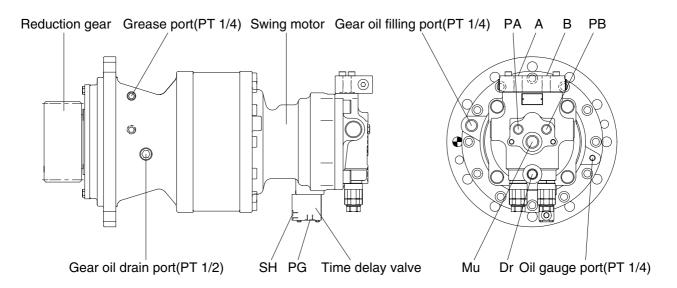
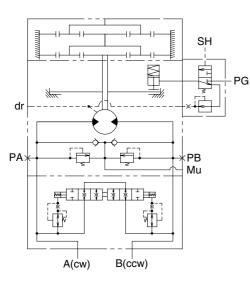
GROUP 3 SWING DEVICE

1. STRUCTURE

Swing device consists swing motor, swing reduction gear. Swing motor include mechanical parking valve, relief valve, make up valve and time delay valve.



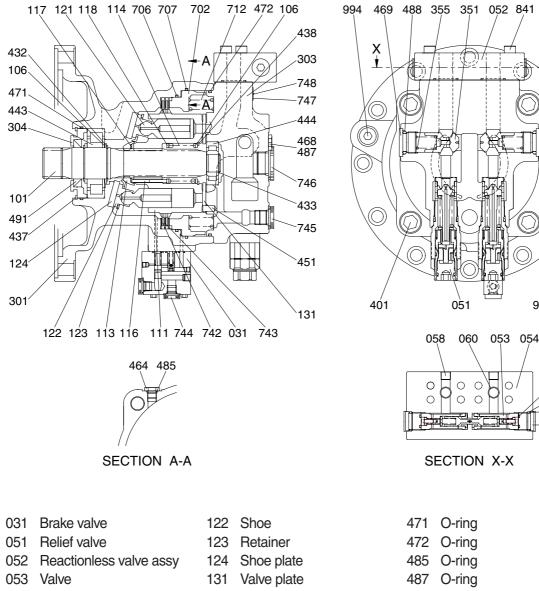
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Hydraulic circuit

Port	Port name	Port size
A	Main port	SAE PF 3/4
В	Main port	SAE PF 3/4
Dr	Drain port	PF 1/2
Mu	Make up port	PF 1
PG	Brake release port	PF 1/4
SH	Brake pilot port	PF 1/4
PA,PB	Gage port	PF 1/4

1) SWING MOTOR



- 054 Block
 055 Plug
 056 Back up ring
 057 O-ring
 058 Plug
 059 O-ring
- 059 O-ring
 060 O-ring
 101 Drive shaft
 106 Spacer
 111 Cylinder block
 113 Bushing
 114 Spring
 116 Push rod
 117 Spacer

118 Spacer

121 Piston

301 Casing 303 Casing 304 Front cover 351 Plunger 355 Spring 401 Hexagon socket bolt 432 Snap ring 433 Snap ring 437 Snap ring 438 Snap ring 443 Roller bearing 444 Roller bearing 451 Spring pin Plug 464 Plug 468 469 Plug

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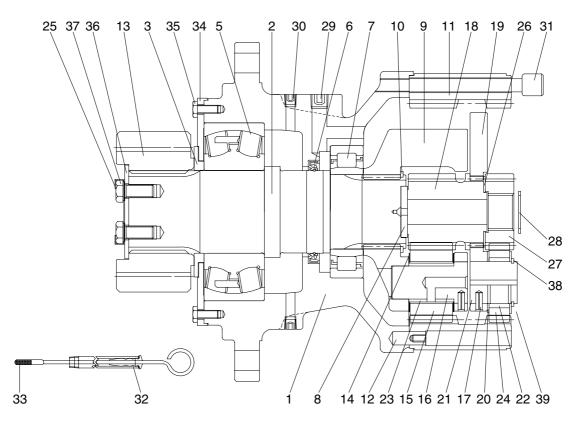
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471 O-ring
472 O-ring
485 O-ring
487 O-ring
488 O-ring
491 Oil seal
702 Piston
706 O-ring
707 O-ring
712 Brake spring
742 Friction plate
743 Separate plate
744 Plug
745 Plug
746 Plug
841 Hexagon socket bolt
993 Plug
994 Plug

