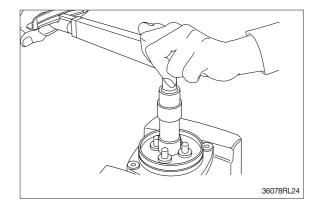


(9) When return spring is strong in force, assemble 4 sets at the same time, utilizing plate (17), and tighten joint (19) temporarily.



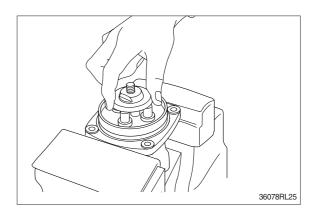
(10) Fit plate (17).

(11) Tighten joint (19) with the specified torque to casing, utilizing jig.

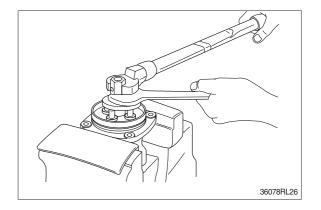


(12) Assemble plate (20) to joint (19).

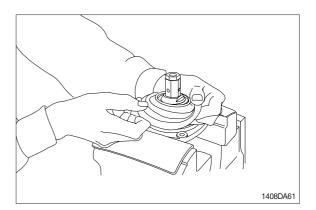
- * Screw it to position that it contacts with 4 push rods evenly.
- * Do not screw it over.



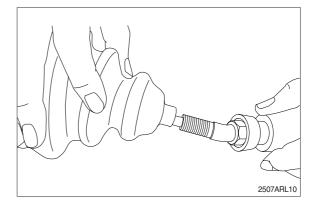
- (13) Assemble adjusting nut (21), apply spanner to width across flat of swash plate (20) to fix it, and tighten adjusting nut to the specified torque.
- * During tightening, do not change position of disk.

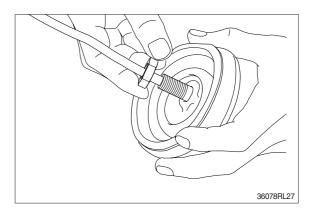


(14) Fit boot (18) to plate.

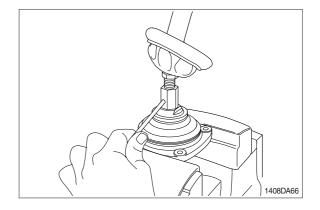


(15) Fit boot (26) and lock nut (22), and handle subassembly is assembled completely.

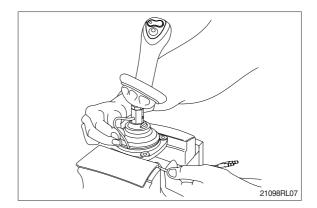




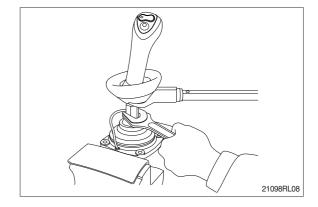
(16) Pull out cord and tube through adjusting nut hole provided in direction 60° to 120° from casing hole.



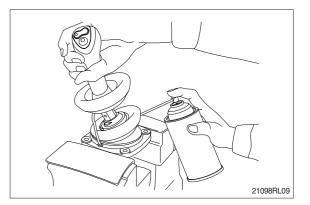
- (17) Assemble bushing (27) to plate and pass cord and tube through it.
- * Provide margin necessary to operation.



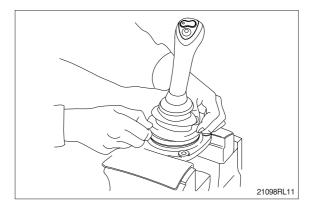
(18) Determine handle direction, tighten locknut (22) to specified torque to fix handle.



(19) Apply grease to rotating section of joint and contacting faces of disk and push rod.



- (20) Assemble lower end of bellows to casing.
- (21) Inject volatile rust-preventives through all ports and then put blind plugs in ports.



GROUP 8 TURNING JOINT

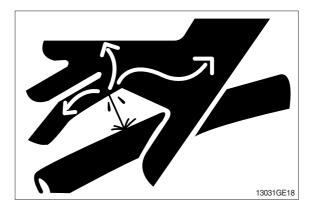
1. REMOVAL AND INSTALL

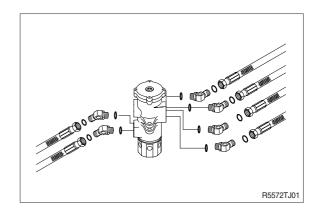
1) REMOVAL

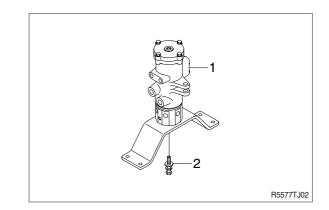
- (1) Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- Escaping fluid under pressure can penetrate the skin causing serious injury.
- When pipes and hoses are disconnected, the oil inside the piping will flow out, so catch it in oil pan.
- (4) Disconnect all hoses.
- (5) Sling the turning joint assembly (1) and remove the mounting bolt (2).
 - Weight : 30 kg (70 lb)
 - $\begin{array}{l} \cdot \text{ Tightening torque : } 12.3 \pm 1.3 \text{ kgf} \cdot \text{m} \\ (88.9 \pm 9.4 \text{ lbf} \cdot \text{ft}) \end{array}$
- (6) Remove the turning joint assembly.
- * When removing the turning joint, check that all the hoses have been disconnected.

2) INSTALL

- (1) Carry out installation in the reverse order to removal.
- * Take care of turning joint direction.
- * Assemble hoses to their original positions.
- * Confirm the hydraulic oil level and check the hydraulic oil leak or not.

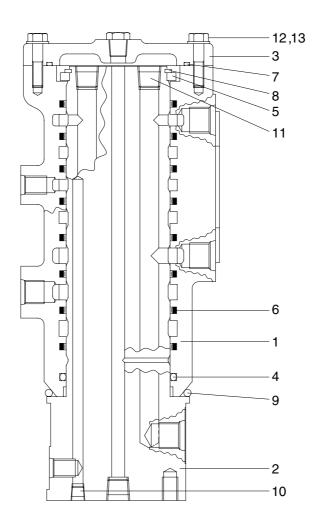






2. DISASSEMBLY AND ASSEMBLY

1) STRUCTURE



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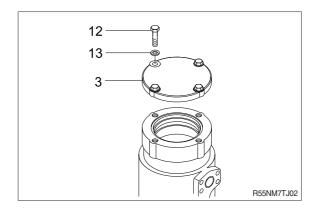
- 1 Hub
- 2 Shaft
- 3 Cover
- 4 O-ring
- 5 Ring

- 6 Slipper seal
- 7 O-ring
- 8 Retainer ring
- 9 O-ring

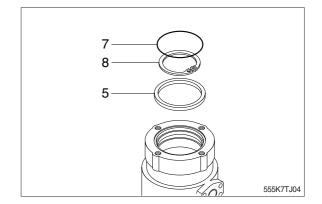
- 10 Plug
- 11 Plug
- 12 Hexagon bolt
- 13 Spring washer

2) DISASSEMBLY

- * Before the disassembly, clean the turning joint.
- (1) Remove bolts (12), washer (13) and cover(3).



- (2) Remove O-ring (7).
- (3) Remove retainer ring (8) and ring (5).



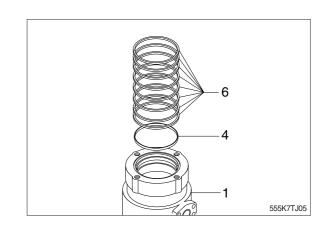
Wooden block

V block

Secure with hand

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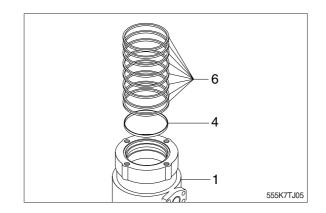
- (4) Place hub (1) on a V-block and by using a wood buffer at the shaft end, hit out shaft(2) to about 1/2 from the body with a hammer.
- * Take care not to damage the shaft (2) when remove hub (1) or rest it sideway.
- * Put a fitting mark on hub (1) and shaft (2).
- (5) Remove eight slipper seals (6) and O-ring(4) from hub (1).



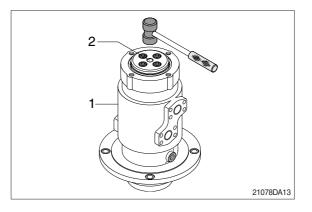
Work bench

3) ASSEMBLY

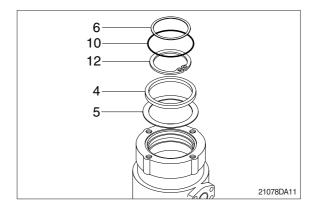
- * Clean all parts.
- * As a general rule, replace oil seals and O-ring.
- * Coat the sliding surfaces of all parts with engine oil or grease before installing.
- (1) Fix eight slipper seal (6) and O-ring (4) to hub (1).



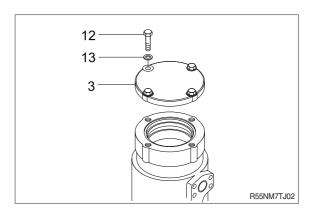
(2) Set shaft (2) on block, tap hub (1) with a plastic hammer to install.



- (3) Ring (5) and retainer ring (8) to shaft (2).
- (4) Fit O-ring (7) to hub (1).