2) REDUCTION GEAR



17W72SM03

- 1 Casing
- 2 Drive shaft
- 3 Spacer
- 5 Roller bearing
- 6 Oil seal
- 7 Roller bearing
- 8 Thrust plate
- 9 Carrier 2
- 10 Stop ring
- 11 Ring gear
- 12 Knock pin
- 13 Pinion gear
- 14 Thrust washer

- 15 Planet gear 2
- 16 Pin 2
- 17 Spring pin
- 18 Sun gear 2
- 19 Carrier 1
- 20 Side plate 1
- 21 Pin 1
- 22 Needle cage
- 23 Bushing 2
- 24 Planet gear 1
- 25 Lock washer
- 26 Side plate 3
- 27 Sun gear 1

- 28 Stop ring
- 29 Plug
- 30 Plug
- 31 Socket bolt
- 32 Gauge pipe
 - 33 Gauge bar
- 34 Cover plate
- 35 Hexagon bolt
- 36 Lock plate
- 37 Hexagon bolt
- 38 Stop ring
- 39 Side plate 2

2. FUNCTION

1) ROTARY PART

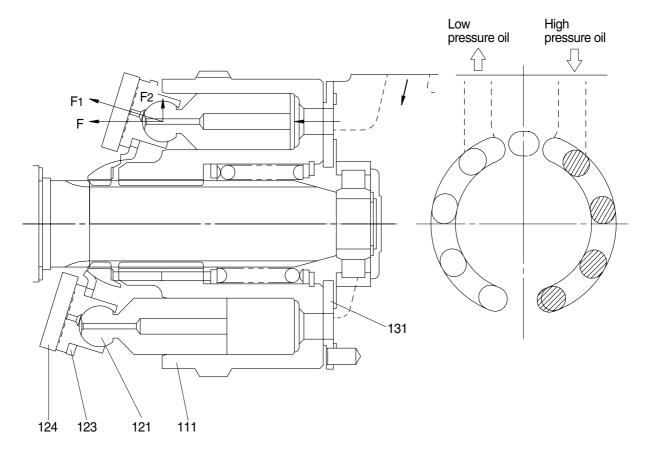
When high pressurized oil enters a cylinder through port(a), which is the inlet of balance plate(131), hydraulic pressure acting on the piston causes axial force F. The pressure force F works via the piston(121) upon the return plate(123) which acts upon the swash plate(124) via an hydrostatic bearing. Force F1 perpendicular to swash plate(124) and force F2 perpendicular to cylinder center. Being transferred to the cylinder block(111) through piston, force F2 causes rotational moment at surroundings of cylinder.

Since cylinder block has 9 equidistantly arrayed pistons, rotational torque is transmitted to cylinder shaft in order by several pistons connected to the inlet port of high pressurized oil. When the direction of oil flow is reversed, rotational direction of cylinder is also reversed. Output torque is given by the equation.

$$T = \frac{p \times q}{2\pi}, q = Z \cdot A \cdot PCD \cdot \tan\theta, F1 = \frac{F}{COS\theta}, F_2 = F \tan\theta, S = PCD \times \tan\theta$$

Where p: Effective difference of pressure(kgf/cm²)

- q : Displacement(cc/rev)
- T : Output torque(kgf \cdot cm)
- Z : Piston number(9EA)
- A : Piston area(cm²)
- θ : Tilting angle of swash plate(degree)
- S: Piston stroke(cm)



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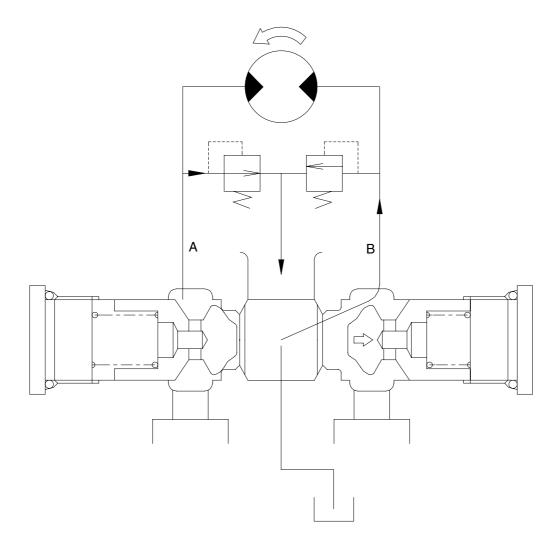
2) MAKE UP VALVE

In the system using this type of motor, there is no counter balance functioning valve and there happens the case of revolution exceeding hydraulic supply of motor. To prevent the cavitation caused by insufficient oil flow there is a make up valve to fill up the oil insufficiency.

A make up value is provided immediately before the port leading to the hydraulic oil tank to secure feed pressure required when the hydraulic motor makes a pumping action. The boost pressure acts on the hydraulic motor's feed port via the make up value.

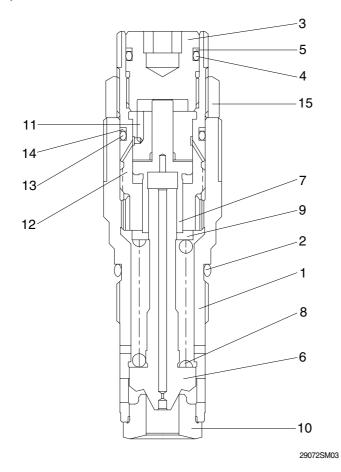
Pressurized oil into the port B, the motor rotate counterclockwise.

If the plunger of MCV moves neutral position, the oil in the motor is drain via left relief valve, the drain oil run into motor via right make up valve, which prevent the cavitation of motor.



29072SM09

3) RELIEF VALVE



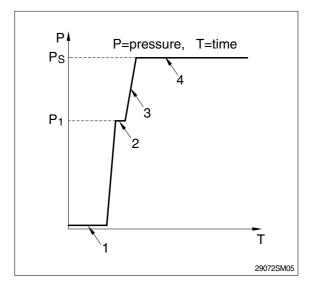
- 1 Body
- 2 O-ring
- 3 Plug
- 4 O-ring
- 5 Back up ring
- 6 Plunger
- 7 Piston
- 8 Spring
- 9 Seat spring
- 10 Seat
- 11 Sleeve
- 12 Adjust plug
- 13 O-ring
- 14 Back up ring
- 15 Nut

(1) Construction of relief valve

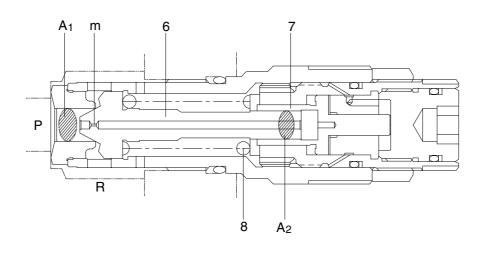
The valve casing contains two cartridge type relief valves that stop the regular and reverse rotations of the hydraulic motor. The relief valves relieve high pressure at start or at stop of swing motion and can control the relief pressure in two steps, high and low, in order to insure smooth operation.

(2) Function of relief valve

Figure illustrates how the pressure acting on the relief valve is related to its rising process. Here is given the function, referring to the figure following page.



① Ports (P,R) at tank pressure.

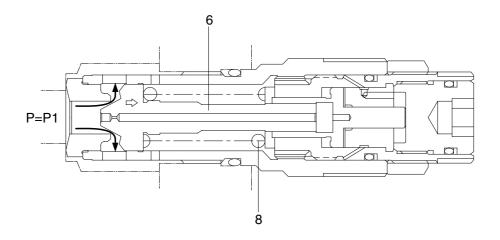


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② When hydraulic oil pressure(P×A1) reaches the preset force(FSP) of spring(8), the plunger (6) moves to the right as shown.

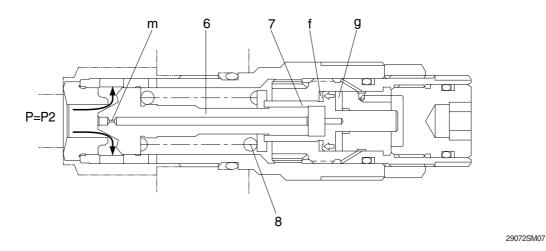
$$P1 \times A1 = Fsp + P1 \times A2$$

$$P1 = \frac{Fsp}{A1 - A2}$$



29072SM06

③ When the pressure of chamber g reaches the preset force(Fsp) of spring(8), the piston(7) moves right and stop the piston(7) hits the end of body.



④ When piston(7) hits the end of body, it stops moving to the right any further. As the result, the pressure in chamber(g) equals(Ps).

$$Ps \times A1 = Fsp + Ps \times A2$$

$$Ps = \frac{Fsp}{A1 - A2}$$

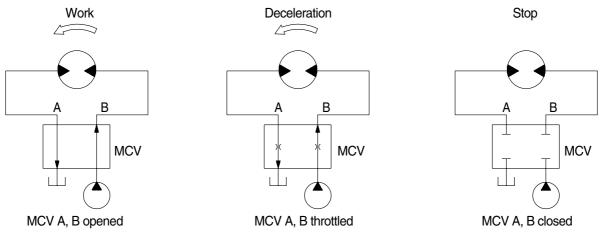
Ps

29072SM08

4) BRAKE SYSTEM

(1) Control valve swing brake system

This is the brake system to stop the swing motion of the excavator during operation. In this system, the hydraulic circuit is throttled by the swing control valve, and the resistance created by this throttling works as a brake force to slow down the swing motion.