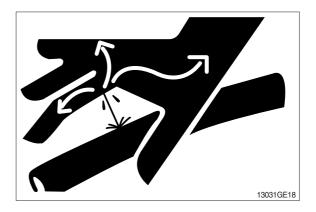
(5) Install cover (3) to body (1) and tighten bolts (12) with washer (13).

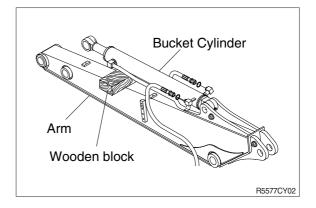


GROUP 9 BOOM, ARM AND BUCKET CYLINDERS

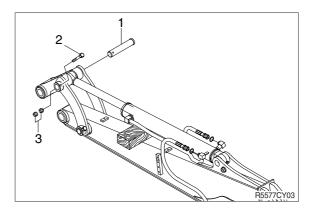
1. REMOVAL AND INSTALL

- 1) BUCKET CYLINDER
- (1) Removal
- Expand the arm and bucket fully, lower the work equipment to the ground and stop the engine.
- * Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- ▲ Loosen the breather slowly to release the pressure inside the hydraulic tank. Escaping fluid under pressure can penetrate the skin causing serious injury.
- Fit blind plugs in the hoses after disconnecting them, to prevent dirt or dust from entering.
- ① Set block between bucket cylinder and arm.

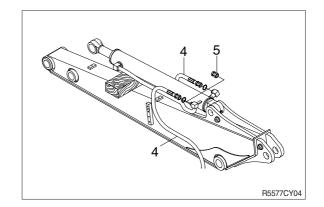




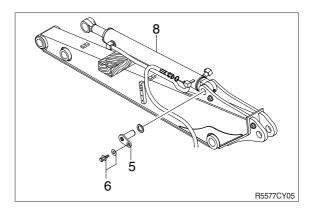
- 2 Remove bolt (2), nut (3) and pull out pin (1).
- * Tie the rod with wire to prevent it from coming out.



③ Disconnect bucket cylinder hoses (4) and put plugs (5) on cylinder pipe.



- ④ Sling bucket cylinder assembly (8) and remove bolt (6) then pull out pin (5).
- (5) Remove bucket cylinder assembly (8).
 - Weight : 30 kg (70 lb)



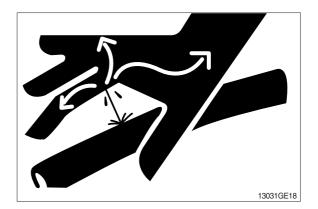
(2) Install

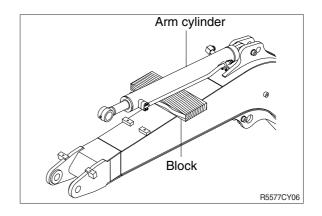
- ① Carry out installation in the reverse order to removal.
- ▲ When aligning the mounting position of the pin, do not insert your fingers in the pin hole.
- * Bleed the air from the bucket cylinder.
- Confirm the hydraulic oil level and check the hydraulic oil leak or not.

2) ARM CYLINDER

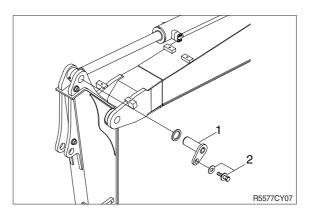
(1) Removal

- Expand the arm and bucket fully, lower the work equipment to the ground and stop the engine.
- * Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- ▲ Loosen the breather slowly to release the pressure inside the hydraulic tank.
- Escaping fluid under pressure can penetrate the skin causing serious injury.
- Fit blind plugs in the hoses after disconnecting them, to prevent dirt or dust from entering.
- ① Set block between arm cylinder and boom.

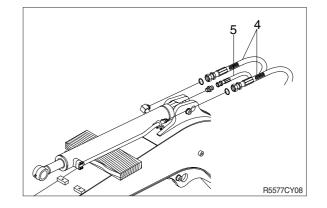




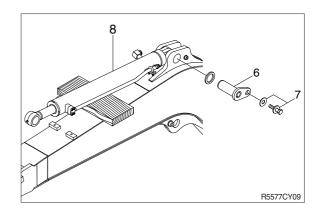
- ② Remove bolt (2) and pull out pin (1).
- * Tie the rod with wire to prevent it from coming out.



- ③ Disconnect arm cylinder hoses (4) and put plugs on cylinder pipe.
- ④ Disconnect greasing pipings (5).



- (5) Sling arm assembly (8) and remove bolt(7) then pull out pin (6).
- 6 Remove arm cylinder assembly (8).
 - Weight : 50 kg (110 lb)

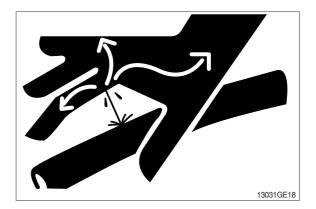


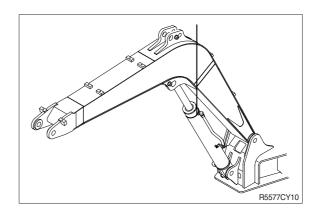
- ① Carry out installation in the reverse order to removal.
- A When aligning the mounting position of the pin, do not insert your fingers in the pin hole.
- * Bleed the air from the arm cylinder.
- Confirm the hydraulic oil level and check the hydraulic oil leak or not.

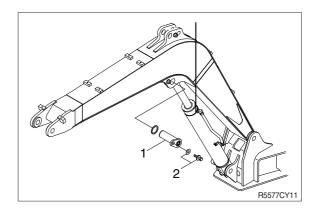
3) BOOM CYLINDER

(1) Removal

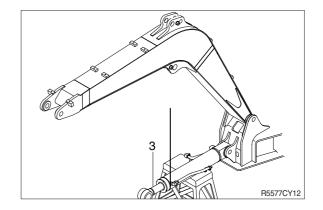
- Expand the arm and bucket fully, lower the work equipment to the ground and stop the engine.
- * Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping.
- A Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrate the skin causing serious injury.
- Fit blind plugs in the hoses after disconnecting them, to prevent dirt or dust from entering.
- ① Disconnect greasing hoses (1).
- ② Sling boom cylinder assembly.
- ③ Remove bolt (2) and pull out pin (1).
- * Tie the rod with wire to prevent it from coming out.



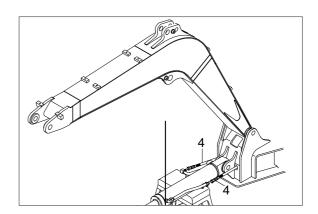




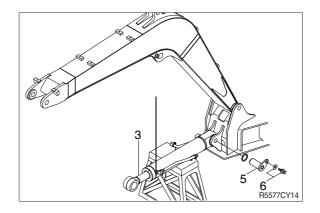
④ Lower the boom cylinder assembly (3) on a stand.



⑤ Disconnect boom cylinder hoses (4) and put plugs on cylinder pipe.



- 6 Remove bolt (6) and pull out pin (5).
- O Remove boom cylinder assembly (3).
 - · Weight : 60 kg (130 lb)

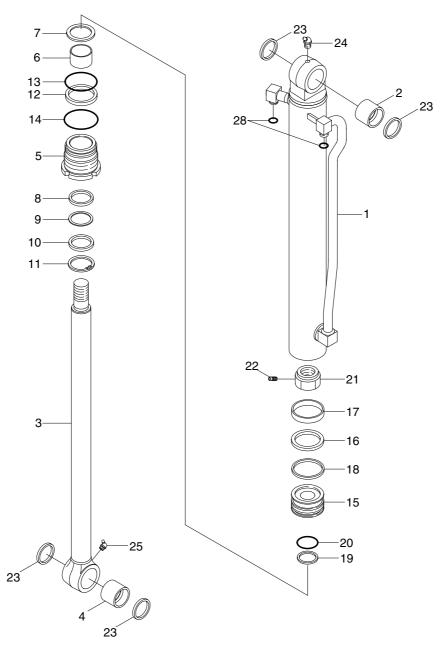


- ① Carry out installation in the reverse order to removal.
- A When aligning the mounting position of the pin, do not insert your fingers in the pin hole.
- * Conformed the hydraulic oil level and check the hydraulic oil leak or not.

2. DISASSEMBLY AND ASSEMBLY

1) STRUCTURE

(1) Bucket cylinder

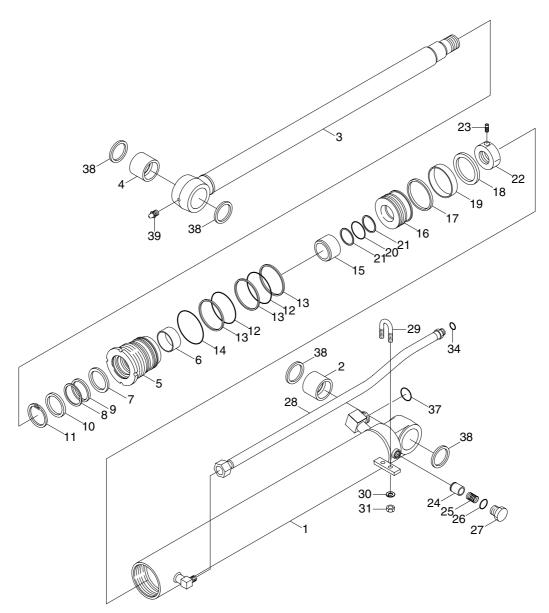


555C97CY22

- 1 Tube assembly
- 2 Bushing
- 3 Bushing
- 4 Du bushing
- 5 Rod cover
- 6 Rod bushing
- 7 Retaining ring
- 8 Buffer ring
- 9 U-packing

- 10 Dust seal
- 11 Retaining ring
- 12 Back-up ring
- 13 O-ring
- 14 O-ring
- 15 Piston
- 16 Piston seal
- 17 Wear ring
- 18 Dust ring

- 19 Back-up ring
- 20 O-ring
- 21 Piston nut
- 22 Set screw
- 23 Dust seal
- 24 Grease nipple
- 25 Grease nipple
- 28 O-ring

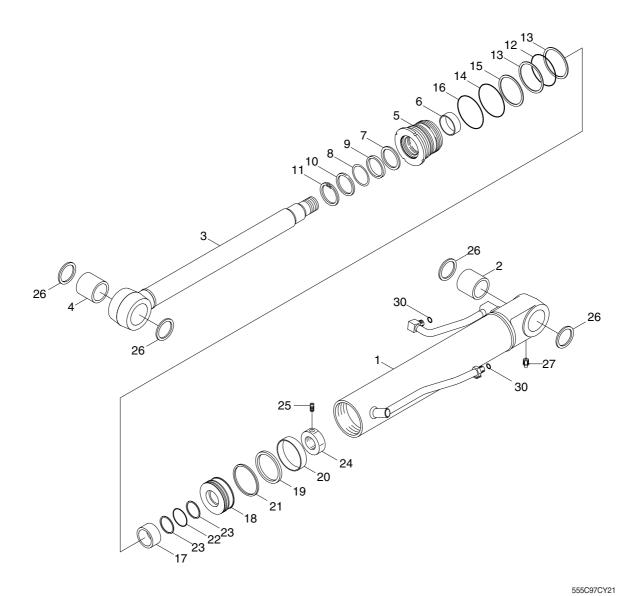


555C97CY24

- 1 Tube assembly
- 2 Bushing
- 3 Bushing
- 4 DD2 bushing
- 5 Rod cover
- 6 Rod bushing
- 7 Buffer seal
- 8 U-packing
- 9 Back-up ring
- 10 Dust wiper
- 11 Retaining ring

- 12 O-ring
- 13 Back-up ring
- 14 O-ring
- 15 Cushion ring
- 16 Piston
- 17 Piston seal
- 18 Wear ring
- 19 Dust ring
- 20 Wear ring
- 21 Back-up ring
- 22 Piston nut

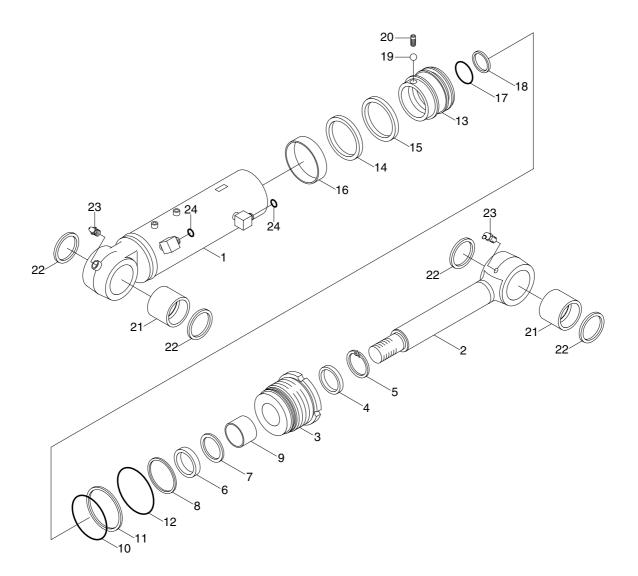
- 23 Set screw
- 24 Check valve
- 25 Spring
- 26 Support spring
- 29 U-bolt
- 30 Spring washer
- 31 Hex nut
- 34 O-ring
- 37 O-ring
- 38 Dust seal
- 39 Grease nipple



- 1 Tube assembly
- 2 Bushing
- 3 Bushing
- 4 Du bushing
- 5 Rod cover
- 6 Rod bushing
- 7 Buffer ring
- 8 U-packing
- 9 Back-up ring
- 10 Dust seal

- 11 Retaining ring
- 12 O-ring
- 13 Back-up ring
- 14 O-ring
- 15 Back-up ring
- 16 O-ring
- 17 Cushion ring
- 18 Piston
- 19 Piston seal
- 20 Wear ring

- 21 Dust ring
- 22 O-ring
- 23 Back-up ring
- 24 Piston nut
- 25 Set screw
- 26 Dust seal
- 27 Grease nipple
- 30 O-ring



- 1 Tube assembly
- 2 Rod assembly
- 3 Gland
- 4 Dust wiper
- 5 Retaining ring
- 6 Rod seal
- 7 Back-up ring
- 8 Buffer ring

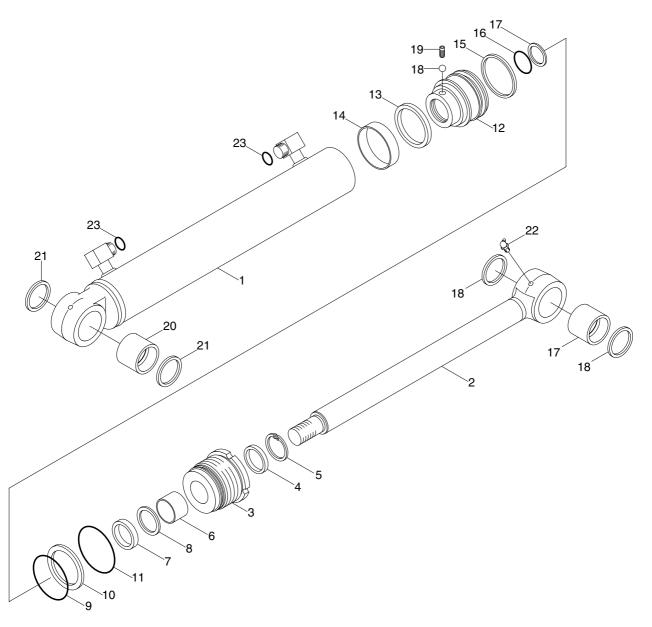
- 9 DU bushing
- 10 O-ring
- 11 Back-up ring
- 12 O-ring
- 13 Piston
- 14 Piston seal
- 15 Dust ring
- 16 Wear ring

- 17 O-ring
- 18 Back-up ring

5597CY23

- 19 Steel ball
- 20 Set screw
- 21 Bushing
- 22 Dust seal
- 23 Grease nipple
- 24 O-ring

(5) Boom swing cylinder



5596MC02

- 1 Tube assembly
- 2 Rod assembly
- 3 Gland
- 4 Dust wiper
- 5 Retaining ring
- 6 DU bushing
- 7 Rod seal
- 8 Buck-up ring

- 9 O-ring
- 10 Buck-up ring
- 11 O-ring
- 12 Piston
- 13 Piston seal
- 14 Wear ring
- 15 Dust ring
- 16 O-ring

- 17 Back-up ring
- 18 Steel ball
- 19 Set screw
- 20 Pin bushing
- 21 Dust seal
- 22 Grease nipple
- 23 O-ring

2) TOOLS AND TIGHTENING TORQUE

(1) Tools

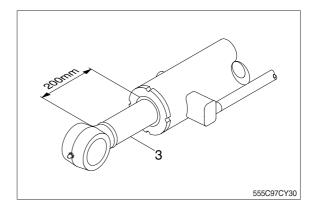
Name	Specification		
	8 B		
Allen wrench	10		
Spanner	M22		
Hook spanner	Suitable size		
(-) Driver	Small and large sizes		
Torque wrench	Capable of tightening with the specified torques		

(2) Tightening torque

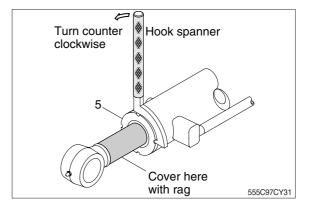
Part name		ltem	Size	Torque	
		nem		kgf ∙ m	lbf ∙ ft
	Boom cylinder	3	M115	70±7.0	510±51
	Arm cylinder	3	M95	70±7.0	510±51
Rod cover	Bucket cylinder	3	M85	75±7.5	540±54
	Dozer cylinder	3	M115	95±9.5	690±69
	Boom swing cylinder	3	M100	70±7.0	510±51
	Boom cylinder	22	M45	75±7.5	540±54
	Arm cylinder	21	M39	75±7.5	540±54
Piston nut	Bucket cylinder	19	M36	75±7.5	540±54
	Dozer cylinder	16	M45	113±11.3	817±137
	Boom swing cylinder	12	M39	97.5±9.8	705±71

3) DISASSEMBLY

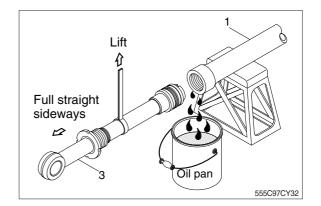
- (1) Remove cylinder head and piston rod
- ① Hold the clevis section of the tube in a vise.
- * Use mouth pieces so as not to damage the machined surface of the cylinder tube. Do not make use of the outside piping as a locking means.
- ② Pull out rod assembly (3) about 200 mm (7.1 in). Because the rod assembly is rather heavy, finish extending it with air pressure after the oil draining operation.



- ③ Remove rod cover (5) by hook spanner.
- * Cover the extracted rod assembly (3) with rag to prevent it from being accidentally damaged during operation.