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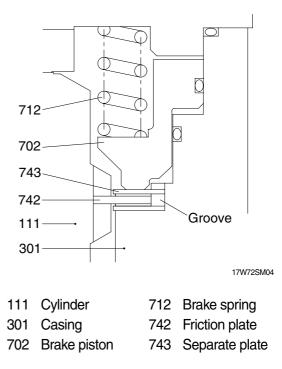
(2) Mechanical swing parking brake system

The mechanical swing parking brake system is installed to prevent the upper structure from swinging downhill because of its own weight when the excavator is parked on a slope since it completely eliminates the hydraulic drift of swing motion while the excavator is on a slop, work can be done more easily and safely.

① Brake assembly

Circumferential rotation of separate plate(743) is constrained by the groove located at casing(301). When housing is pressed down by brake spring(712) through friction plate(742), separate plate(743) and brake piston(702), friction force occurs there.

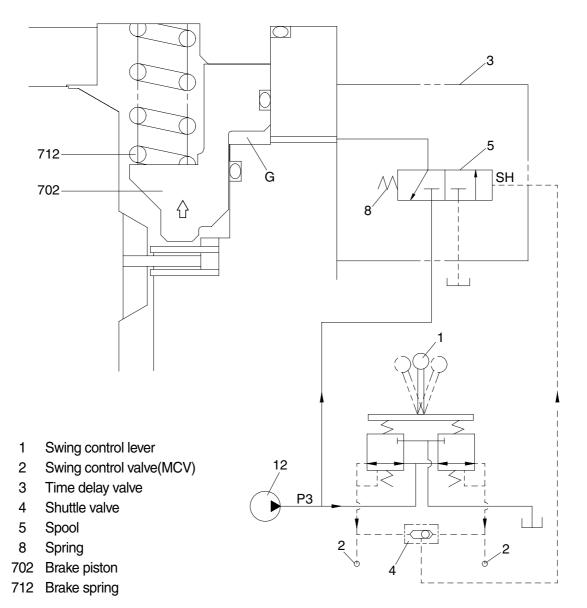
Cylinder(111) is constrained by this friction force and brake acts, while brake releases when hydraulic force exceeds spring force.



② Operating principle

a. When the swing control lever(1) is set to the swing position, the pilot oil go to the swing control valve(2) and to SH of the time delay valve(3) via the shuttle valve(4), this pressure move spool(5) to the leftward against the force of the spring(8), so pilot pump charged oil(P3) goes to the chamber G.

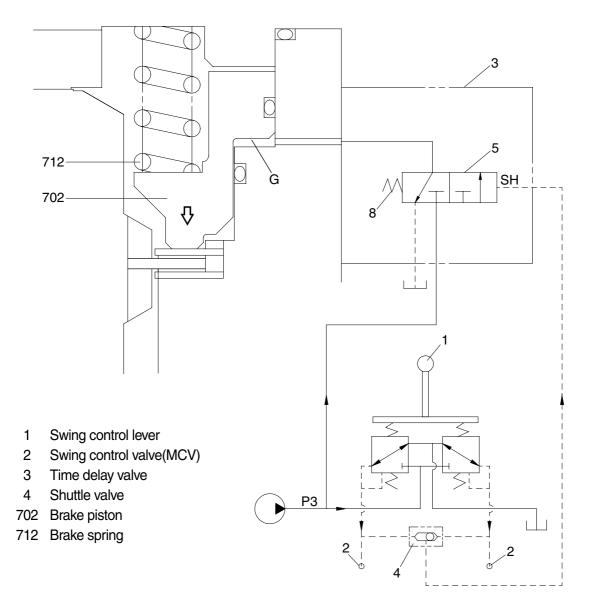
This pressure is applied to move the piston(702) to the upward against the force of the spring(712). Thus, it releases the brake force.



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b. When the swing control lever(1) is set the neutral position, the time delay valve(3) shifts the neutral position and the pilot oil blocked chamber G.

Then, the piston(702) is moved lower by spring(712) force and the return oil from the chamber G is drain.



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