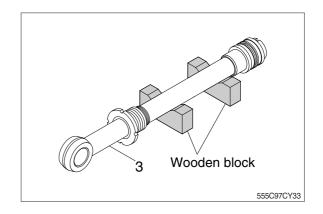


- ④ Draw out cylinder head and rod assembly(3) together from tube assembly (1).
- Since the rod assembly is heavy in this case, lift the tip of the rod assembly (3) with a crane or some means and draw it out. However, when rod assembly (3) has been drawn out to approximately two thirds of its length, lift it in its center to draw it completely.



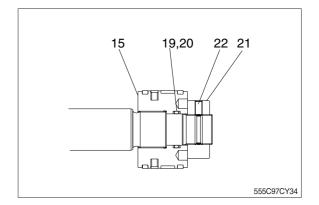
Note that the plated surface of rod assembly (3) is to be lifted. For this reason, do not use a wire sling and others that may damage it, but use a strong cloth belt or a rope.

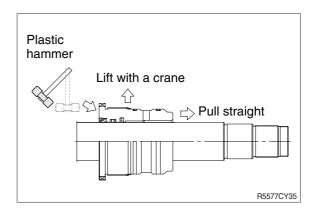
- ⑤ Place the removed rod assembly on a wooden V-block that is set level.
- * Cover a V-block with soft rag.



(2) Remove piston and rod cover

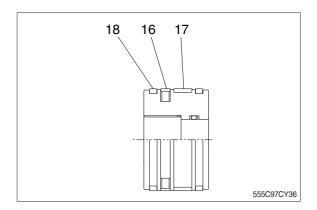
- ① Loosen set screw (22) and remove piston nut (21).
- Since piston nut (21) is tightened to a high torque, use a hydraulic and power wrench that utilizers a hydraulic cylinder, to remove the piston nut (21).
- ② Remove piston assembly (15), back up ring (19), and O-ring (20).
- ③ Remove the rod cover from rod assembly (3).
- If it is too heavy to move, move it by striking the flanged part of gland with a plastic hammer.
- Pull it straight with cylinder head assembly lifted with a crane.
 Exercise care so as not to damage the lip of Du bushing (6) and packing (8, 9, 10, 11, 12, 13, 14) by the threads of rod assembly (3).





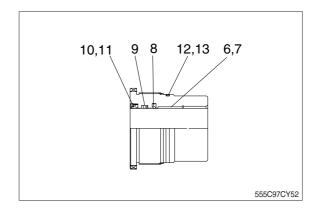
(3) Disassemble the piston assembly

- 1 Remove wear ring (17).
- ② Remove dust ring (18) and piston seal (16).
- * Exercise care in this operation not to damage the grooves.



(4) Disassemble gland assembly

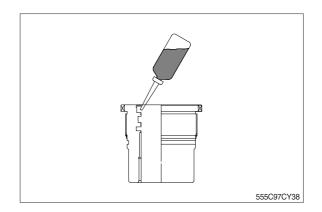
- Remove back up ring (12) and O-ring (13).
- ② Remove snap ring (11), dust wiper (10).
- ③ Remove U-packing (9) and buffer seal (8).
- * Exercise care in this operation not to damage the grooves.
- * Do not remove seal and ring, if does not damaged.



4) ASSEMBLY

(1) Assemble cylinder head assembly

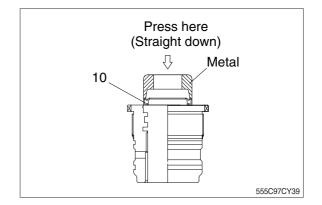
- * Check for scratches or rough surfaces if found smooth with an oil stone.
- ① Coat the inner face of rod cover (5) with hydraulic oil.



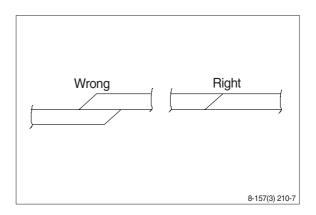
② Coat dust wiper (10) with grease and fit dust wiper (10) to the bottom of the hole of dust seal.

At this time, press a pad metal to the metal ring of dust seal.

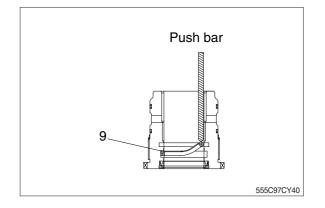
 \bigcirc Fit snap ring (11) to the stop face.



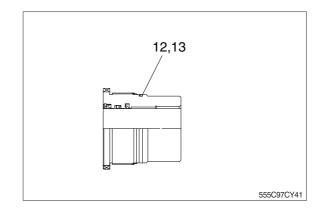
- ④ Fit U-packing (9) and buffer seal (8) to corresponding grooves, in that order.
- * Coat each packing with hydraulic oil before fitting it.
- Insert the backup ring until one side of it is inserted into groove.



- U-packing (9) has its own fitting direction.
 Therefore, confirm it before fitting them.
- Fitting U-packing (9) upside down may damage its lip. Therefore check the correct direction that is shown in fig.

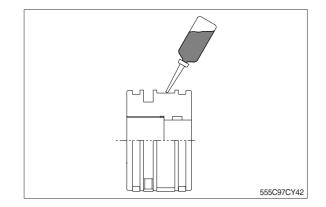


- (5) Fit back up ring (12) to rod cover (5).
- * Put the backup ring in the warm water of $30{\sim}50^{\circ}C$.
- 6 Fit O-ring (13) to rod cover (5).

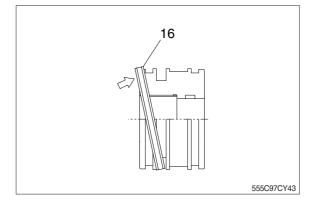


(2) Assemble piston assembly

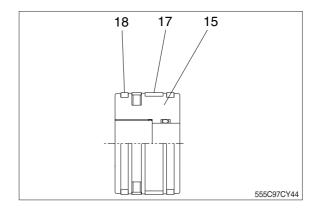
- * Check for scratches or rough surfaces. If found smooth with an oil stone.
- ① Coat the outer face of piston (15) with hydraulic oil.



- ② Fit piston seal (16) to piston.
- * Put the piston seal in the warm water of 60~100°C for more than 5 minutes.
- * After assembling the piston seal, press its outer diameter to fit in.

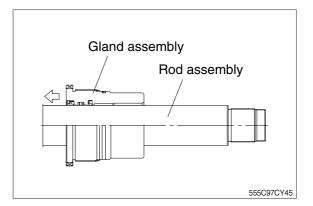


③ Fit wear ring (17) and dust ring (18) to piston (15).

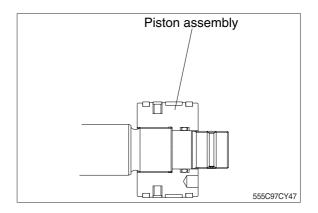


(3) Install piston and cylinder head

- Tix the rod assembly to the work bench.
- ② Apply hydraulic oil to the outer surface of rod assembly (3), the inner surface of piston and cylinder head.
- ③ Insert cylinder head assembly to rod assembly.

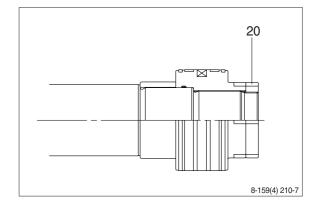


⁵ Fit piston assembly to rod assembly.



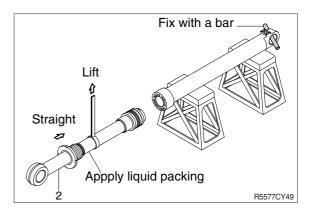
6 Fit piston nut and tighten the set screw (22).

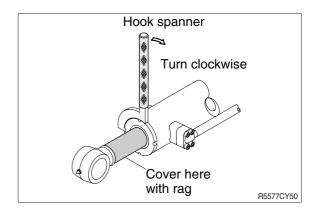
Item		kgf ∙ m	lbf ∙ ft
Boom	22	75±7.5	540±54
Arm	21	75±7.5	540±54
Bucket	19	75±7.5	540±54
Dozer	16	113±11.3	817±137
Boom swing	12	97.5±9.8	705±71



(3) Overall assemble

- Place a V-block on a rigid work bench. Mount the tube assembly (2) on it and fix the assembly by passing a bar through the clevis pin hole to lock the assembly.
- ② Insert the rod assembly in to the tube assembly, while lifting and moving the rod assembly with a crane.
- * Be careful not to damage piston seal by thread of tube assembly.
- ③ Match the bolt holes in the cylinder head flange to the tapped holes in the tube assembly and tighten socket bolts to a specified torque.
- * Refer to the table of tightening torque.



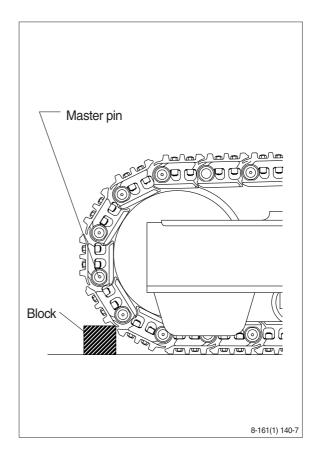


GROUP 10 UNDERCARRIAGE

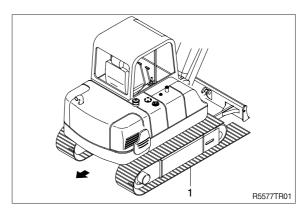
1. TRACK LINK

1) REMOVAL

- Move track link until master pin is over front idler in the position put wooden block as shown.
- (2) Loosen tension of the track link.
- If track tension is not relieved when the grease valve is loosened, move the machine backwards and forwards.
- (3) Push out master pin by using a suitable tool.

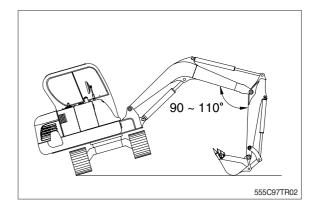


- (4) Move the machine slowly in reverse, and lay out track link assembly (1).
- * Jack up the machine and put wooden block under the machine.
- Don't get close to the sprocket side as the track shoe plate may fall down on your feet.



2) INSTALL

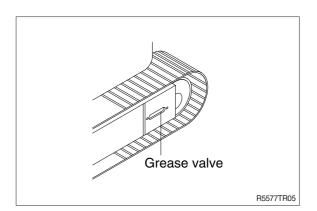
- (1) Carry out installation in the reverse order to removal.
- * Adjust the tension of the track link.



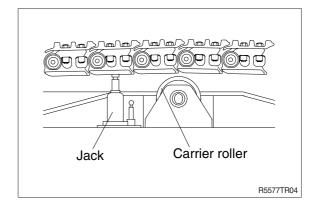
2. CARRIER ROLLER

1) REMOVAL

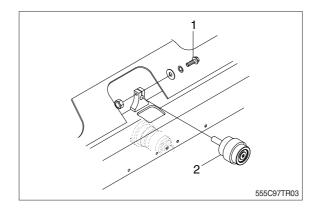
(1) Loosen tension of the track link.



(2) Jack up the track link height enough to permit carrier roller removal.



- (3) Remove bolt (1) at both side.
- (4) Remove carrier roller (2). • Weight : 10 kg (20 lb)



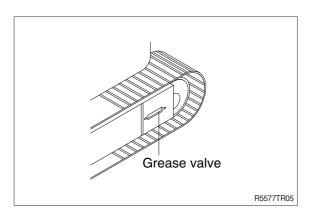
2) INSTALL

(1) Carry out installation in the reverse order to removal.

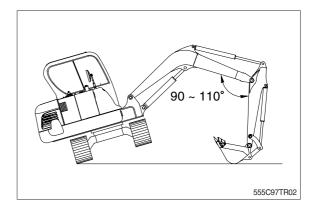
3. TRACK ROLLER

1) REMOVAL

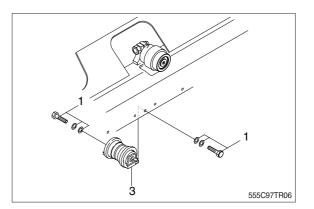
(1) Loosen tension of the track link.



- (2) Using the work equipment, push up track frame on side which is to be removed.
- * After jack up the machine, set a block under the unit.



(3) Remove the mounting bolt (1) and draw out the track roller (3).Weight : 10 kg (20 lb)



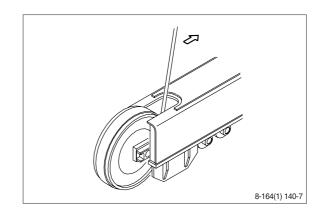
2) INSTALL

(1) Carry out installation in the reverse order to removal.

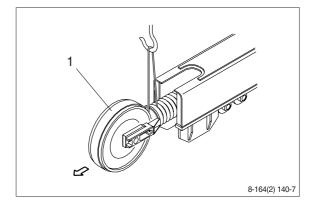
4. IDLER AND RECOIL SPRING

1) REMOVAL

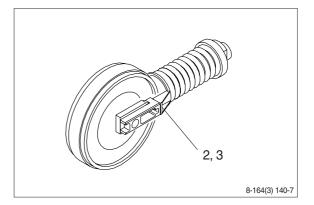
Remove the track link.
 For detail, see removal of track link.



- (2) Sling the recoil spring (1) and pull out idler and recoil spring assembly from track frame, using a pry.
 - · Weight : 100 kg (220 lb)

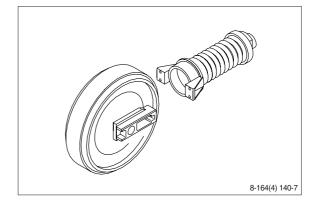


(3) Remove the bolts (2), washers (3) and separate idler from recoil spring.



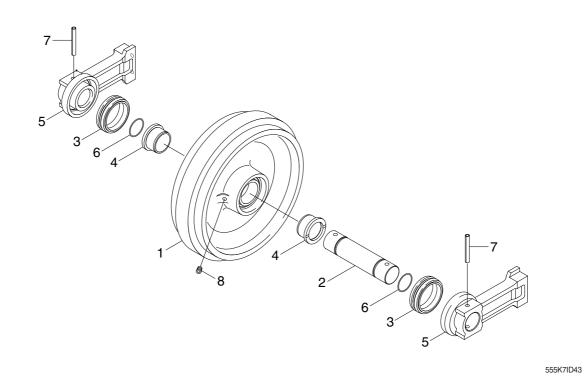
2) INSTALL

- (1) Carry out installation in the reverse order to removal.
- Make sure that the boss on the end face of the recoil cylinder rod is in the hole of the track frame.



3) DISASSEMBLY AND ASSEMBLY OF IDLER

(1) Structure



1 Shell

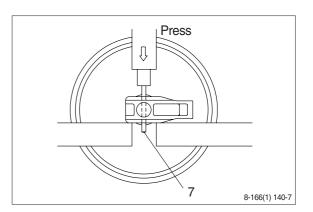
4 Bushing

7 Spring pin8 Plug

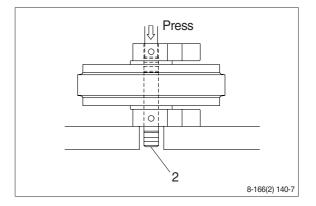
- 2 Shaft
- 3 Seal assembly
- 5 Bracket
- 6 O-ring

(2) Disassembly

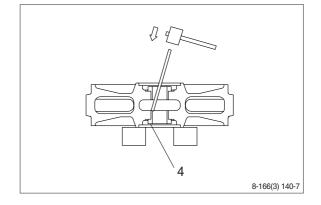
- 1 Remove plug and drain oil.
- ⁽²⁾ Draw out the spring pin (7), using a press.



- \bigcirc Pull out the shaft (2) with a press.
- ④ Remove seal (3) from idler (1) and bracket (5).
- ⁽⁵⁾ Remove O-ring (6) from shaft.



- ⑥ Remove the bushing (4) from idler, using a special tool.
- * Only remove bushing if replacement is necessity.

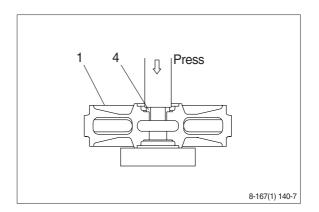


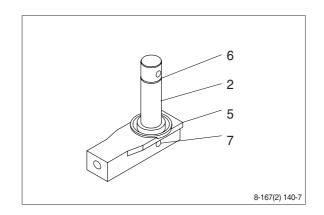
(3) Assembly

- * Before assembly, clean the parts.
- * Coat the sliding surfaces of all parts with oil.
- Cool up bushing (4) fully by some dry ice and press it into shell (1).

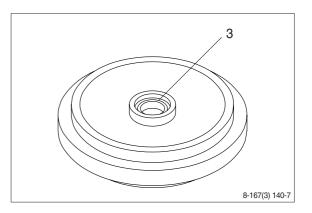
Do not press it at the normal temperature, or not knock in with a hammer even after the cooling.

- ② Coat O-ring (6) with grease thinly, and install it to shaft (2).
- ③ Insert shaft (2) into bracket (5) and drive in the spring pin (7).

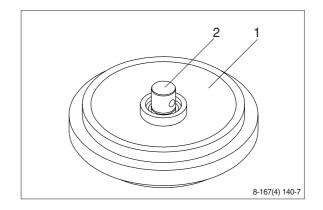




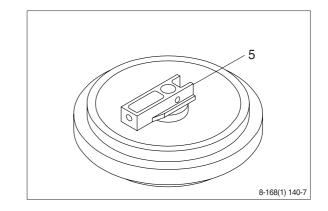
4 Install seal (3) to shell (1) and bracket (5).



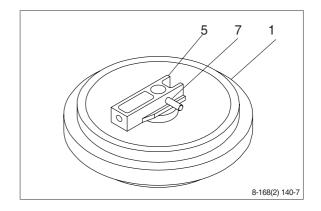




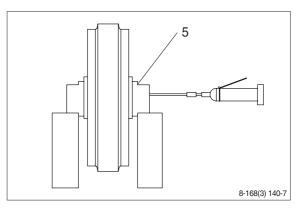
⑥ Install bracket (5) attached with seal (3).



⑦ Knock in the spring pin (7) with a hammer.

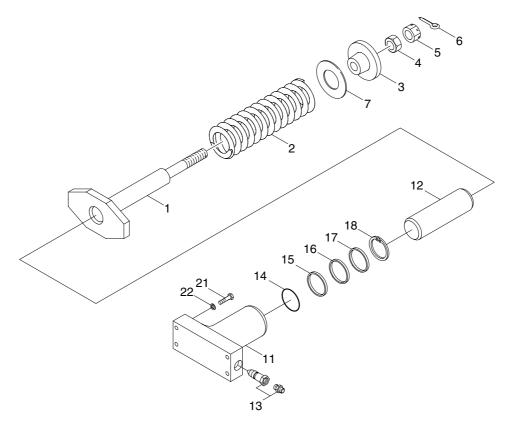


⑧ Lay bracket (5) on its side. Supply engine oil to the specified level, and tighten plug.



4) DISASSEMBLY AND ASSEMBLY OF RECOIL SPRING

(1) Structure



1 Rod

3

4

5

6

2 Spring

Lock washer

Slotted hex-nut

Hex-nut

Split pin

- Spacer 7
- 11 Bracket
- 12 Piston
 - Grease valve 13
 - O-ring 14
 - Back-up ring 15

16 Dust-seal

R5577RS01

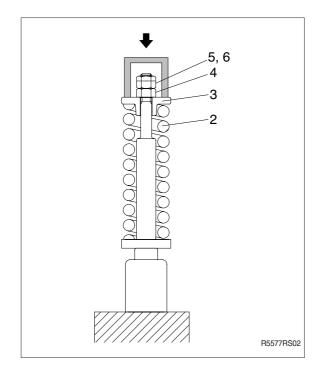
- Spacer
- 17
- Retaining ring 18
- Bolt 21
- 22 Washer

(2) Disassembly

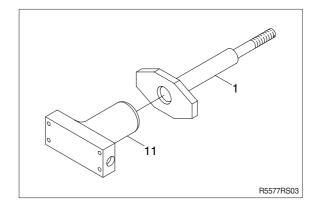
- ① Apply pressure on spring (3) with a press. The spring is under a large installed load.
- * This is dangerous, so be sure to set properly.
 - · Spring set load : 3900 kg (8600 lb)
- 2 Remove split pin (6) and nut (5).
- ③ Remove lock nut (4).

Take enough notice so that the press which pushes down the spring, should not be slipped out in its operation.

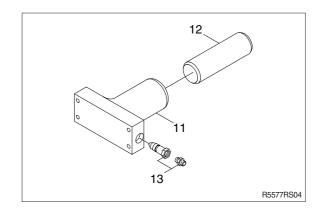
④ Lighten the press load slowly and remove lock washer (3) and spring (2).



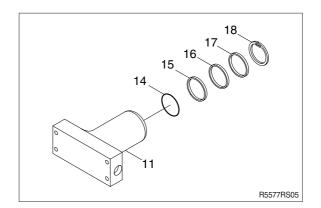
(5) Remove rod (1) from bracket (11).



- 6 Remove grease valve (13) from bracket (11).
- O Remove piston (12) from bracket (11).

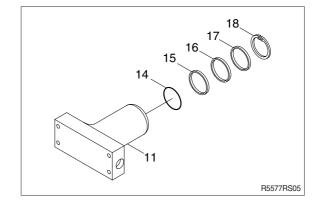


8 Remove retaining ring (18), spacer (17), dust seal (16), back-up ring (15) and O-ring (14).

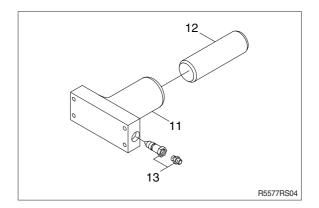


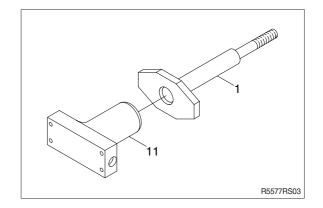
(3) Assembly

- Install O-ring (14), back-up ring (15), dust seal (16), spacer (17) and retaining ring (18) to bracket (11).
- When installing dust seal (16) take full care so as not to damage the lip.



- Pour grease into bracket (11), then push in piston (12) by hand.
 After take grease out of grease valve mounting hole, let air out.
- * If air letting is not sufficient, it may be difficult to adjust the tension of crawler.
- \bigcirc Fit grease value (13) to bracket (11).
 - \cdot Tightening torque : 10±0.5 kg \cdot m (72.4±3.6 lb \cdot ft)
- ④ Install rod (1) to bracket (11).

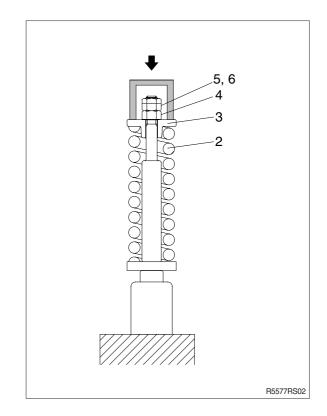




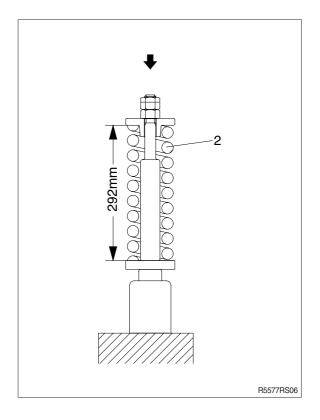
- Install spring (3) and bracket (4) to body (1).
- ⑥ Apply pressure to spring (3) with a press and tighten nut (4).
- * Apply sealant before assembling.
- * During the operation, pay attention specially to prevent the press from slipping out.
 - \cdot Tightening torque : 30 \pm 3 kgf \cdot m

(217±21 lbf ⋅ ft)

O Tighten nut (5) and insert split pin (6).

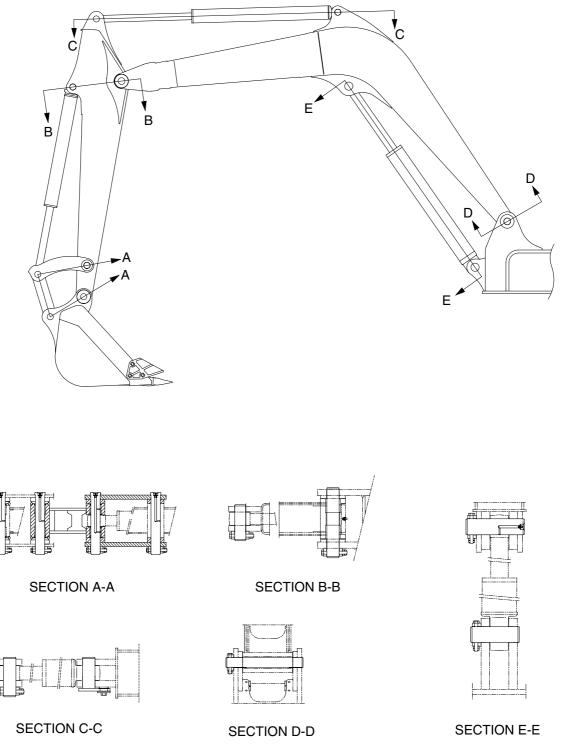


⑧ Lighten the press load and confirm the set length of spring (2).



GROUP 11 WORK EQUIPMENT

1. STRUCTURE



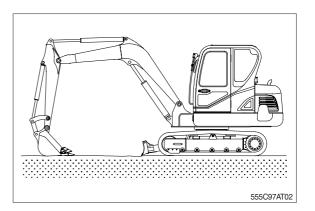
R5577AT01

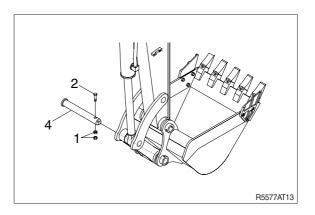
2. REMOVAL AND INSTALL

1) BUCKET ASSEMBLY

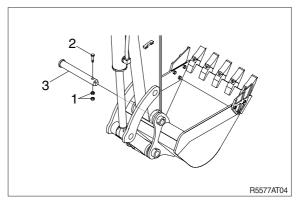
(1) Removal

- ① Lower the work equipment completely to ground with back of bucket facing down.
- ⁽²⁾ Remove nut (1), bolt (2) and draw out the pin (4).

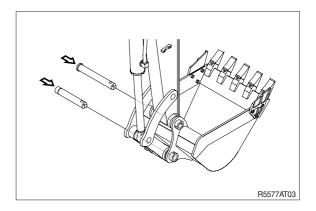




③ Remove nut (1), bolt (2) and draw out the pin (3) then remove the bucket assembly.
 · Weight : 170 kg (370 lb)



- Carry out installation in the reverse order to removal.
- A When aligning the mounting position of the pin, do not insert your fingers in the pin hole.
- Adjust the bucket clearance.
 For detail, see operation manual.



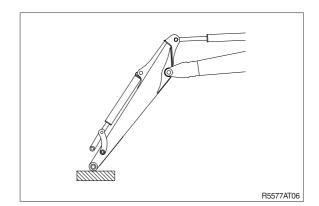
2) ARM ASSEMBLY

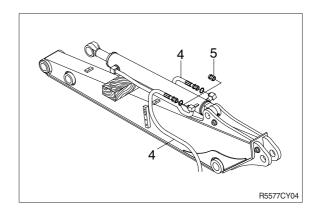
(1) Removal

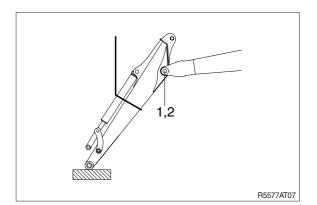
- * Loosen the breather slowly to release the pressure inside the hydraulic tank.
- A Escaping fluid under pressure can penetrated the skin causing serious injury.
- Remove bucket assembly.
 For details, see removal of bucket assembly.
- ② Disconnect bucket cylinder hose (4).
- ▲ Fit blind plugs (5) in the piping at the chassis end securely to prevent oil from spurting out when the engine is started.
- ③ Sling arm cylinder assembly, remove spring, pin stopper and pull out pin.
- * Tie the rod with wire to prevent it from coming out.
- ④ For details, see removal of arm cylinder assembly.

Place a wooden block under the cylinder and bring the cylinder down to it.

- ⑤ Remove bolt (1) and pull out the pin (2) then remove the arm assembly.
 · Weight : 210 kg (470 lb)
- * When lifting the arm assembly, always lift the center of gravity.







- ① Carry out installation in the reverse order to removal.
- A When lifting the arm assembly, always lift the center of gravity.
- * Bleed the air from the cylinder.

3) BOOM CYLINDER

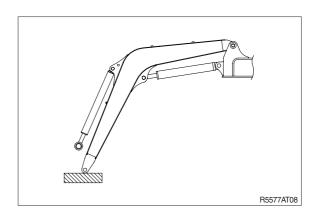
(1) Removal

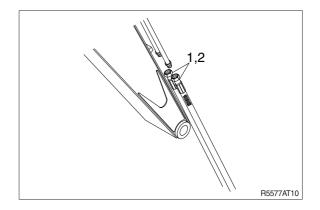
- ① Remove arm and bucket assembly.
- ② For details, see removal of arm and bucket assembly.

Remove boom cylinder assembly from boom.

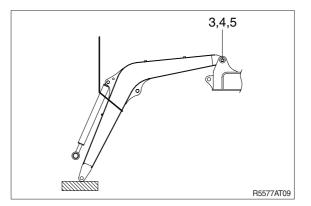
For details, see removal of arm cylinder assembly.

- ③ Disconnect head lamp wiring.
- ④ Disconnect bucket cylinder hose (2) and arm cylinder hos e(1).
- When the hose are disconnected, oil may spurt out.
- (5) Sling boom assembly (3).

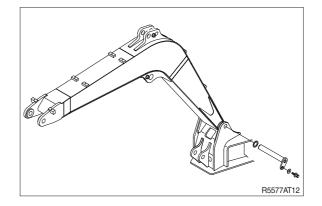




- (6) Remove bolt (3), nut (4) and pull out the pin (5) then remove boom assembly.
 Weight : 310 kg (680 lb)
- * When lifting the boom assembly always lift the center of gravity.



- Carry out installation in the reverse order to removal.
- A When lifting the arm assembly, always lift the center of gravity.
- * Bleed the air from the cylinder.



SECTION 8 COMPONENT MOUNTING TORQUE

Group	1	Introduction guide	8-1
Group	2	Engine system ·····	8-2
Group	3	Electric system ·····	8-4
Group	4	Hydraulic system ·····	8-5
Group	5	Undercarriage	8-7
Group	6	Structure	8-8
Group	7	Work equipment ·····	8-10

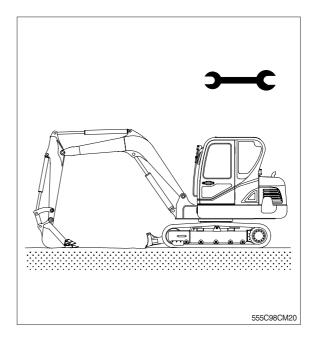
SECTION 8 COMPONENT MOUNTING TORQUE

GROUP 1 INTRODUCTION GUIDE

- 1. This section shows bolt specifications and standard torque values needed when mounting components to the machine.
- Use genuine Hyundai spare parts. We expressly point out that Hyundai will not accept any responsibility for defects resulted from non-genuine parts.

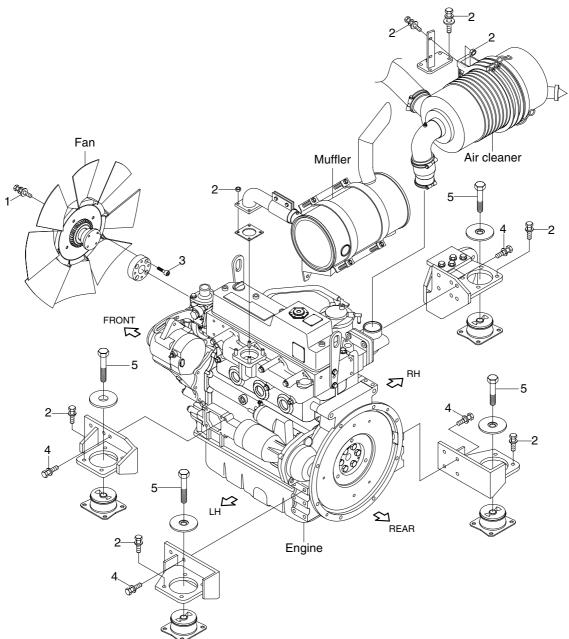
In such cases Hyundai cannot assume liability for any damage.

- * Only metric fasteners can be used and incorrect fasteners may result in machine damage or malfunction.
- Before installation, clean all the components with a non-corrosive cleaner.
 Bolts and threads must not be worn or damaged.



GROUP 2 ENGINE SYSTEM

1. ENGINE AND ACCESSORIES MOUNTING

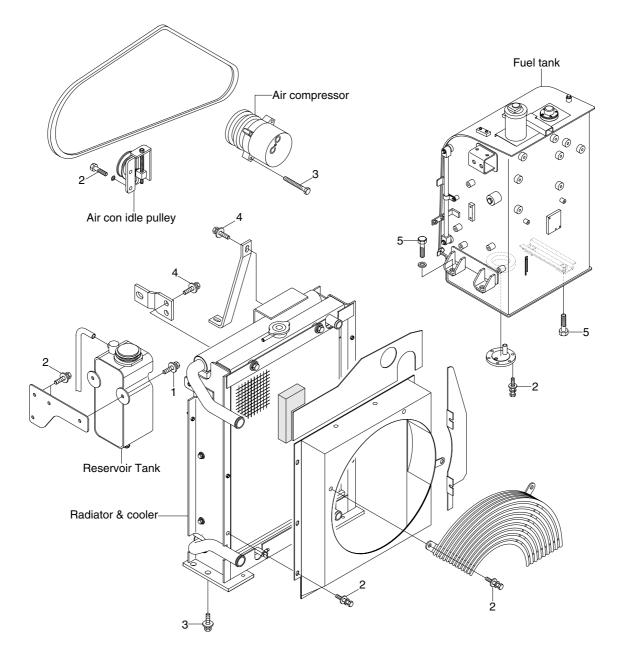


5598CM01

Item	Size	kgf ∙ m	lbf ⋅ ft
1	M 8×1.25	1.8±0.2	13.0±1.4
2	M 8×1.25	2.5±0.5	18.1±3.6
3	M 8×1.25	3.0±0.2	21.7±1.4

Item	Size	kgf ∙ m	lbf ⋅ ft
4	M10×1.5	6.9±1.0	49.9±7.2
5	M16×2.0	25±2.5	181 ± 18

2. COOLING SYSTEM AND FUEL TANK MOUNTING



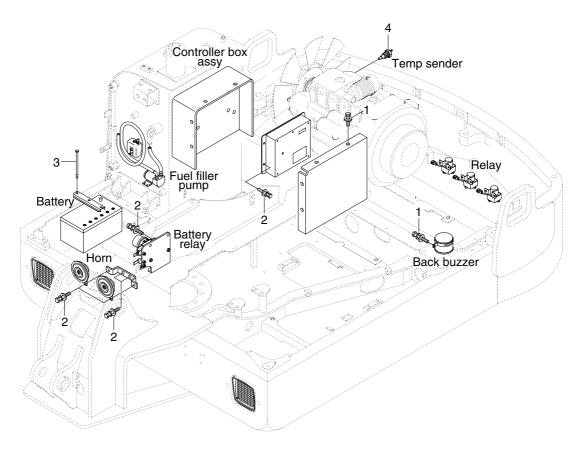
5598CM02

Item	Size	kgf ∙ m	lbf ∙ ft
1	M 6×1.0	1.05±0.2	7.6±1.45
2	M 8×1.25	2.5±0.5	18.1±3.6
3	M10×1.25	6.9±1.4	49.9±10.1

Item	Size	kgf ∙ m	lbf ⋅ ft
4	M12×1.75	12.8±3.0	92.6±21.7
5	M16×2.0	25±2.5	181±18.1

GROUP 3 ELECTRIC SYSTEM

1. ELECTRIC COMPONENTS MOUNTING 1



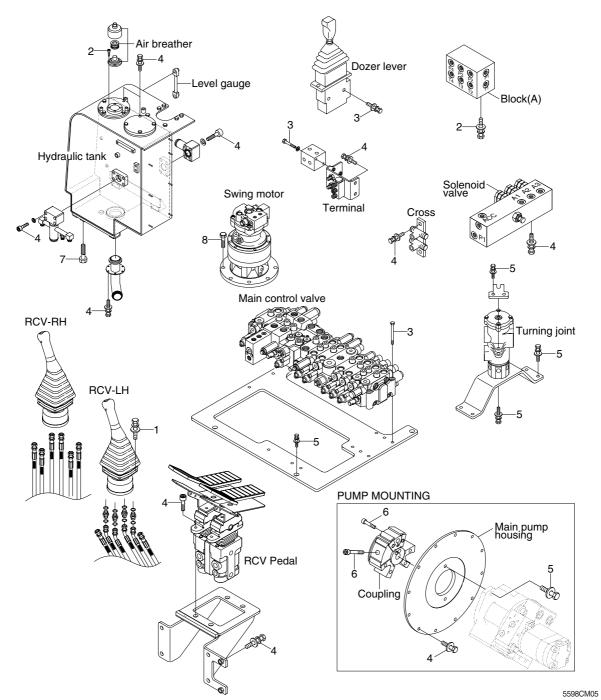
5598CM03

Item	Size	kgf ∙ m	lbf ⋅ ft
1	M 6×1.0	1.05±0.2	7.6±1.45
2	M 8×1.25	2.5 ± 0.5	18.1±3.6

Item	Size	kgf ∙ m	lbf ∙ ft
3	M10×1.5	6.9±1.4	49.9±10.1
4	-	2.0±0.2	14.5±1.4

GROUP 4 HYDRAULIC SYSTEM

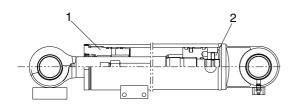
1. HYDRAULIC COMPONENTS MOUNTING 1



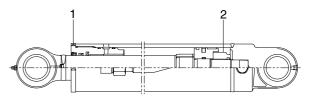
Item	Size	kgf ∙ m	lbf ⋅ ft
1	M 6×1.0	1.05±0.2	7.6±1.45
2	M 6×1.0	1.44 ± 0.3	10.4±2.2
3	M 8×1.25	2.5±0.5	18.1±3.6
4	M10×1.5	6.9±1.4	49.9±10.1

Item	Size	kgf ∙ m	lbf ⋅ ft
5	M12×1.75	12.2±1.3	88.2±9.4
6	M14×2.0	14.0±1.0	101±7.2
7	M16×2.0	25.0±2.5	118±18.1
8	M16×2.0	29.7±4.5	215±33.0

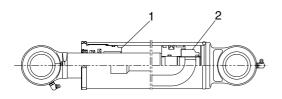
2. HYDRAULIC COMPONENTS MOUNTING 2

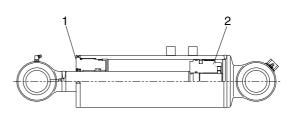


BOOM CYLINDER



ARM CYLINDER





BUCKET CYLINDER

DOZER CYLINDER

5598CM07

• Tightening torque

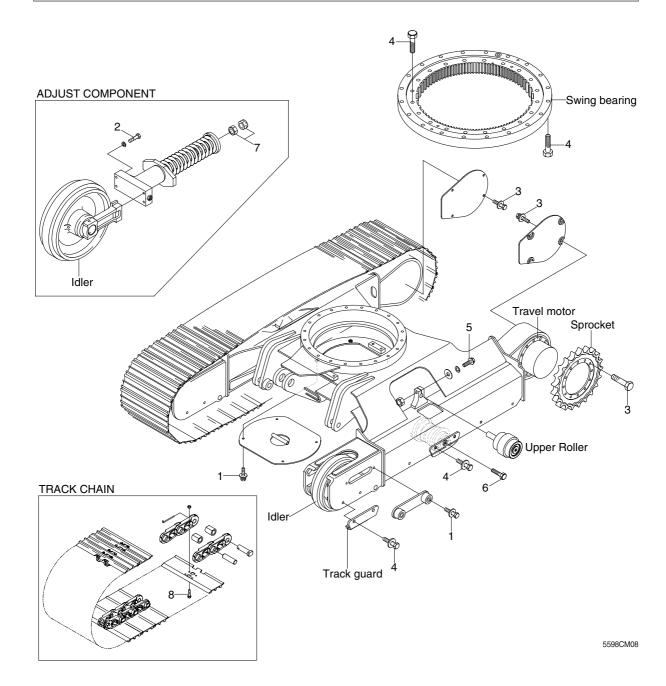
Rod cover (1)

Item	Size	kgf ∙ m	lbf ∙ ft
Boom cylinder	M115	70±7.0	506±51
Arm cylinder	M95	70±7.0	506±51
Bucket cylinder	M85	75±7.5	542±54
Dozer cylinder	M115	95±9.5	690±69

Piston nut (2)

ltem	Size	kgf ∙ m	lbf ∙ ft
Boom cylinder	M45	75±7.5	542±54
Arm cylinder	M39	75±7.5	542±54
Bucket cylinder	M36	75±7.5	542±54
Dozer cylinder	M45	113±11.3	817±82

GROUP 5 UNDERCARRIAGE

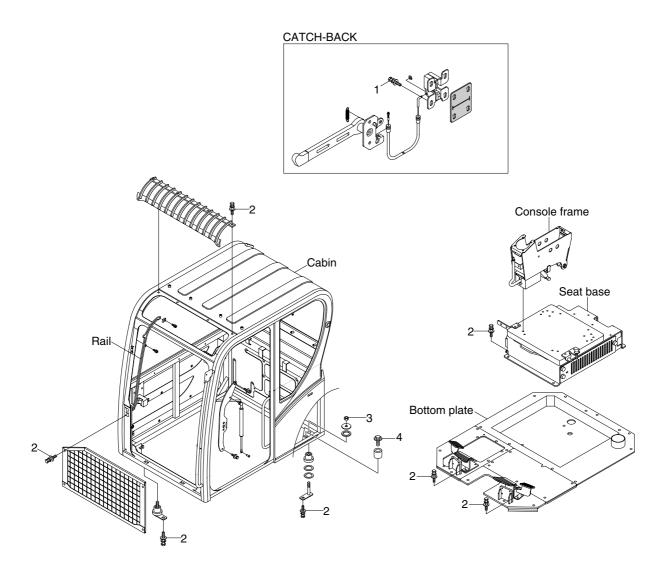


Item	Size	kgf ∙ m	lbf ⋅ ft
1	M10×1.5	6.9±1.4	49.9±10.1
2	M12×1.75	12.8±3.0	92.6±21.7
3	M14×2.0	19.6±2.5	142±18.0
4	M16×2.0	29.7±4.5	215±32.5

Item	Size kgf · m		lbf ⋅ ft
5	M18×2.0	41.0±5.0	297±36.0
6	M20×2.5	57.8±6.4	418±46.3
7	1/2-12	19.0±1.0	137±7.2

GROUP 6 STRUCTURE

1. CAB AND ACCESSORIES MOUNTING

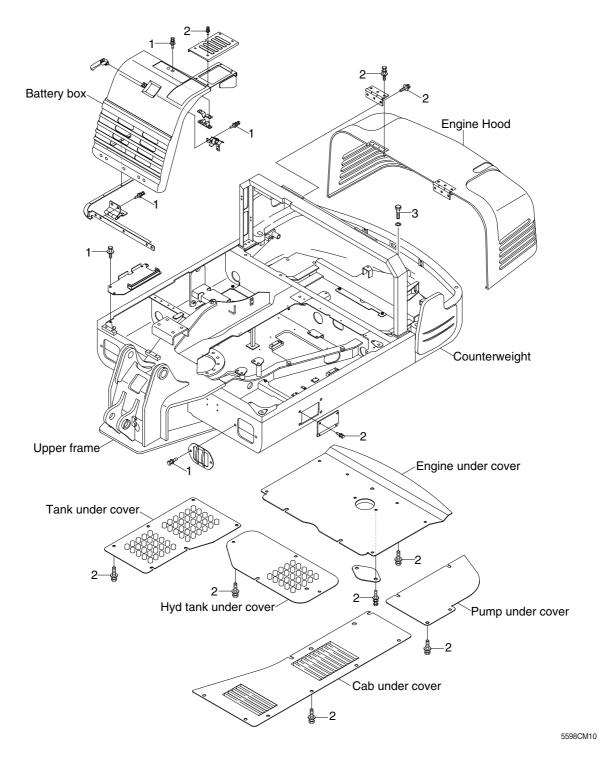


5598CM09

Item	Size	kgf ∙ m	lbf ∙ ft
1	M 8×1.25	2.5±0.5	18.1±3.6
2	M10×1.5	4.7±0.9	34.0±6.5

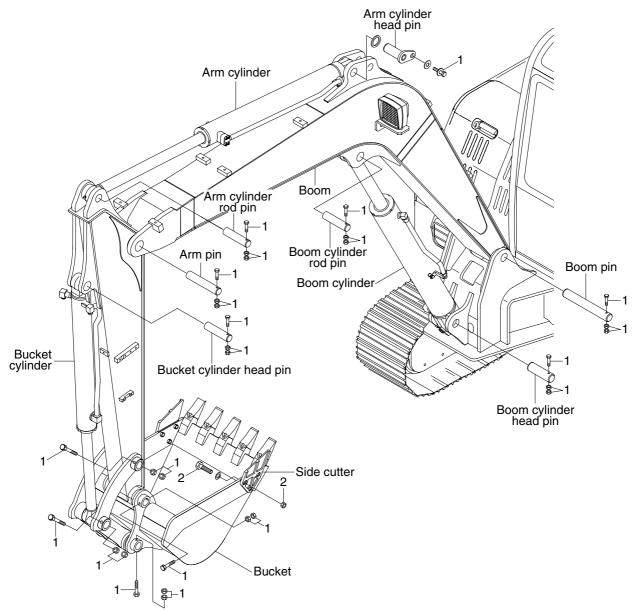
Item	Size	kgf ∙ m	lbf ∙ ft	
3	M12×1.75	12.8±3.0	92.6±21.7	
4	M16×2.0	29.7±4.5	215±32.5	

2. COWLING MOUNTING



Ite	em	Size	kgf ∙ m	lbf ⋅ ft	Item	Size	kgf ∙ m	lbf ⋅ ft
	1	M 8×1.25	2.5±0.5	18.1±3.6	3	M20×2.5	57.8±6.4	418±46.3
	2	M10×1.5	6.9±1.4	49.9±10.1				

GROUP 7 WORK EQUIPMENT



5598CM11

Item	Size	kgf ∙ m	lbf ∙ ft
1	M12×1.75	12.8±3.0	92.6±21.7

Item	Size	kgf ∙ m	lbf ⋅ ft
2	M16×2.0	29.7±4.5	215±32.5